IAP Gesture Recognition Workshop

 $\sum_{i=1}^{G} P(\mathbf{x}|g_i) P(g_i)$

Session 1: Gesture Recognition & Machine Learning Fundamentals $\sum_{k=1}^{K} \frac{1}{P_k} \sum_{t=1}^{T^{(k)}-1} \hat{\alpha}$

Nicholas Gillian

Responsive Environments, MIT Media Lab

Tuesday 8th January, 2013

Tuesday, January 8, 13

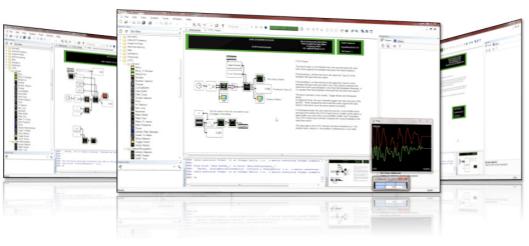
• Gesture Recognition for Musician Computer Interaction

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- Free-air Gestures & Fine-grain Control

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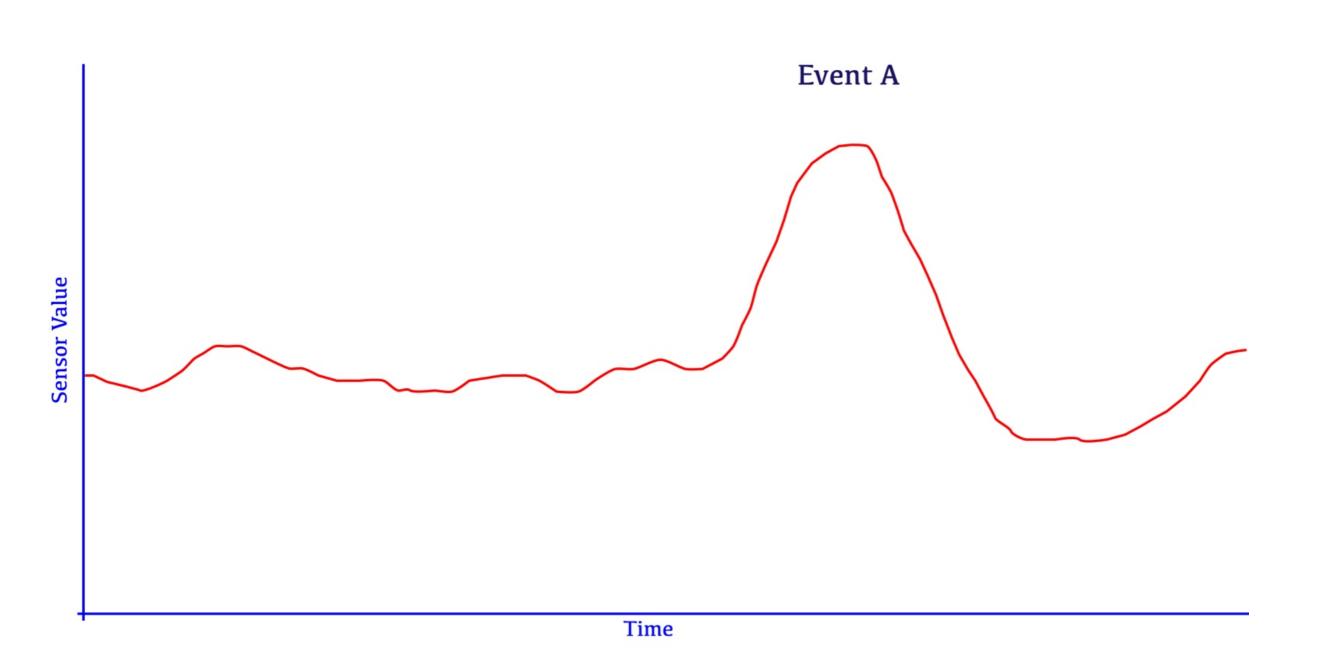
EyesWeb

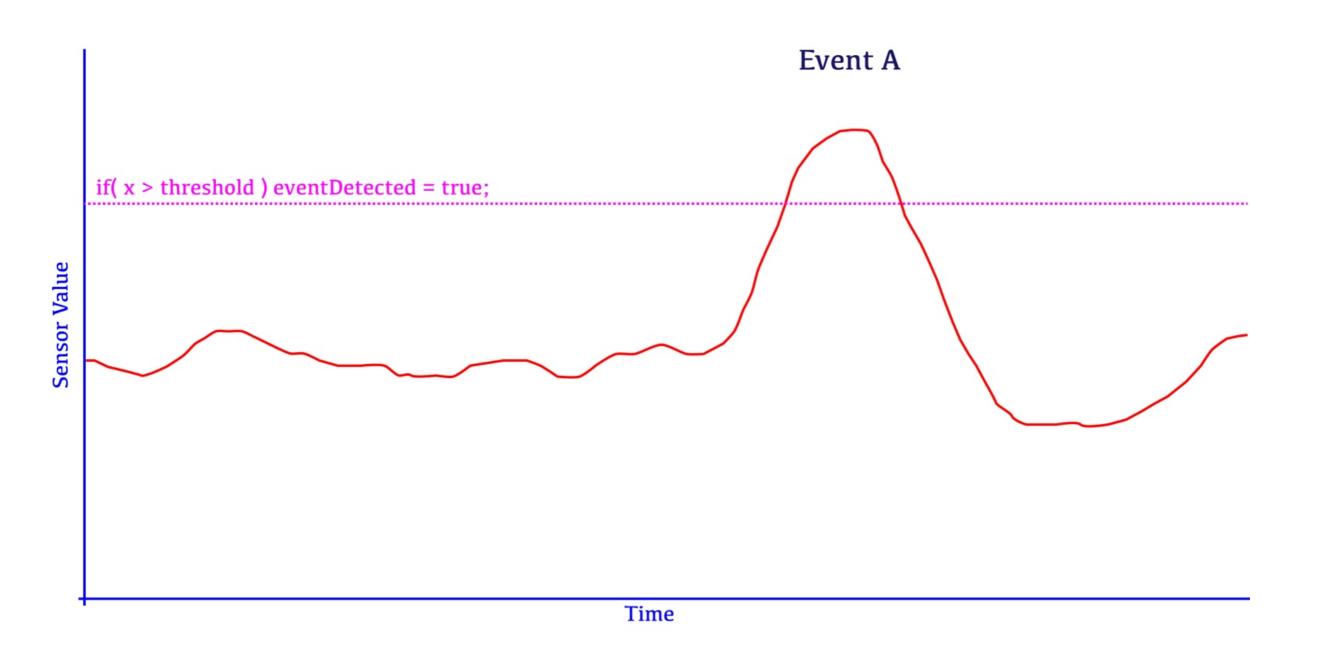


Gesture Recognition Toolkit

Schedule

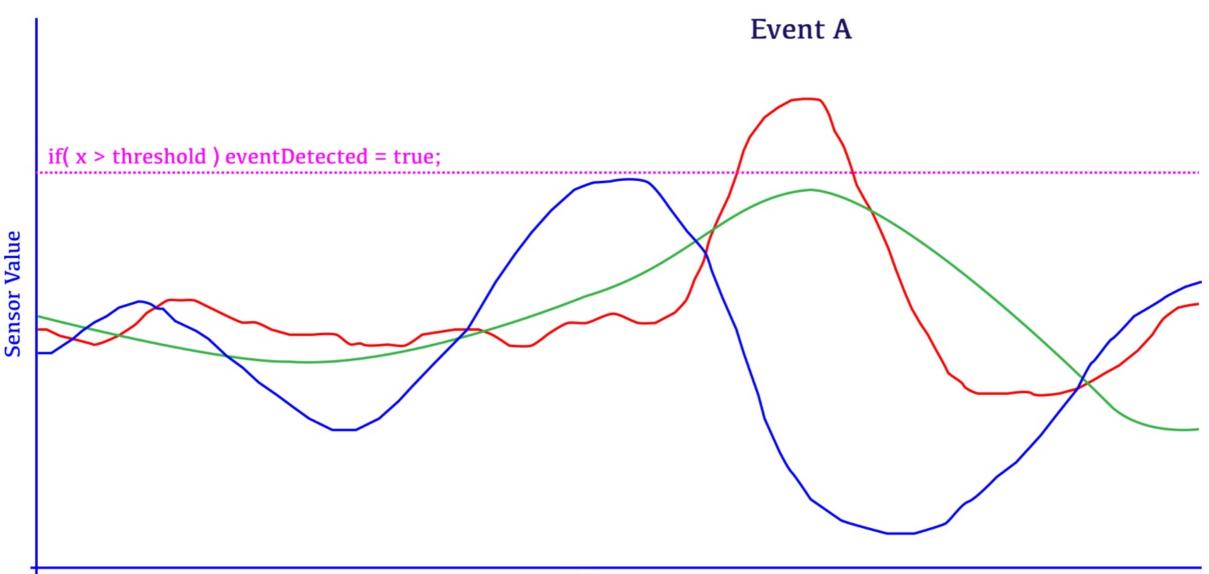
- Machine Learning 101
- Hello World
- Gesture Recognition
- Installation & Setup
- Introduction to the Gesture Recognition Toolkit
- Lunch
- Hands-on Coding Sessions





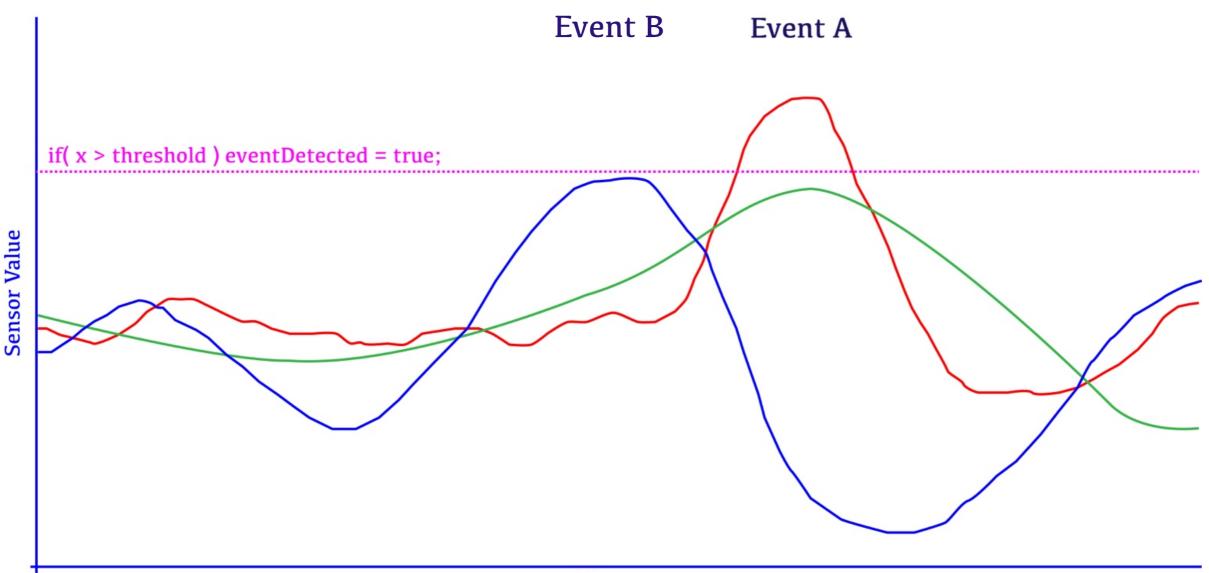
Might work for simple cases...

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Time

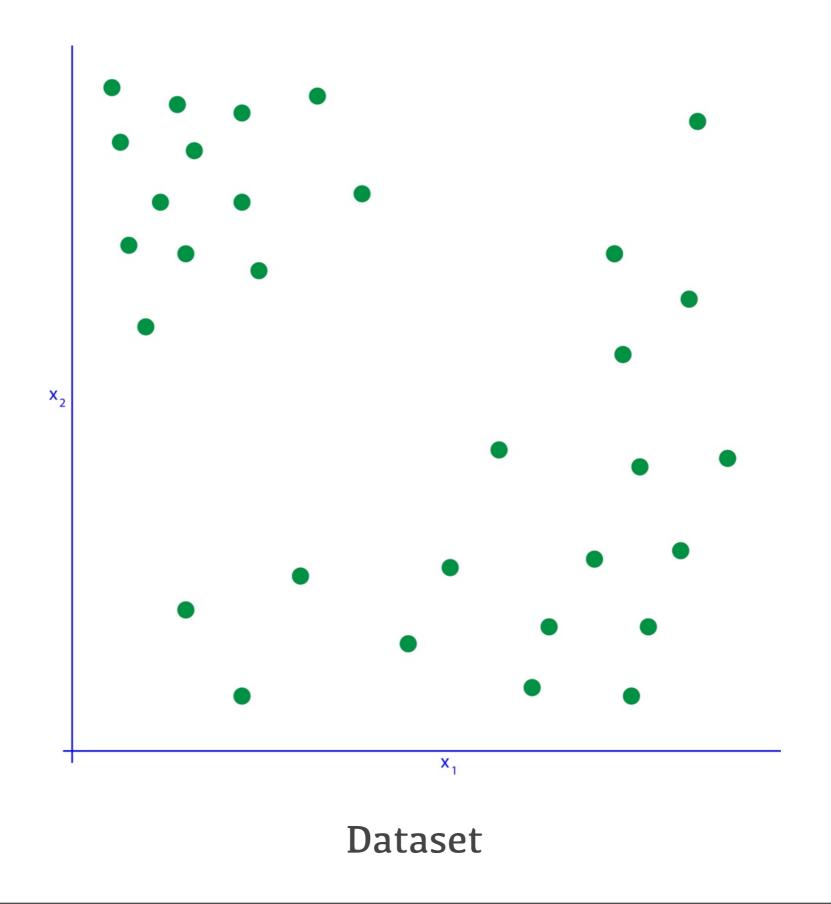
Can be more difficult with multidimensional data!

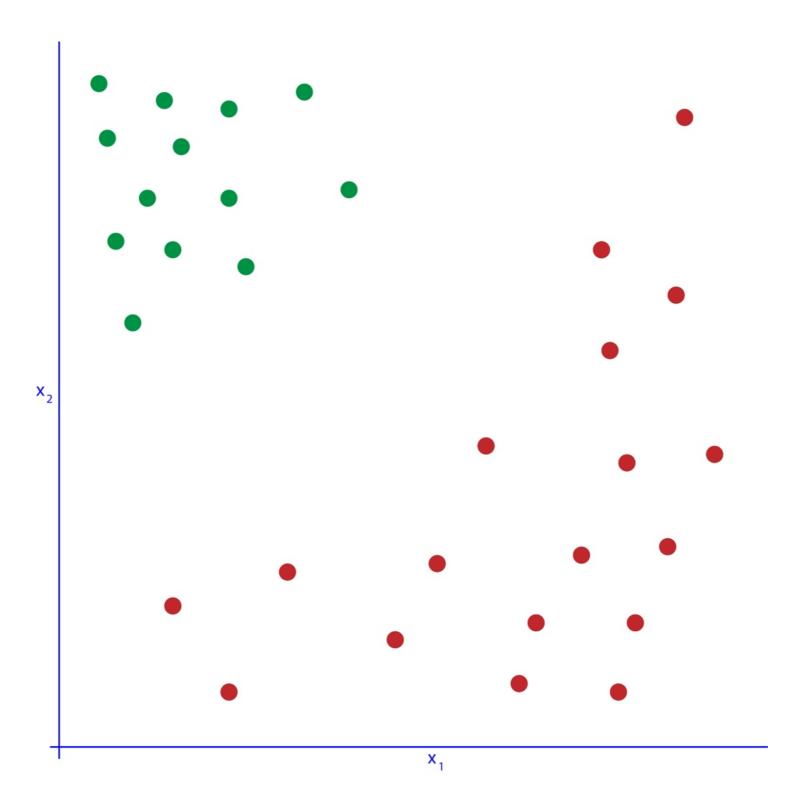


Time

Can be more difficult with multiple events!

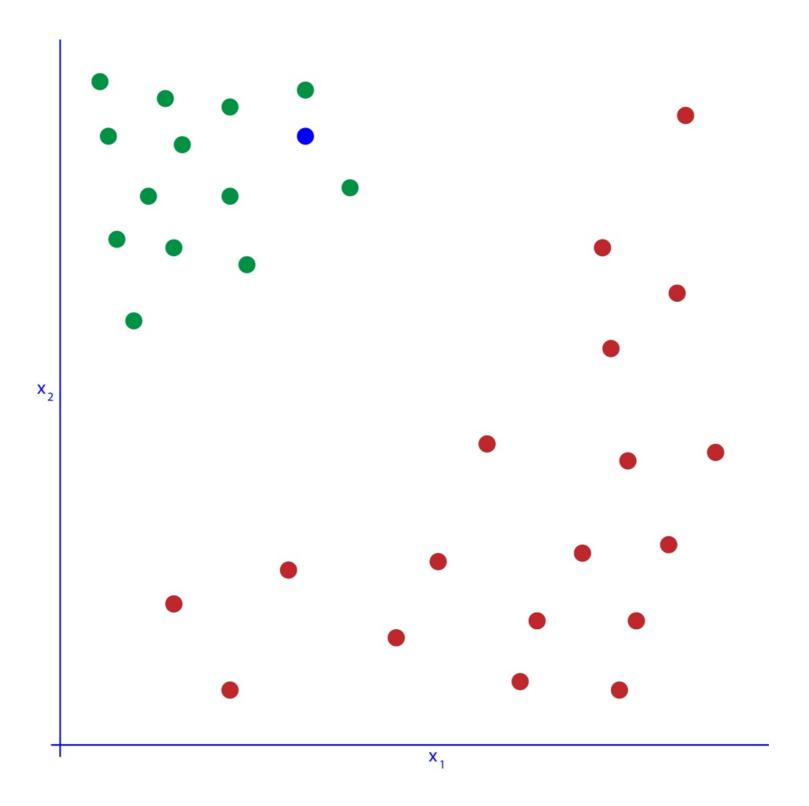
Machine Learning 101





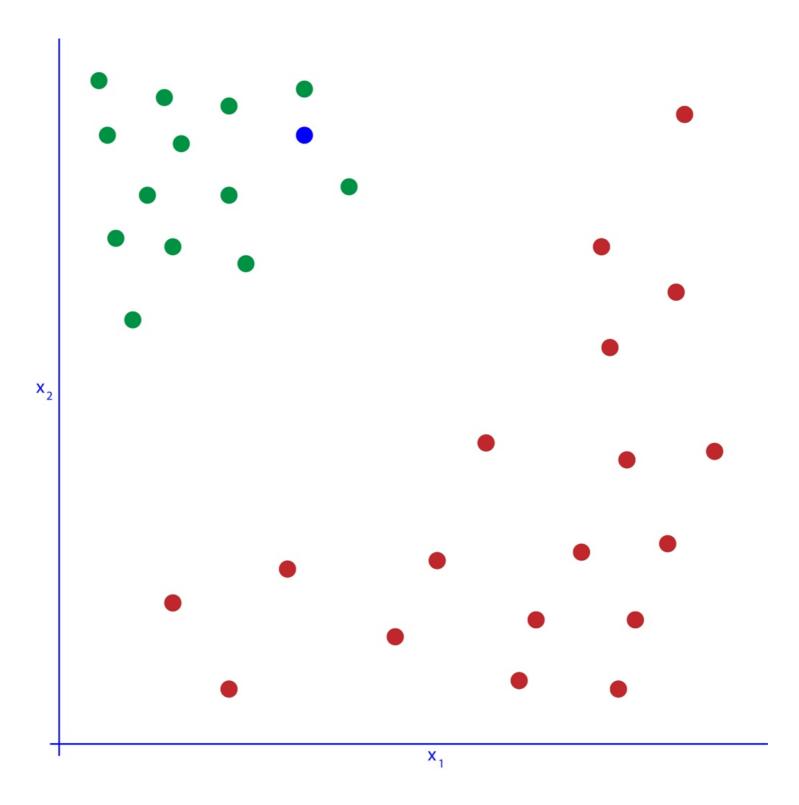
ML can automatically infer the underlying behavior/rules of this data

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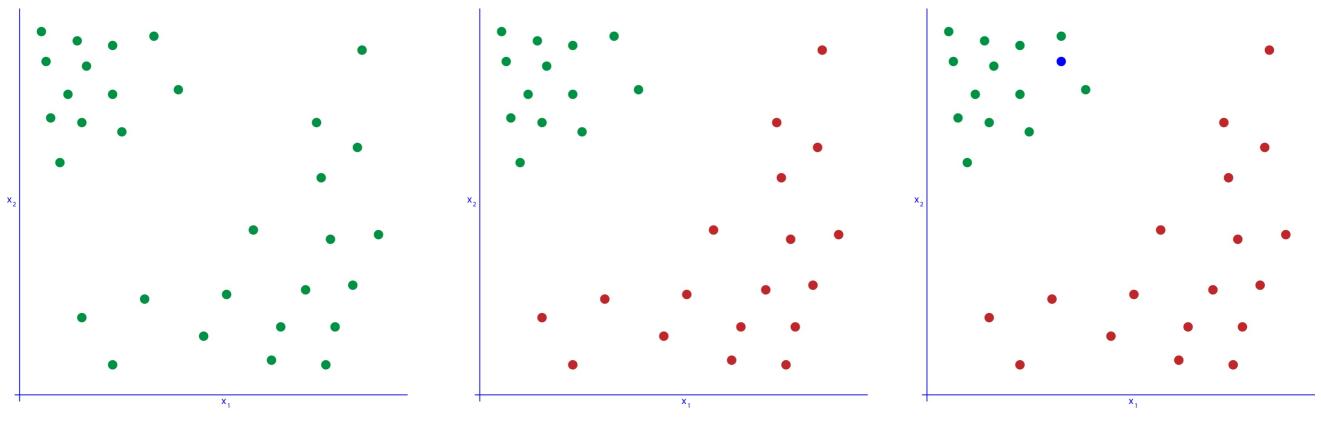


These rules can then be used to make predictions about future data

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The three main phases of machine learning:



Data Collection

Learning

Prediction

Machine Learning is commonly used to solve two main problems:

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CLASSIFICATION

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CLASSIFICATION

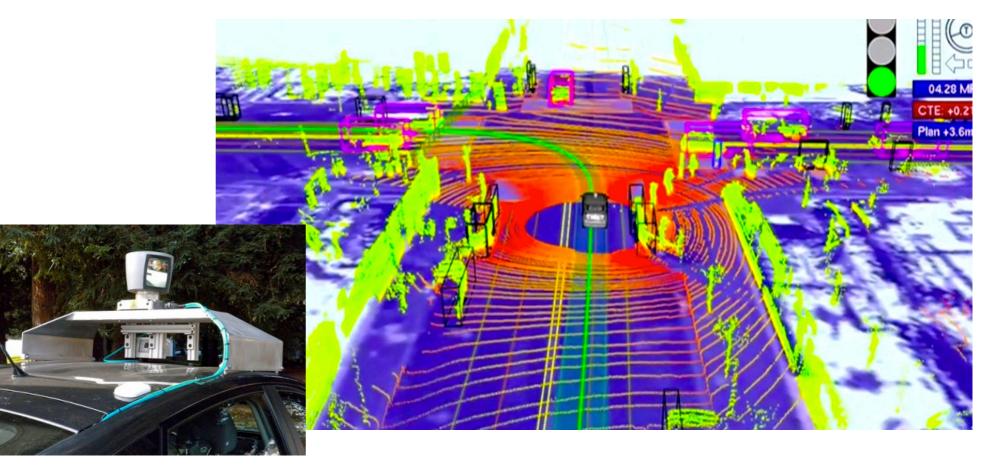
REGRESSION

Machine Learning is commonly used to solve two main problems:







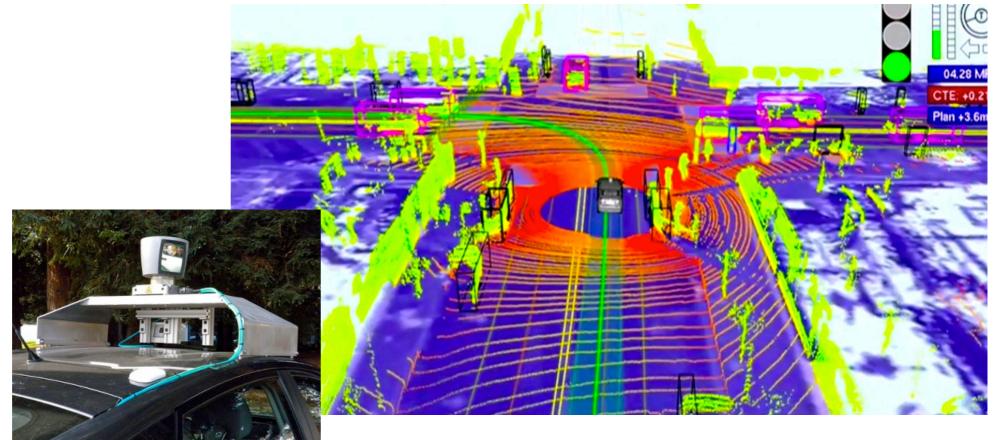


Machine Learning is commonly used to solve two main problems:

CLASSIFICATION

$$f: \mathbf{x} \longmapsto [0, 1, 2, 3, \dots, K]$$

Discrete Output, representing the most likely class that the input **x** belongs to



REGRESSION

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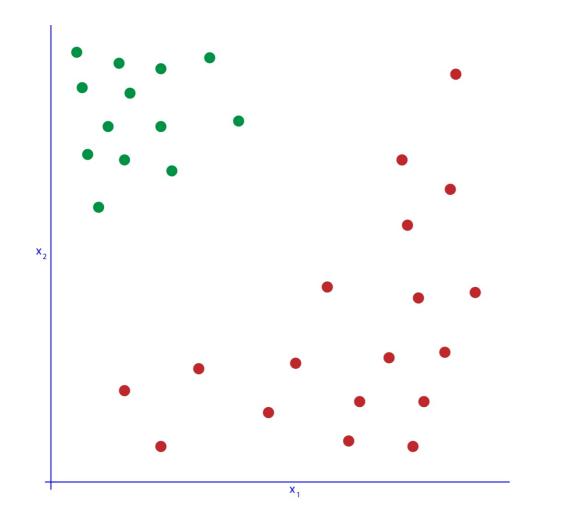
REGRESSION

$$f: \mathbf{x} \mapsto [-1.4, 2.6, 5.2, \dots]$$

Continuous Output, mapping the *N* dimensional input vector **x** to an *M* dimensional vector **y**

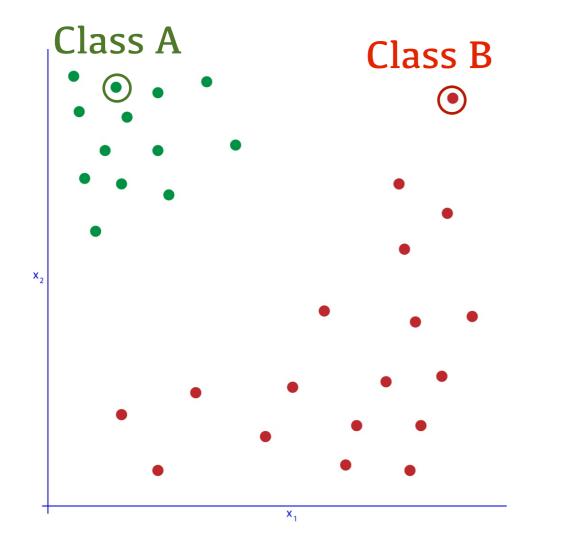
Main types of learning:

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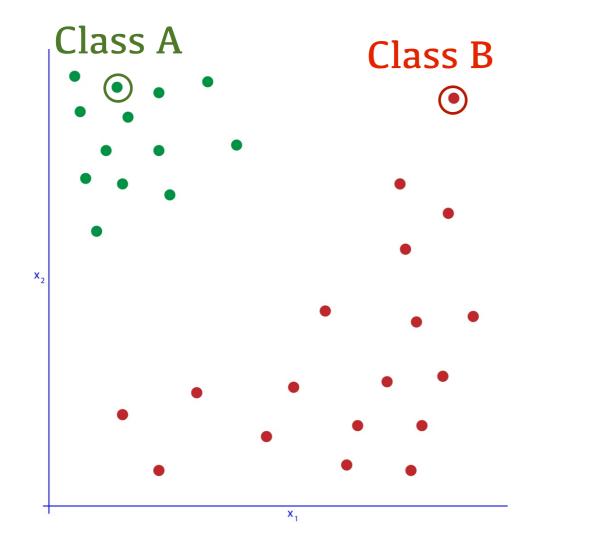
SUPERVISED LEARNING

Main types of learning:

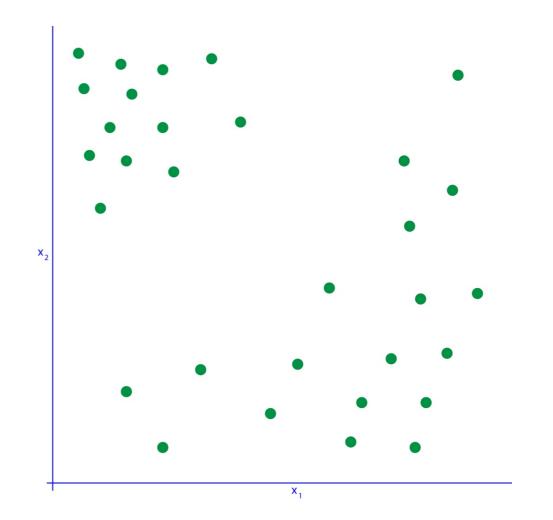


SUPERVISED LEARNING

Main types of learning:

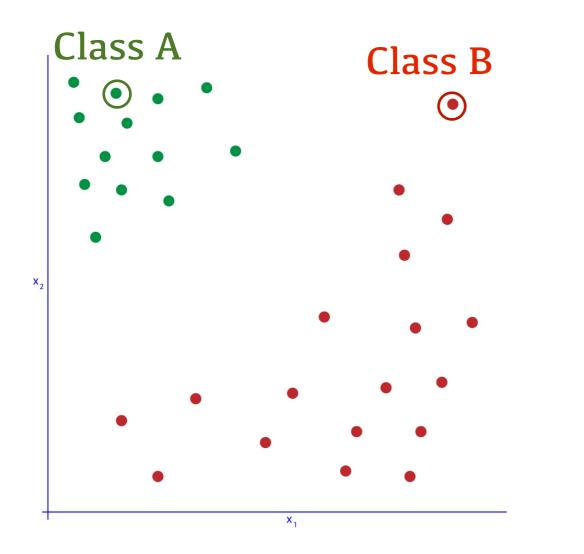


SUPERVISED LEARNING

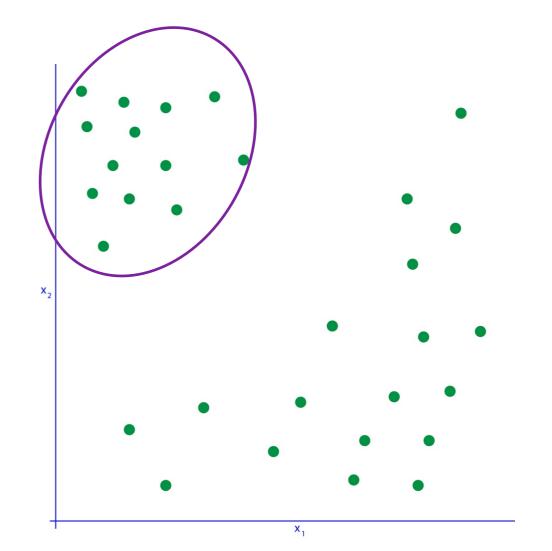


UNSUPERVISED LEARNING

Main types of learning:

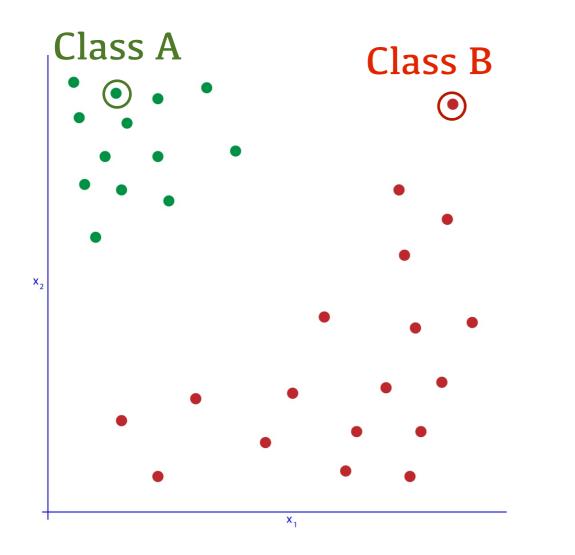


SUPERVISED LEARNING

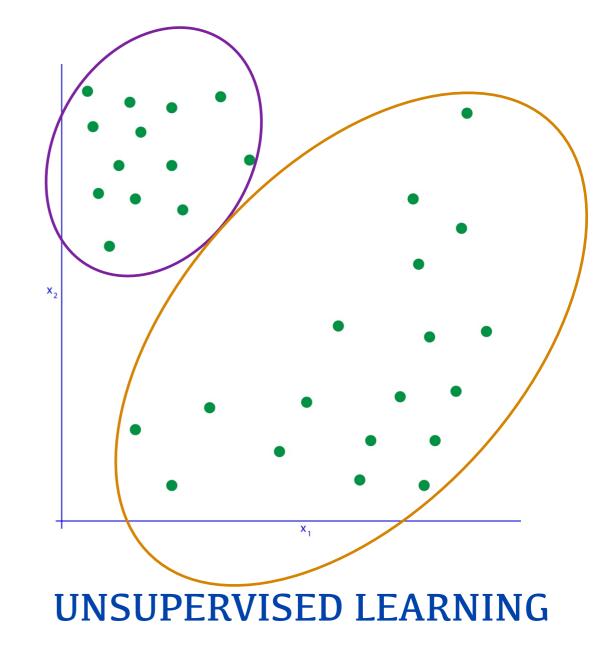


UNSUPERVISED LEARNING

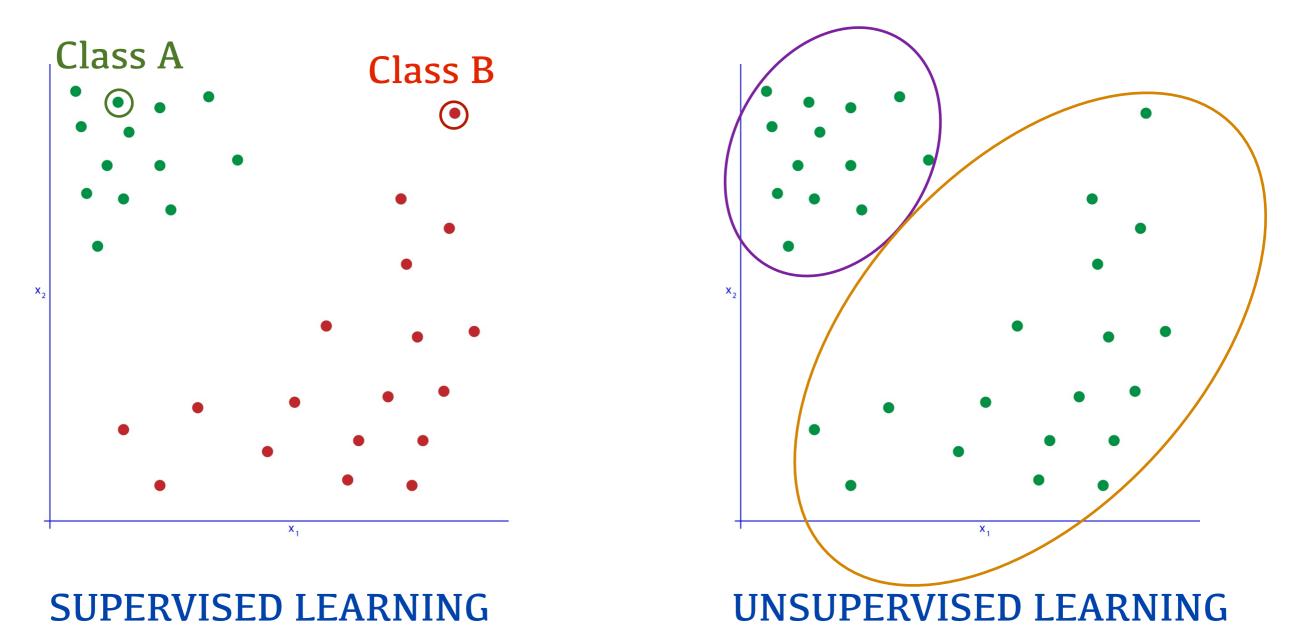
Main types of learning:



SUPERVISED LEARNING



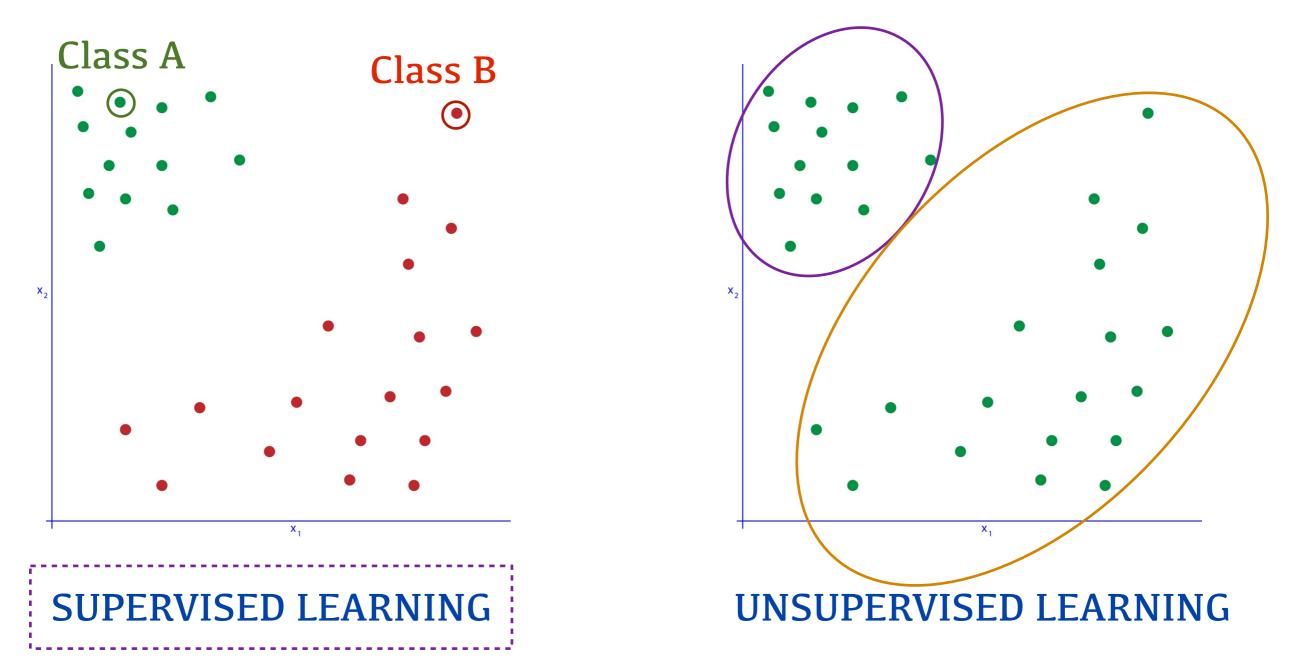
Main types of learning:



many others, such as semi-supervised learning, reinforcement learning, active learning, deep learning, etc..

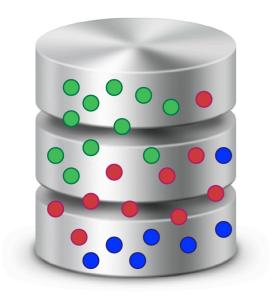
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Main types of learning:

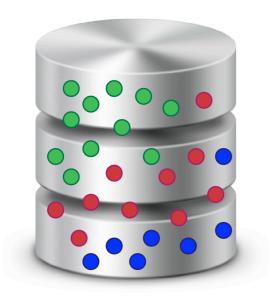


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Supervised Learning



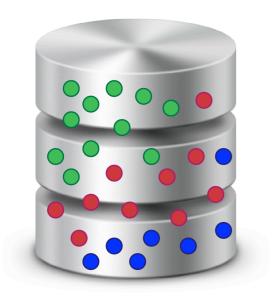
Training Data



Training Data

$\mathbf{X} = \{\{\mathbf{x}_1, \mathbf{t}_1\}, \{\mathbf{x}_2, \mathbf{t}_2\}, \{\mathbf{x}_3, \mathbf{t}_3\}, \dots, \{\mathbf{x}_M, \mathbf{t}_M\}\}^T$

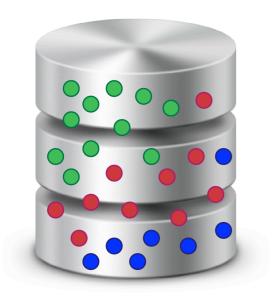
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Training Data

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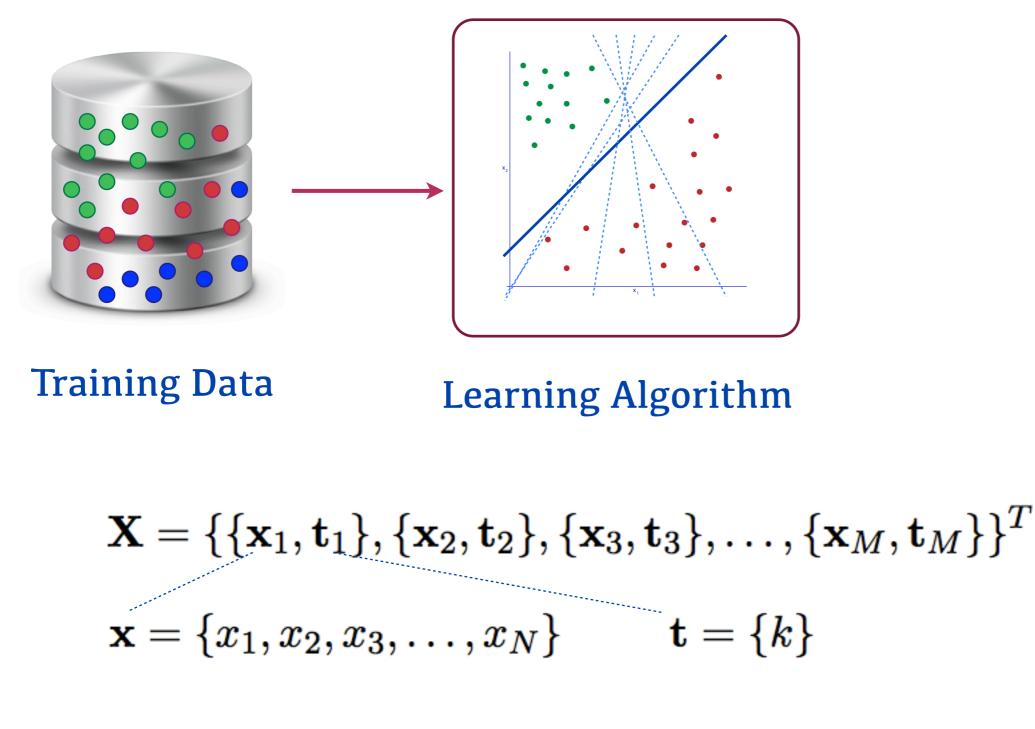
Input Vector



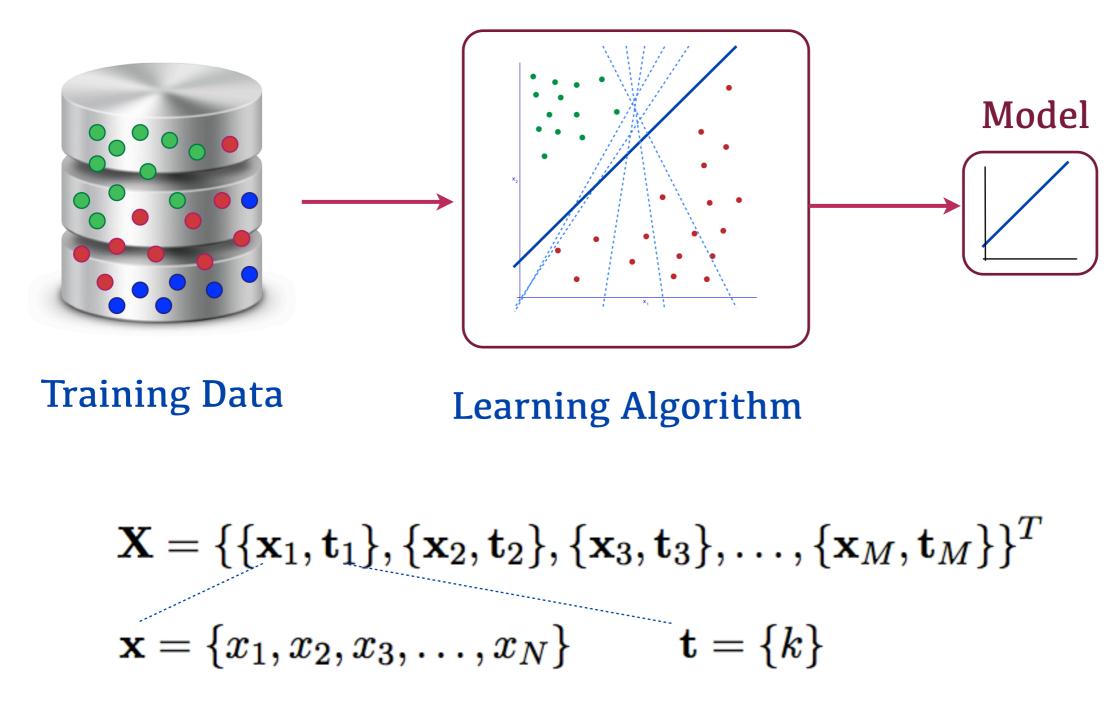
Training Data

$$\begin{split} \mathbf{X} &= \{\{\mathbf{x}_1, \mathbf{t}_1\}, \{\mathbf{x}_2, \mathbf{t}_2\}, \{\mathbf{x}_3, \mathbf{t}_3\}, \dots, \{\mathbf{x}_M, \mathbf{t}_M\}\}^T \\ \mathbf{x} &= \{x_1, x_2, x_3, \dots, x_N\} \qquad \mathbf{t} = \{k\} \end{split}$$

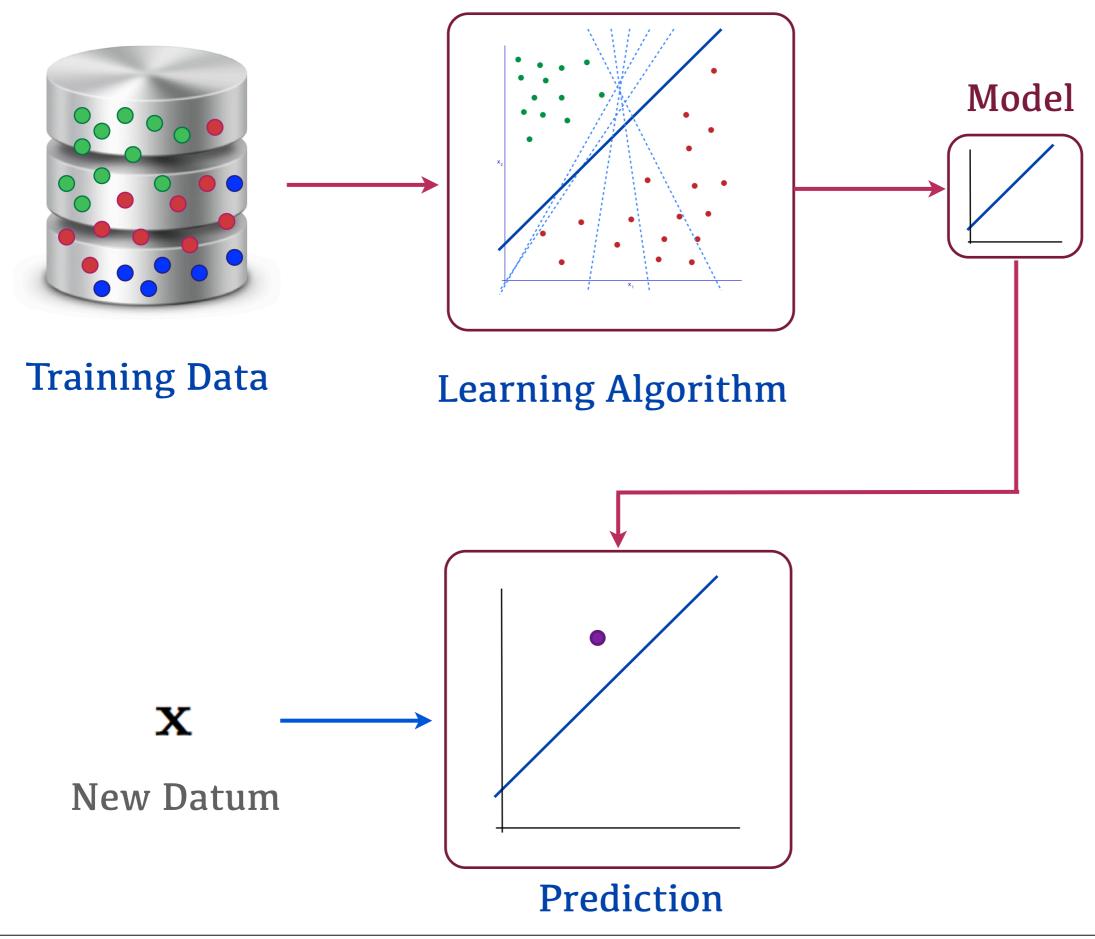
Input Vector Target Vector

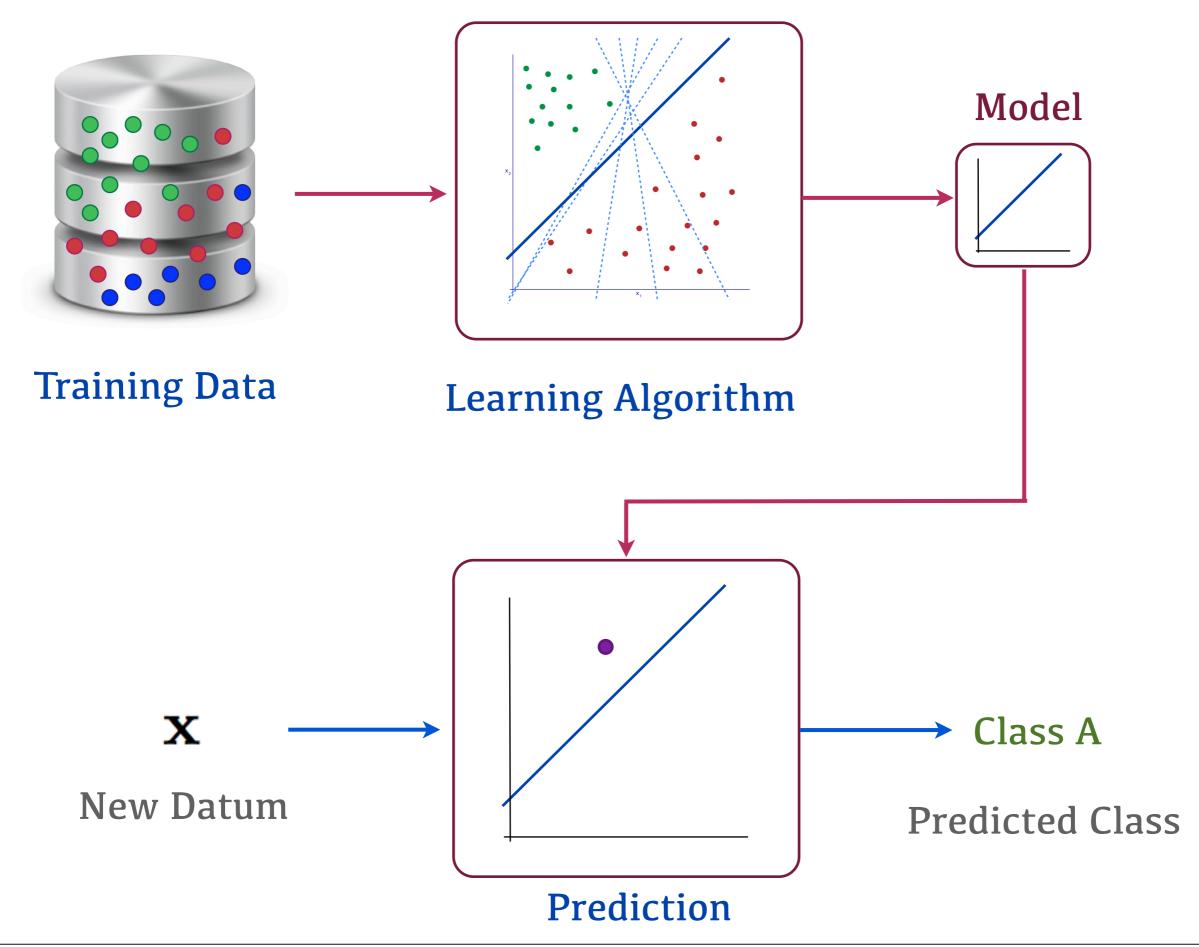


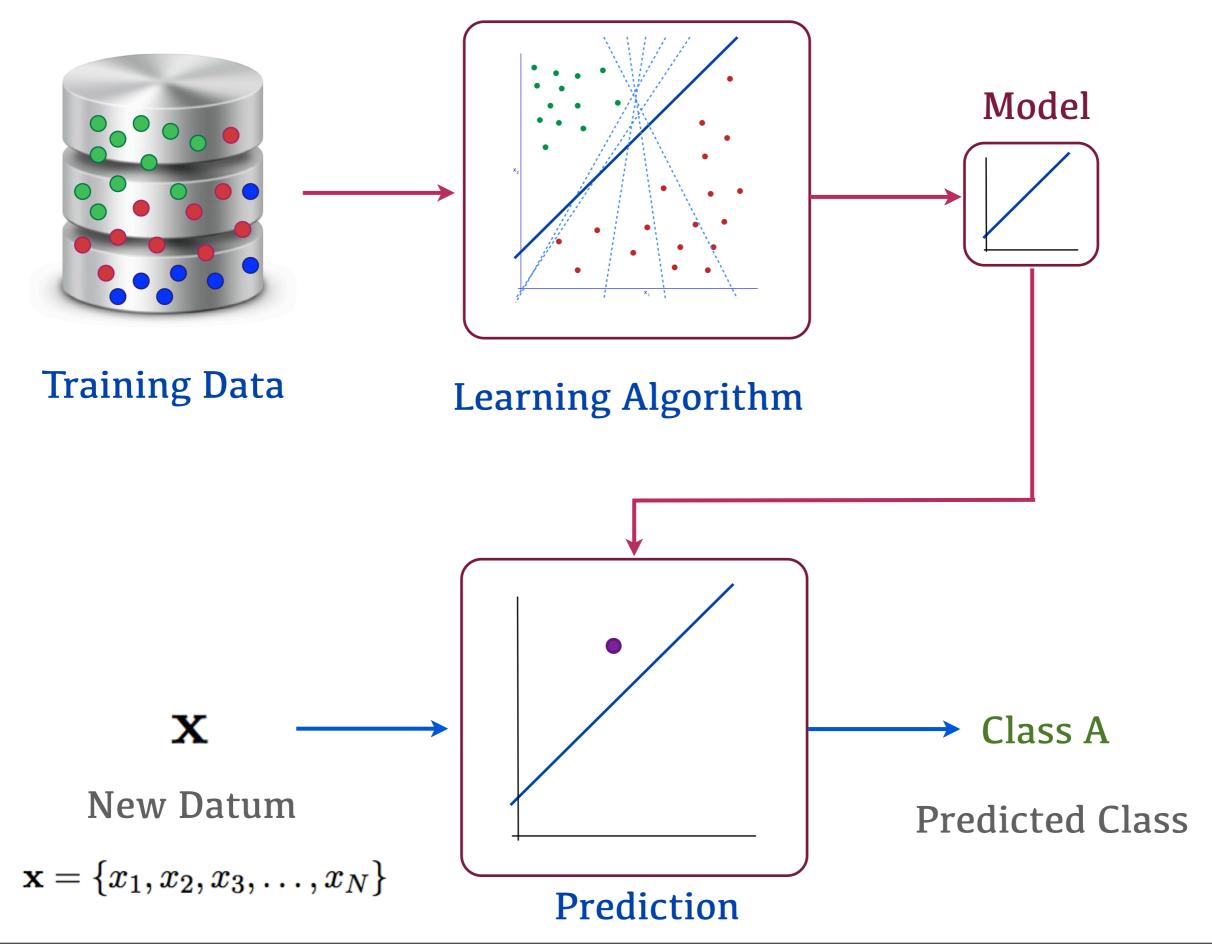
Input Vector Target Vector

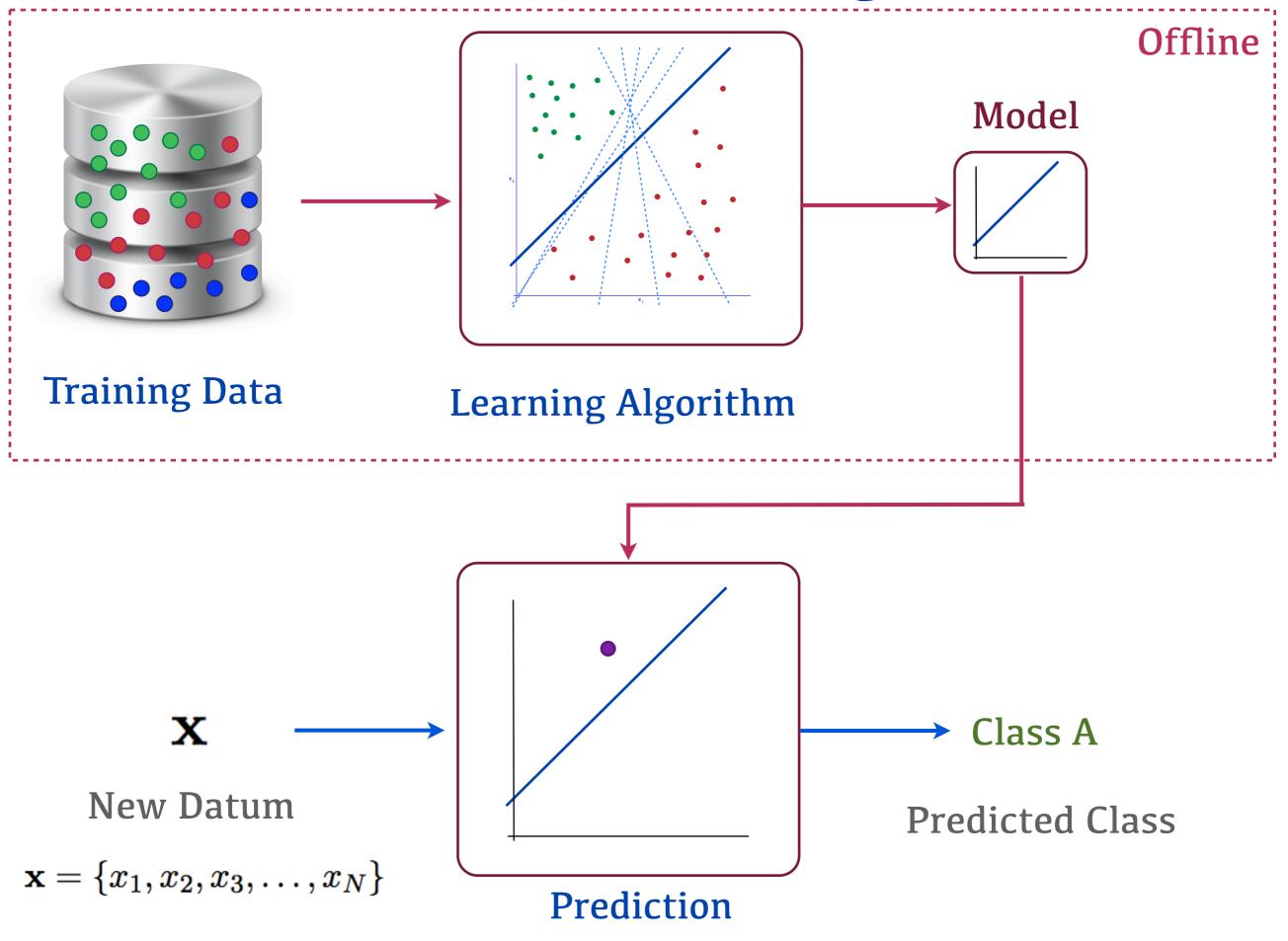


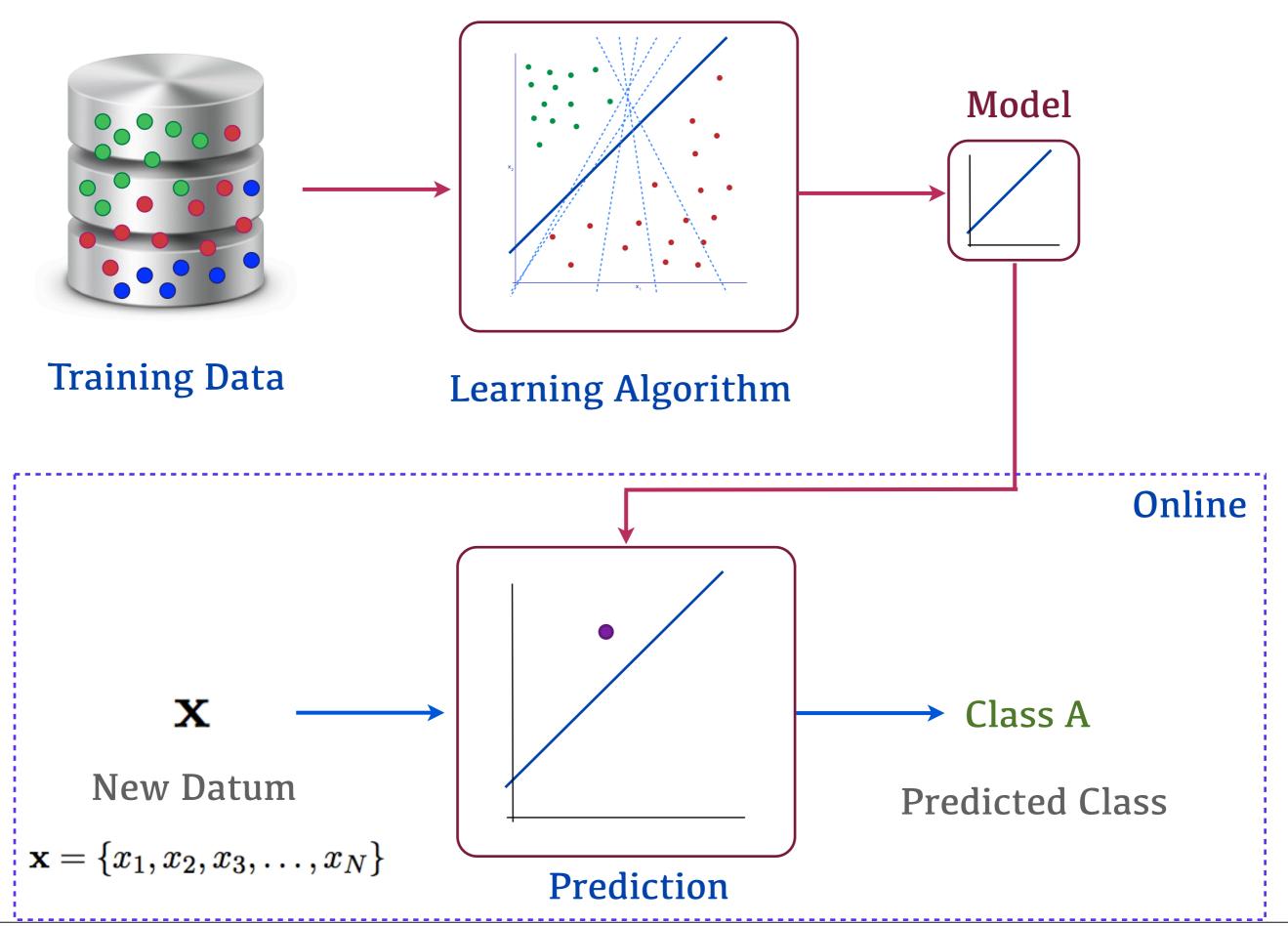
Input Vector Target Vector



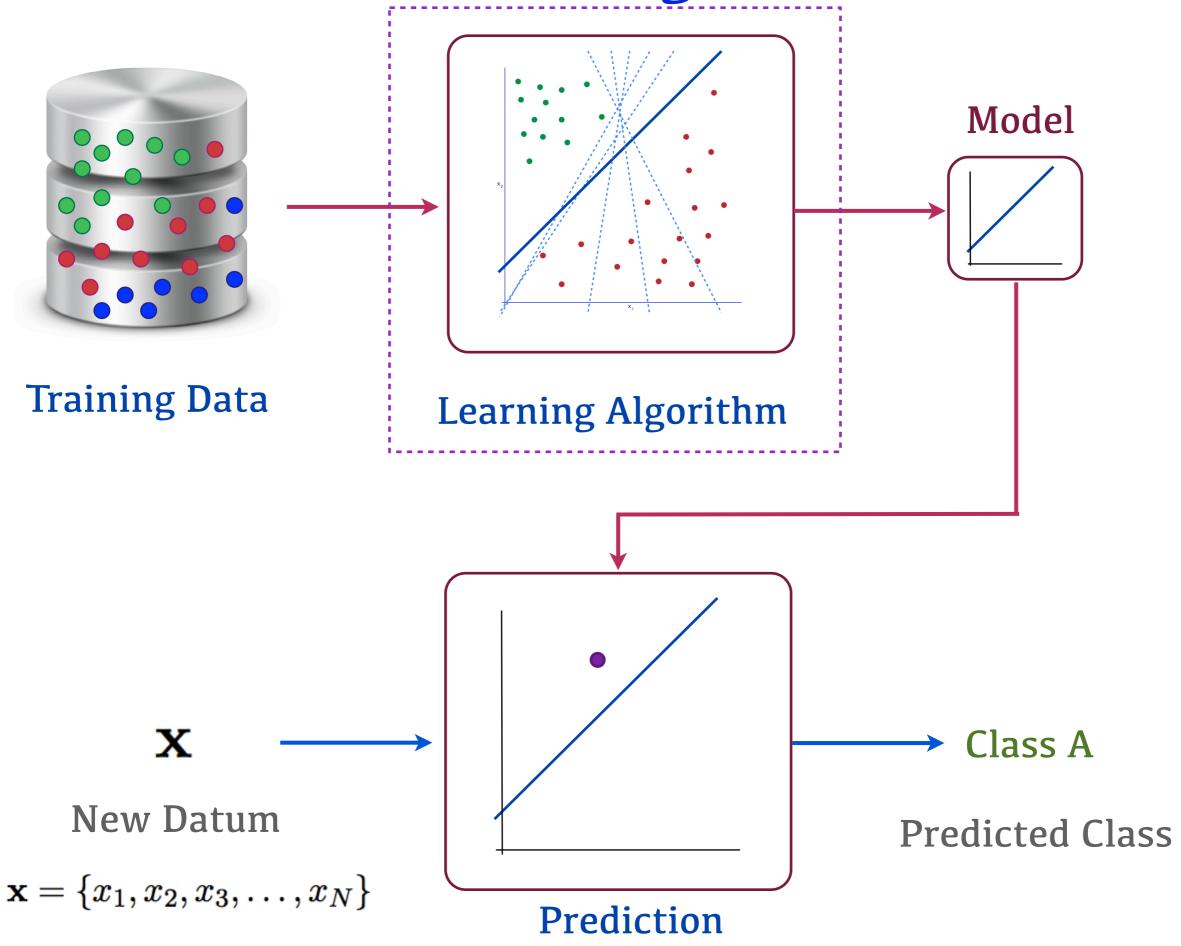


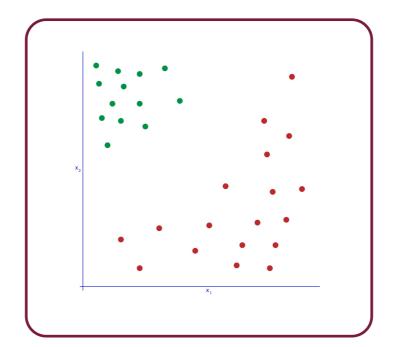


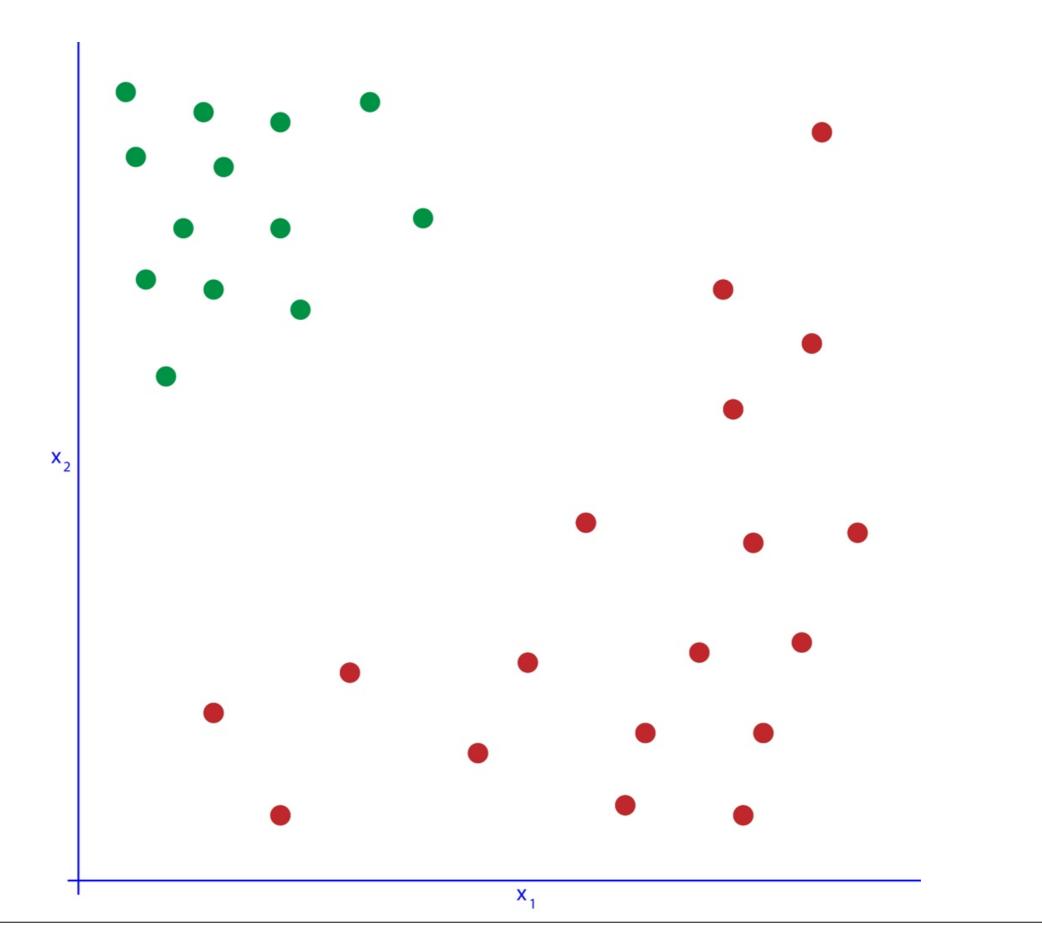


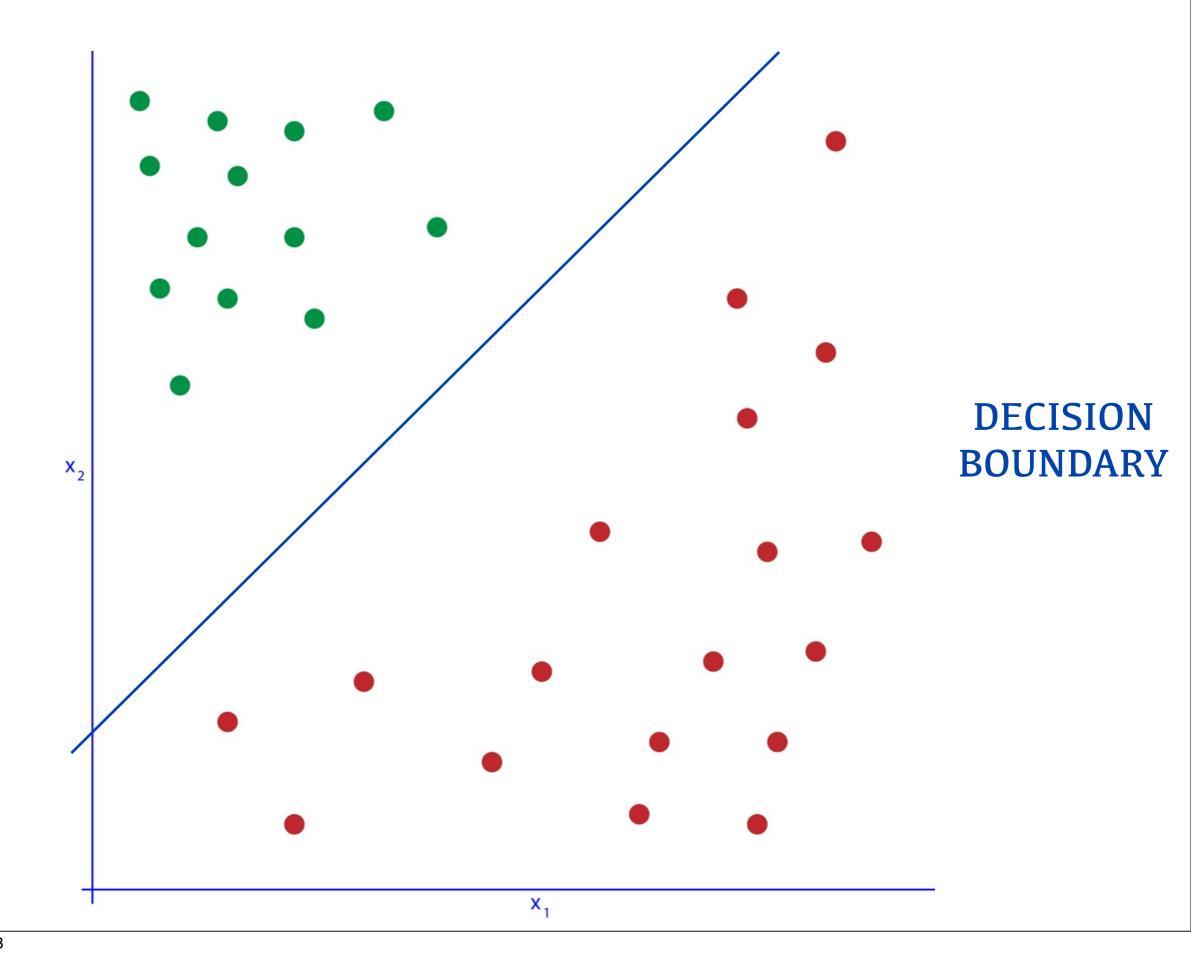


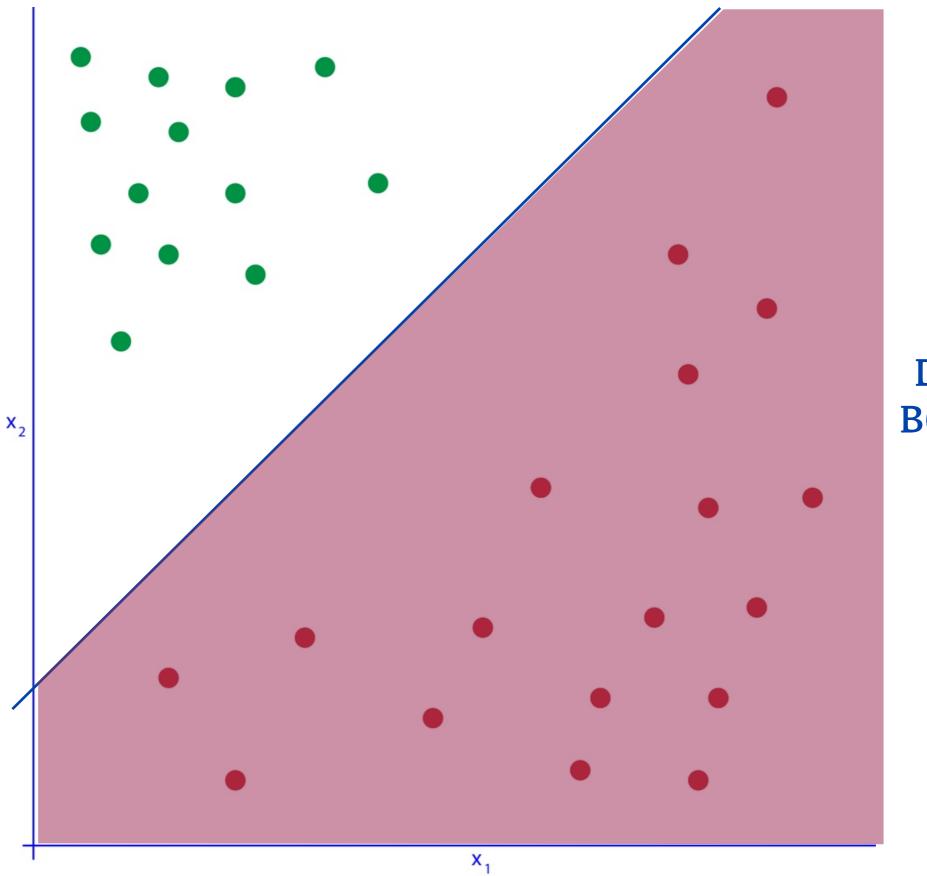
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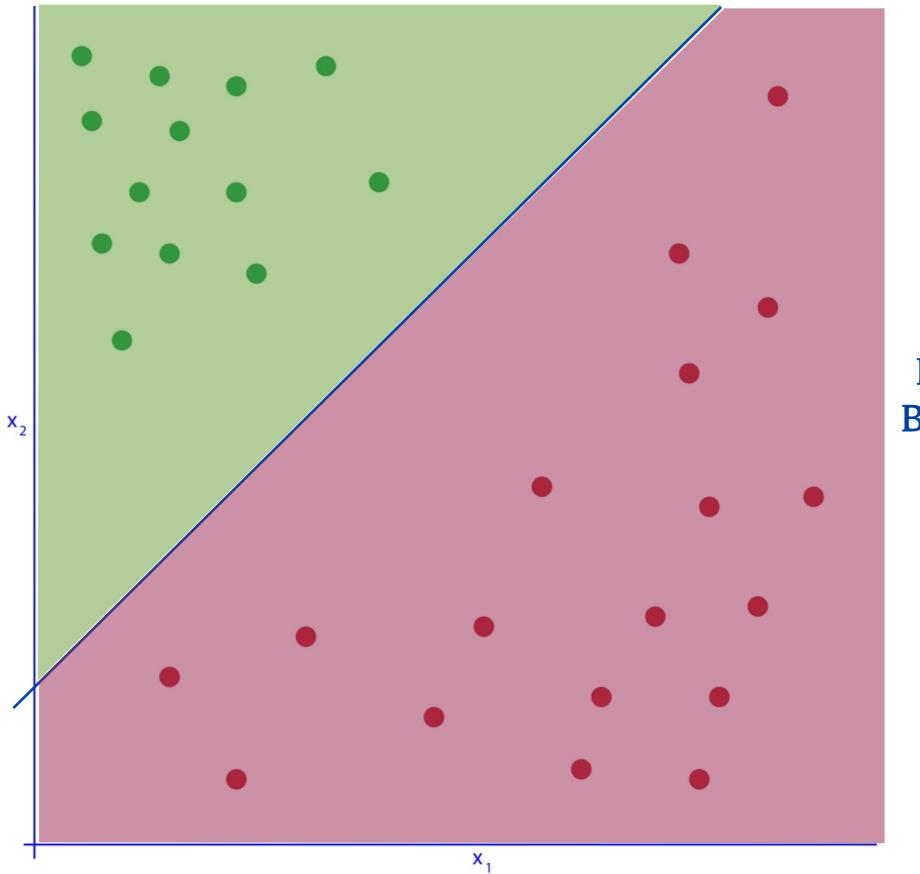




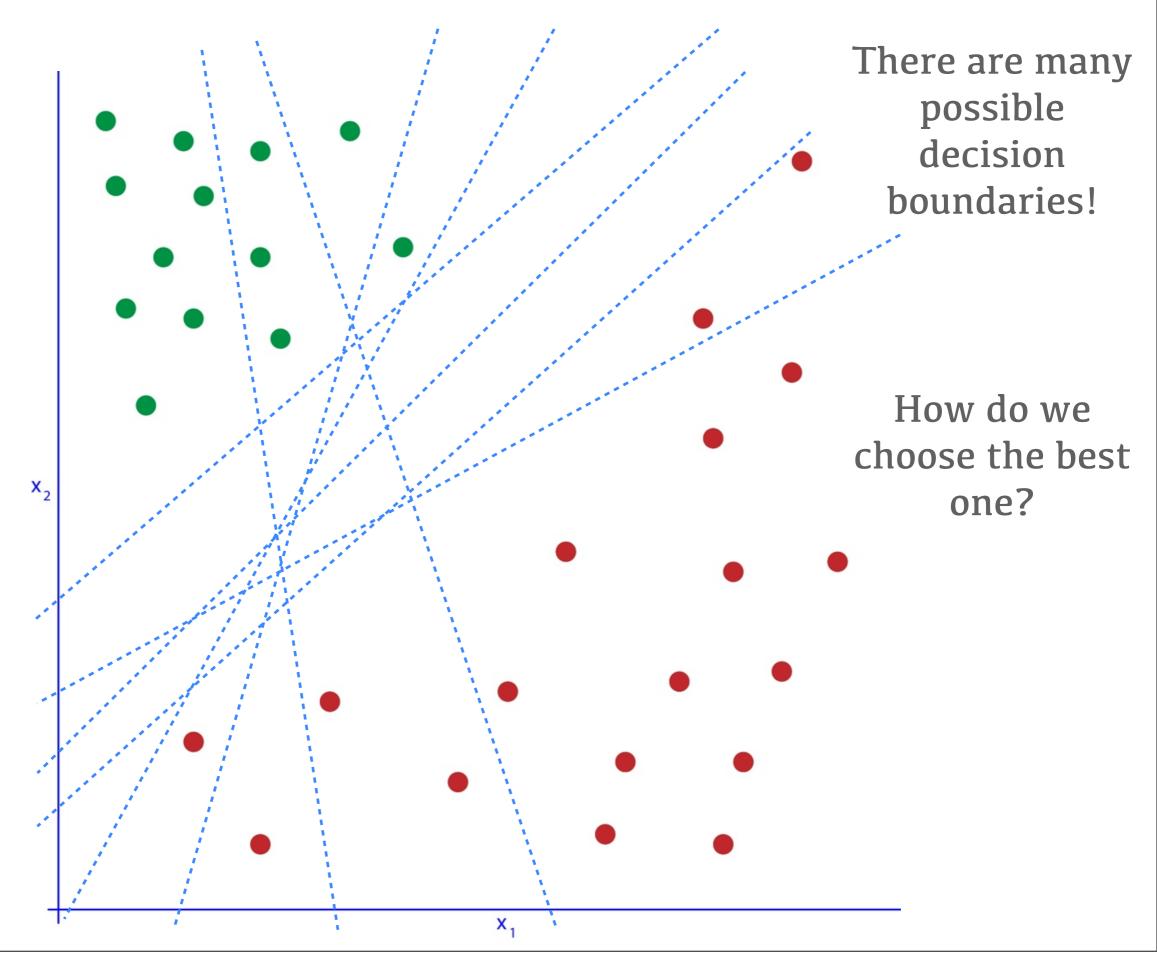


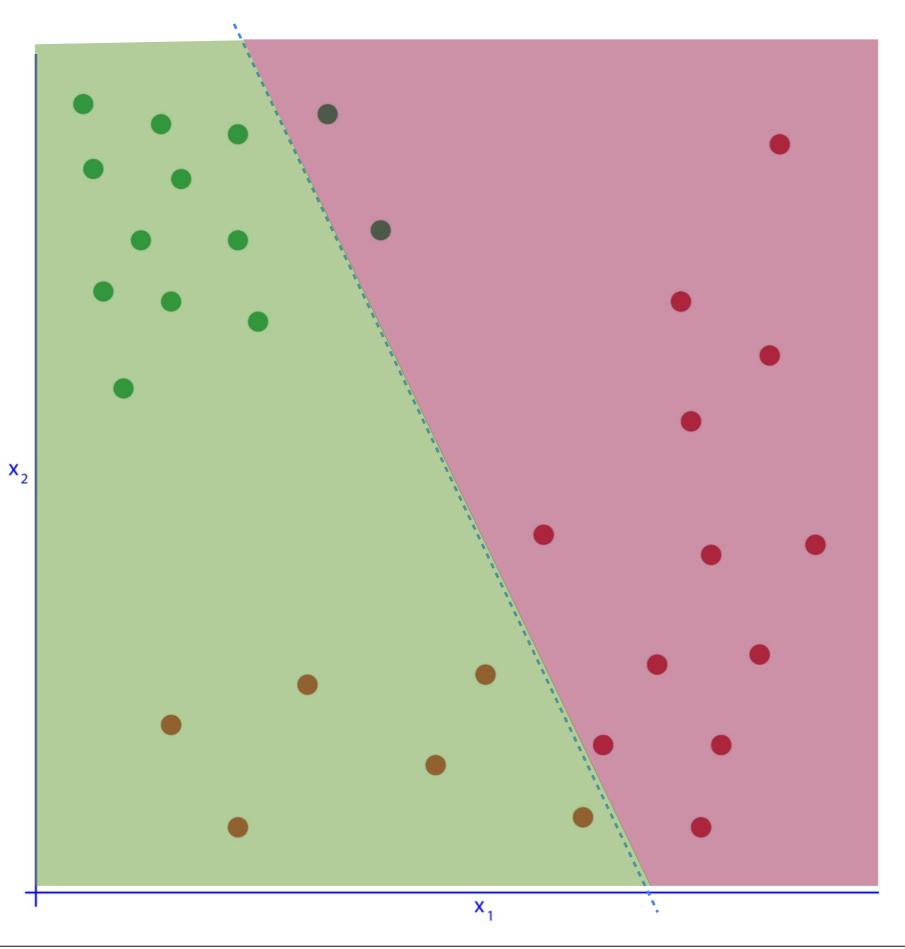


DECISION BOUNDARY



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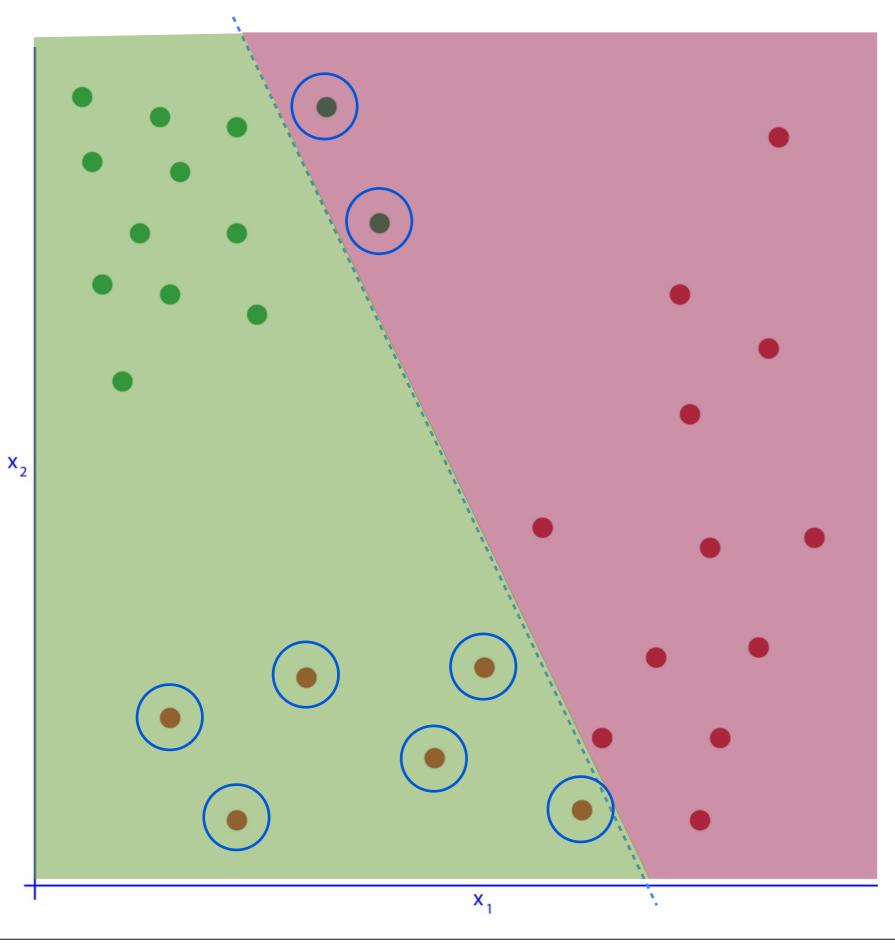




Minimize some error:

Num Correctly Classified Examples

Num Examples

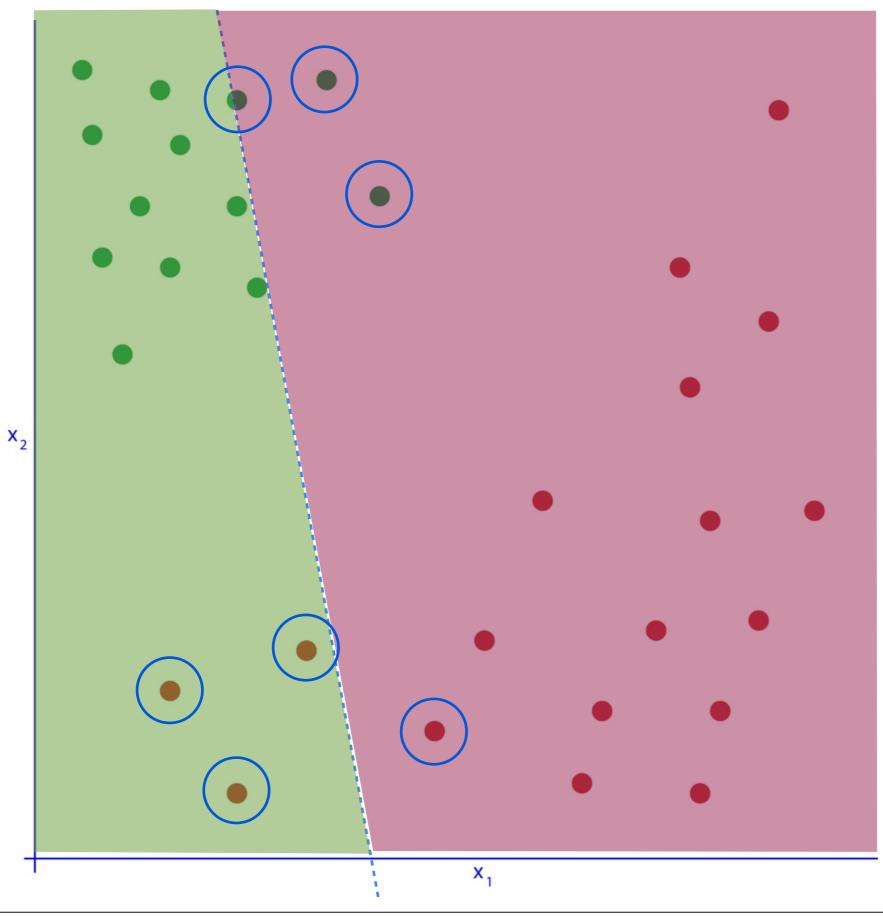


Minimize some error:

Num Correctly Classified Examples

Num Examples

Error = 0.31

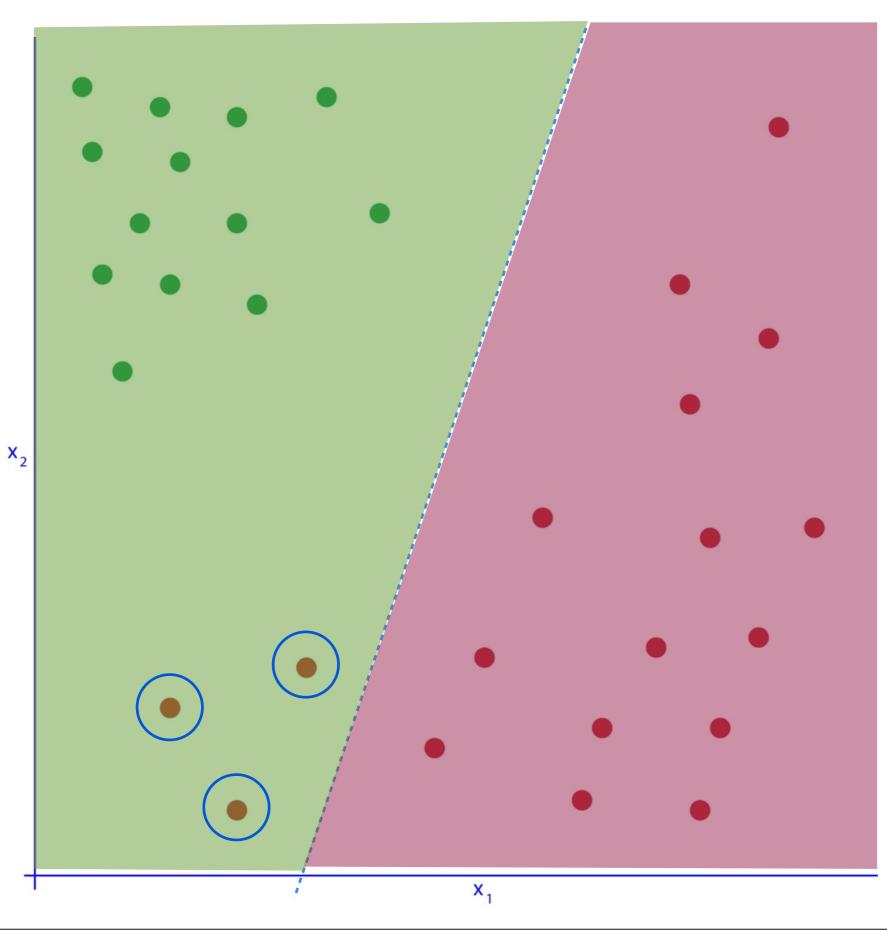


Minimize some error:

Num Correctly Classified Examples

Num Examples

Error = 0.22



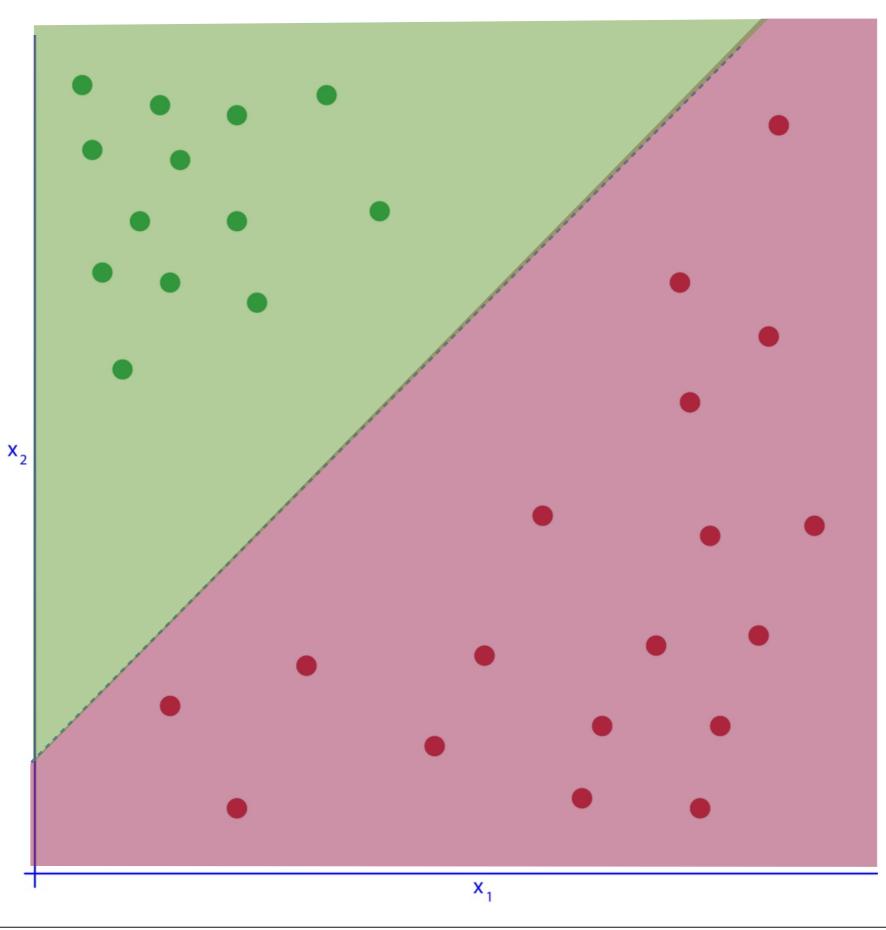
Minimize some error:

Num Correctly Classified Examples

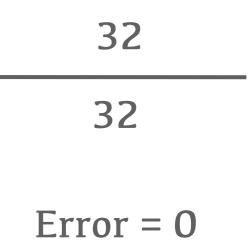
Num Examples

28 32

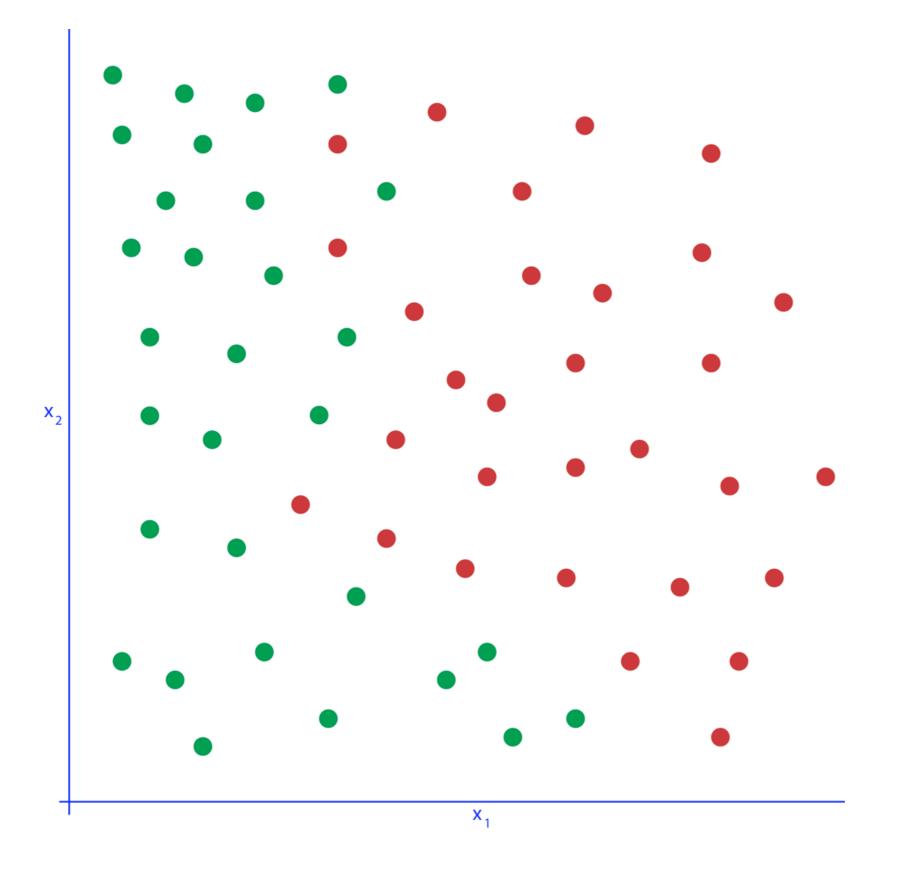
Error = 0.12



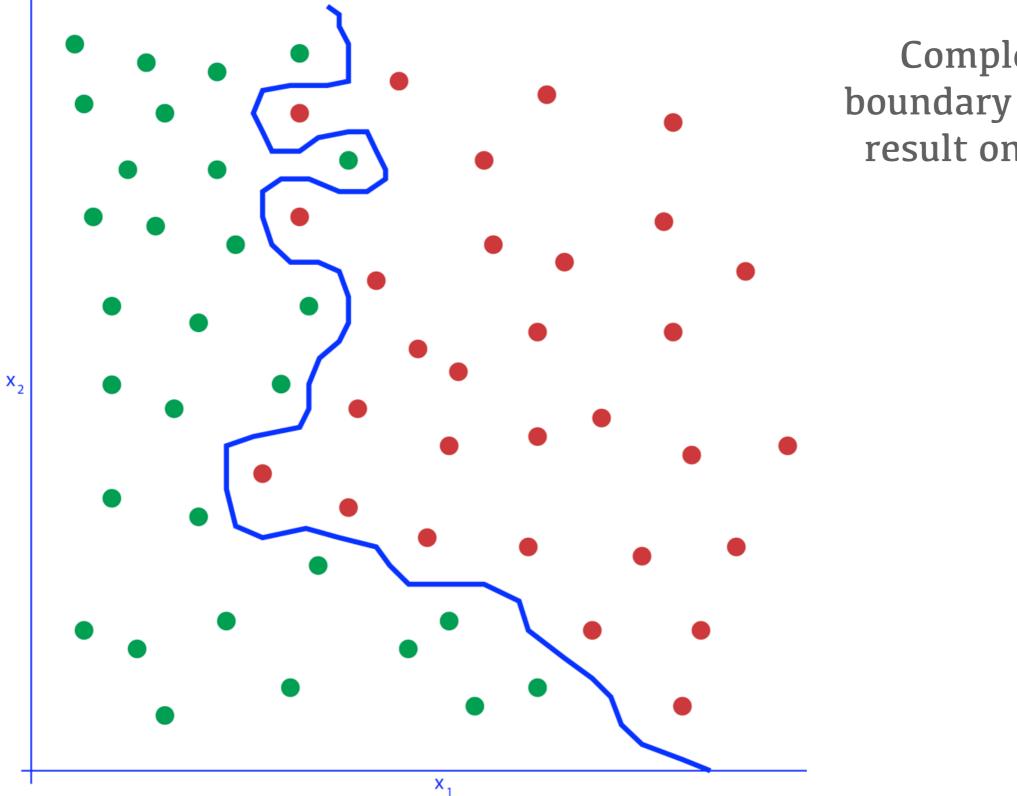
Stop when this error is small



Need to be careful that we don't overtrain the model...

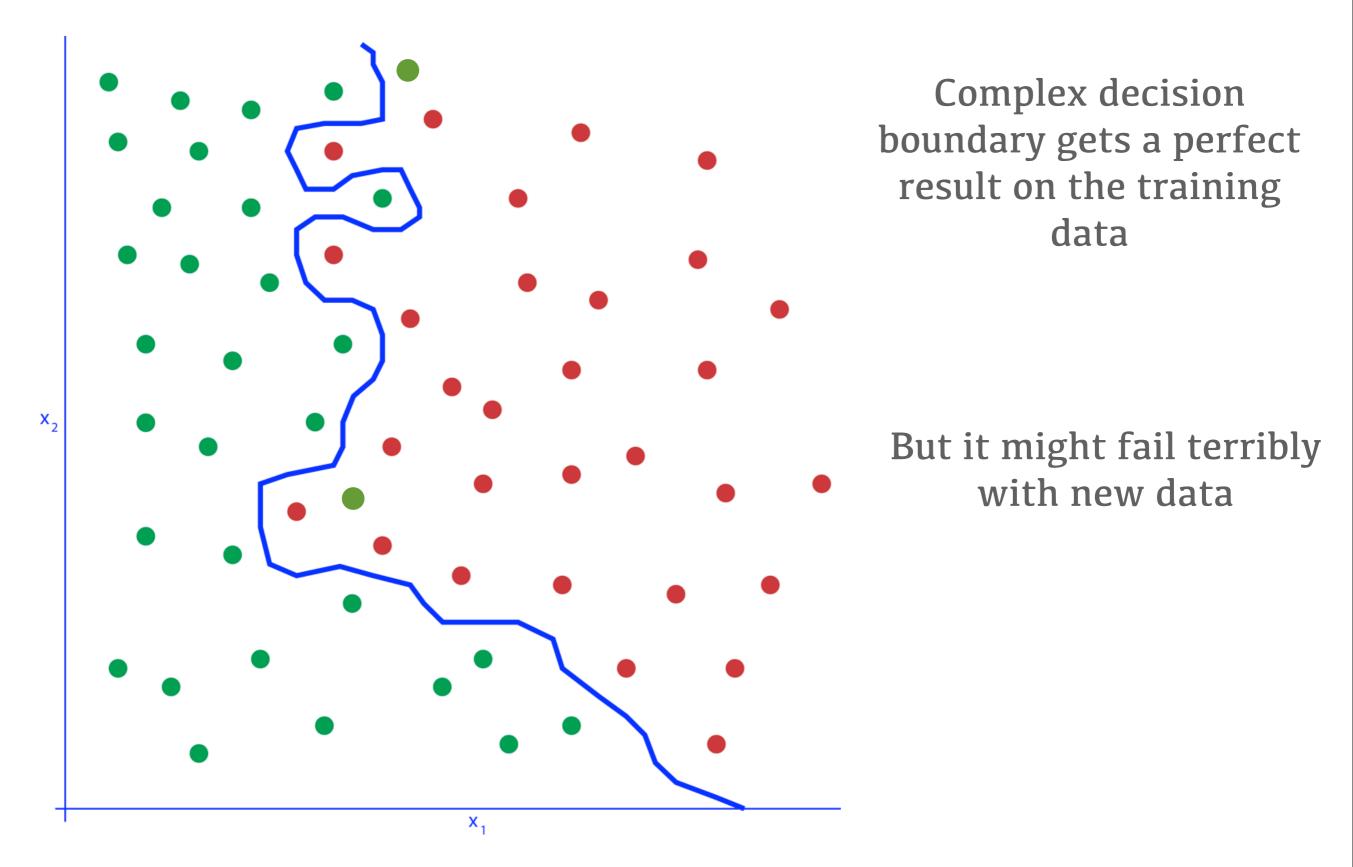


Need to be careful that we don't overtrain the model...

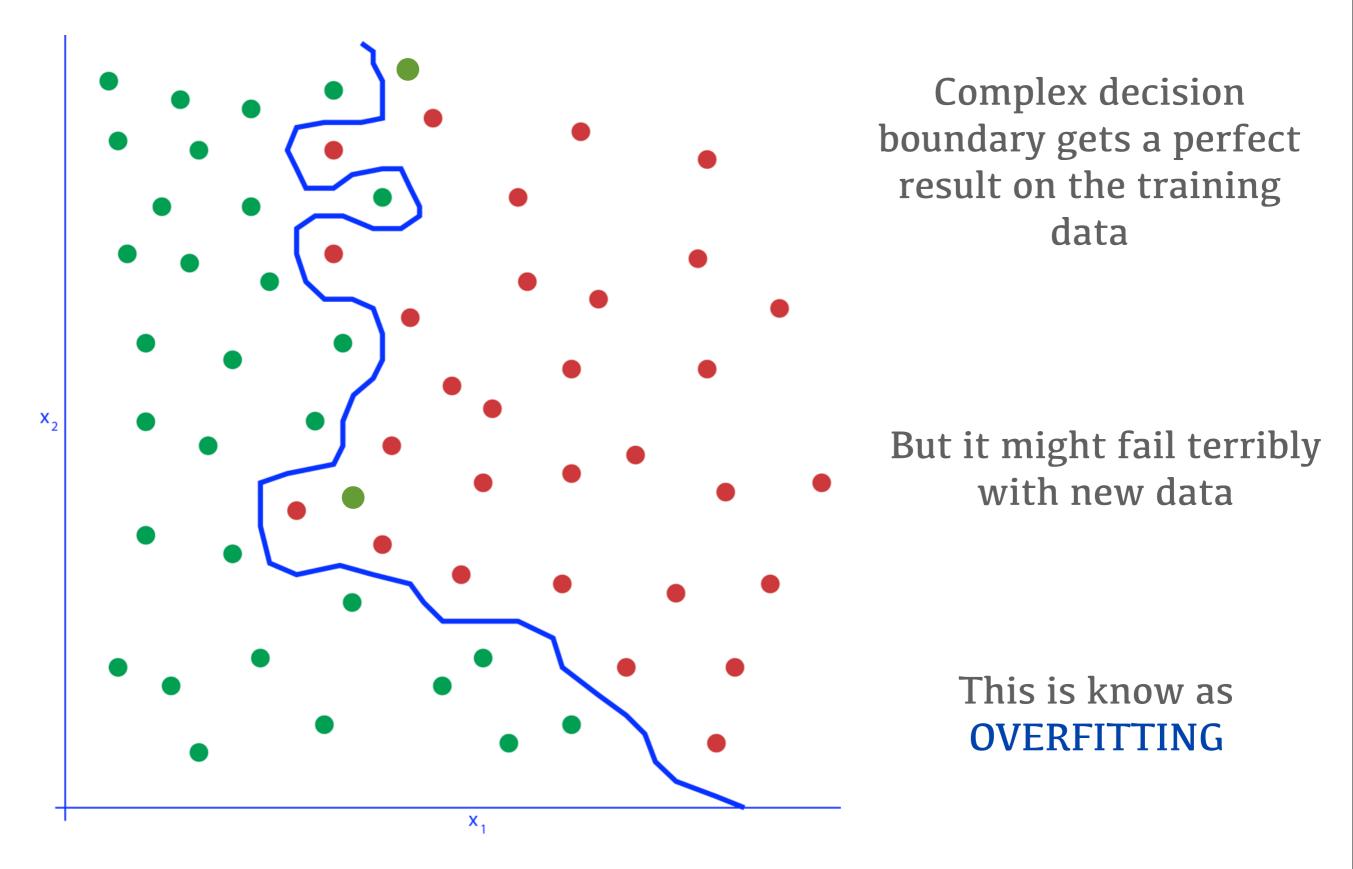


Complex decision boundary gets a perfect result on the training data

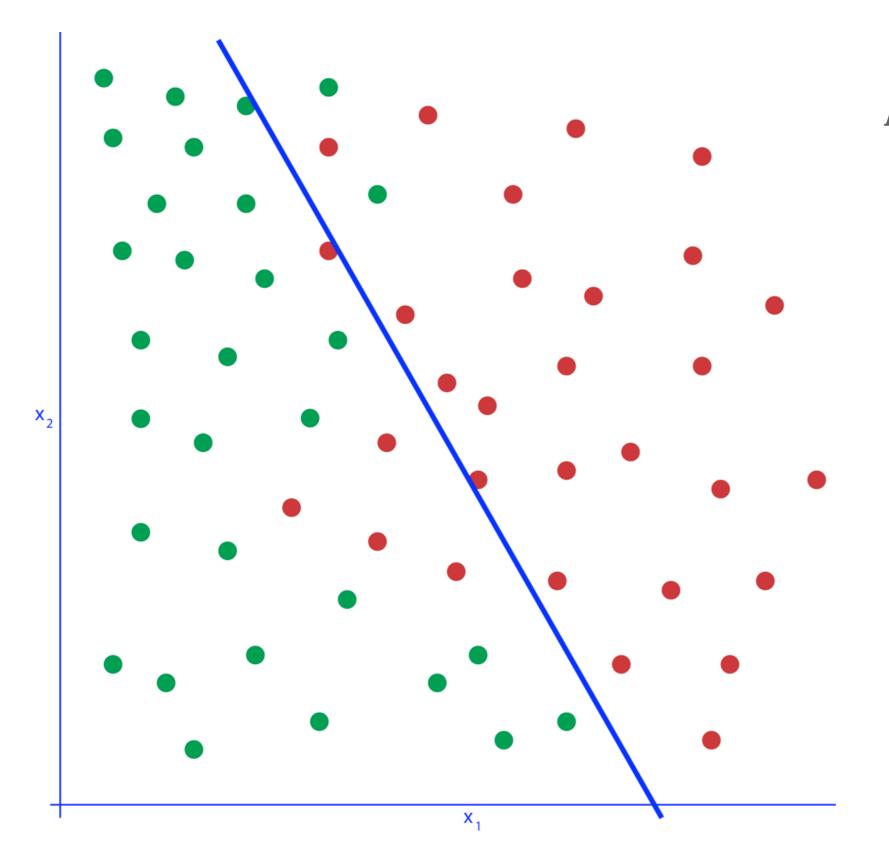
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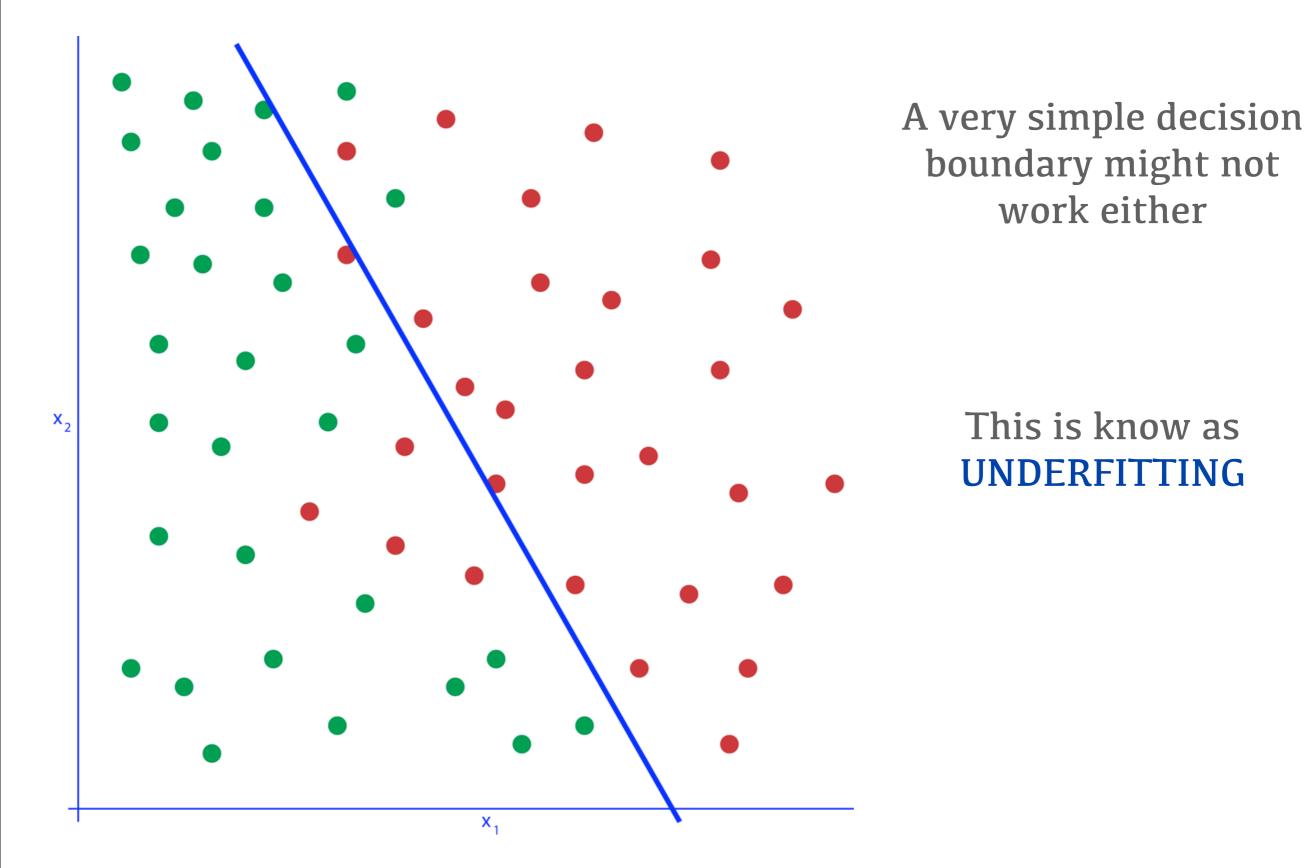


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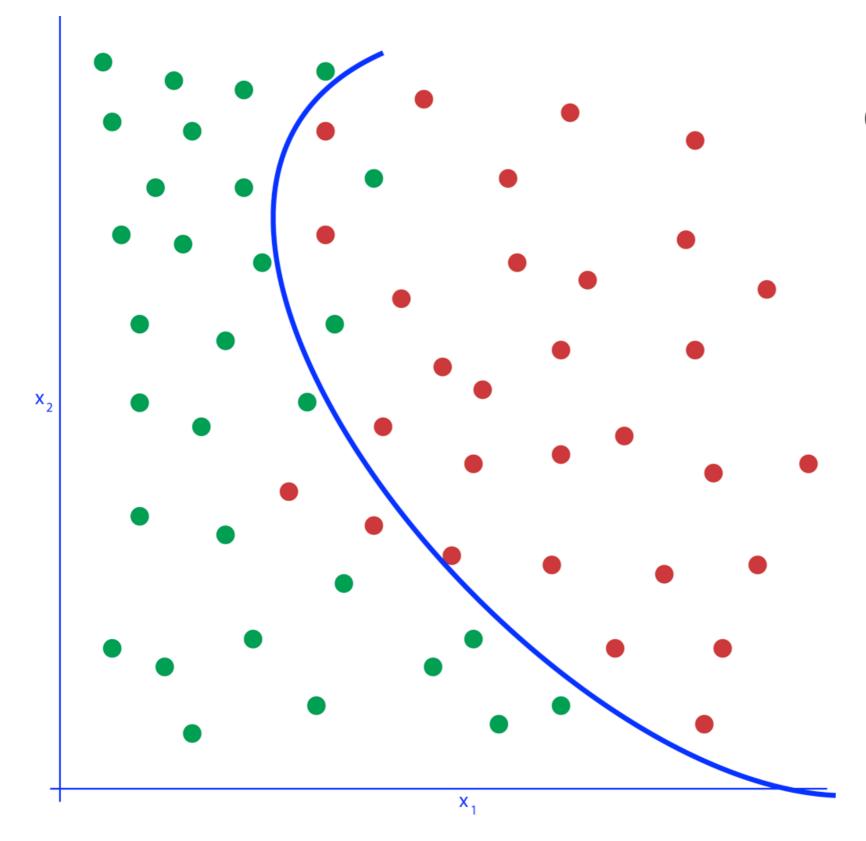


A very simple decision boundary might not work either

Need to be careful that we don't overtrain the model...

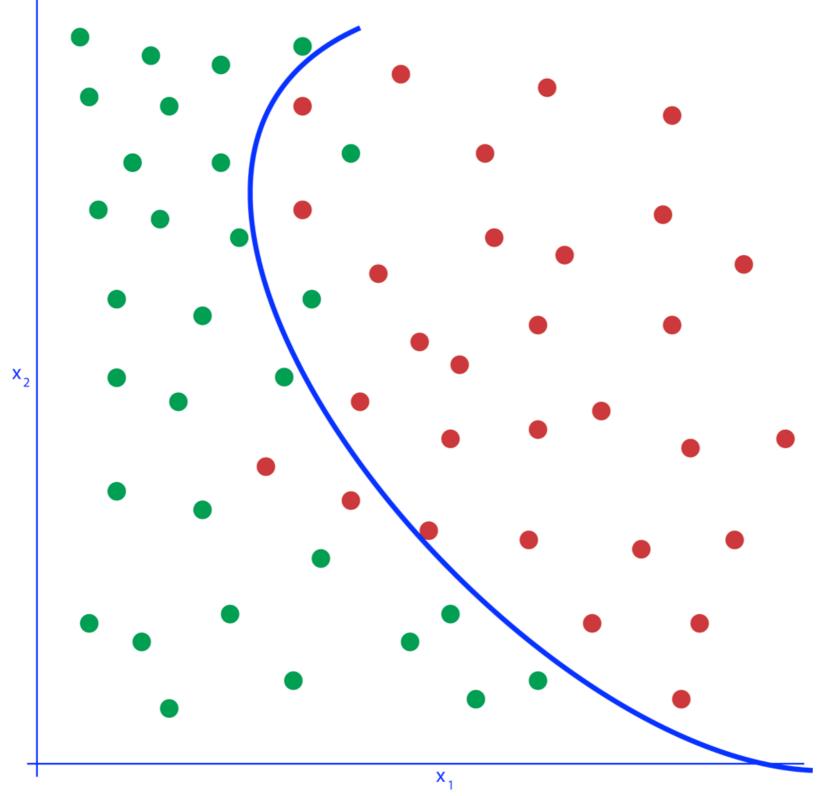


Need to be careful that we don't overtrain the model...



Instead, a less complex decision boundary might work much better, even if it does not perfectly reduce the error on the training data

Need to be careful that we don't overtrain the model...



Instead, a less complex decision boundary might work much better, even if it does not perfectly reduce the error on the training data

A model's ability to correctly predict the values of unseen data is know as GENERALIZATION

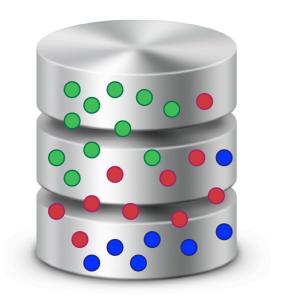
Important not to use the training data to test a model!

Important not to use the training data to test a model!

Instead use a test dataset

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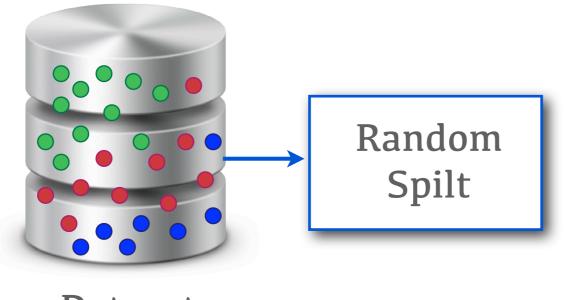
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Dataset

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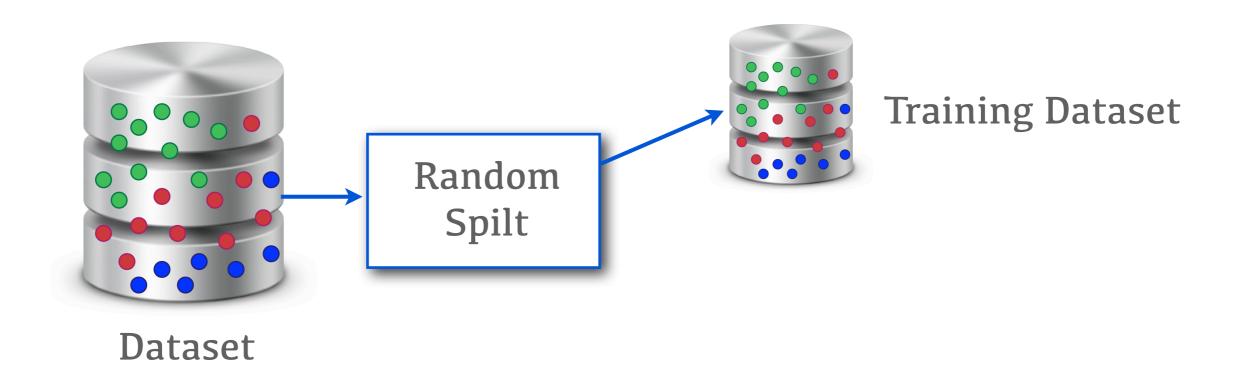
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Dataset

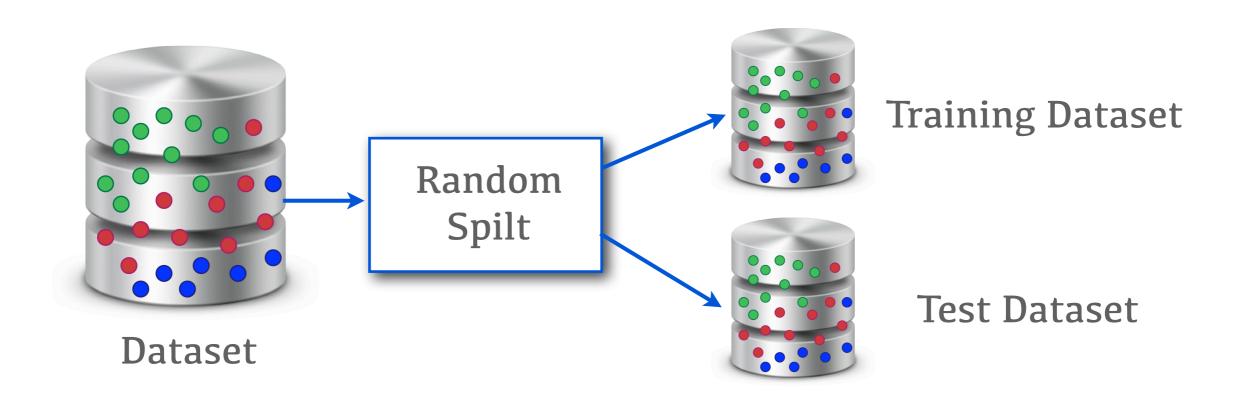
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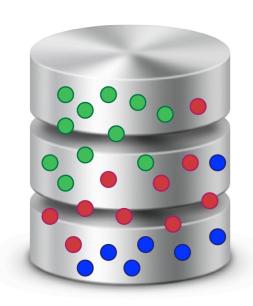
Sometimes there is not enough data to create a test dataset

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Instead use K-FOLD CROSS VALIDATION

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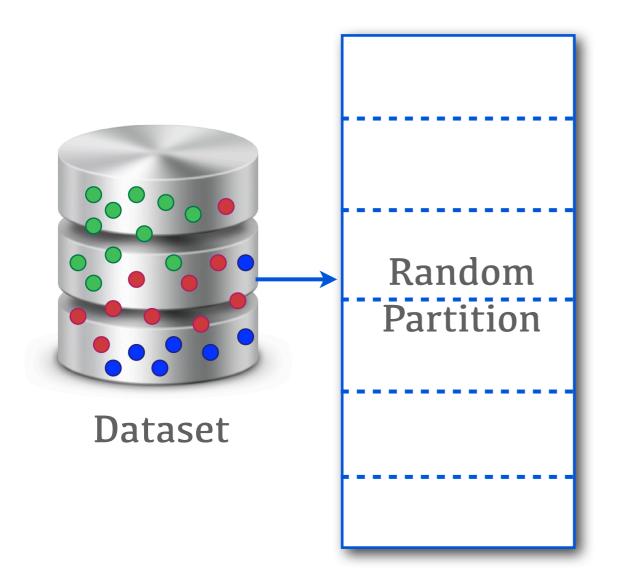
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Dataset

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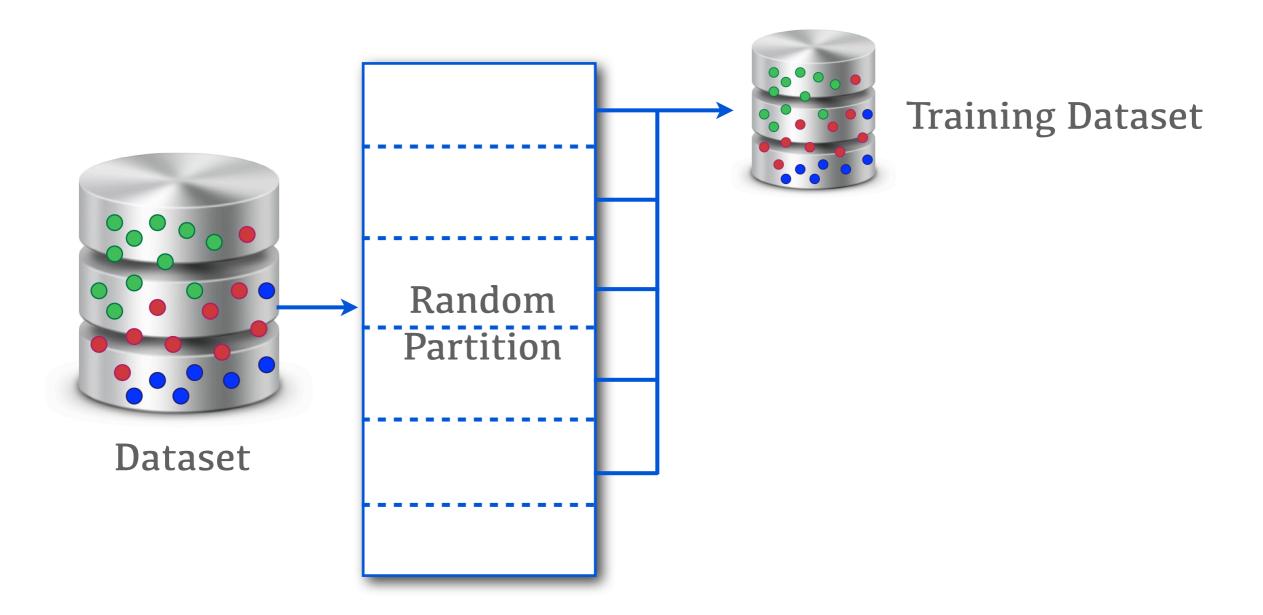
Instead use K-FOLD CROSS VALIDATION



Partition Data into K Folds

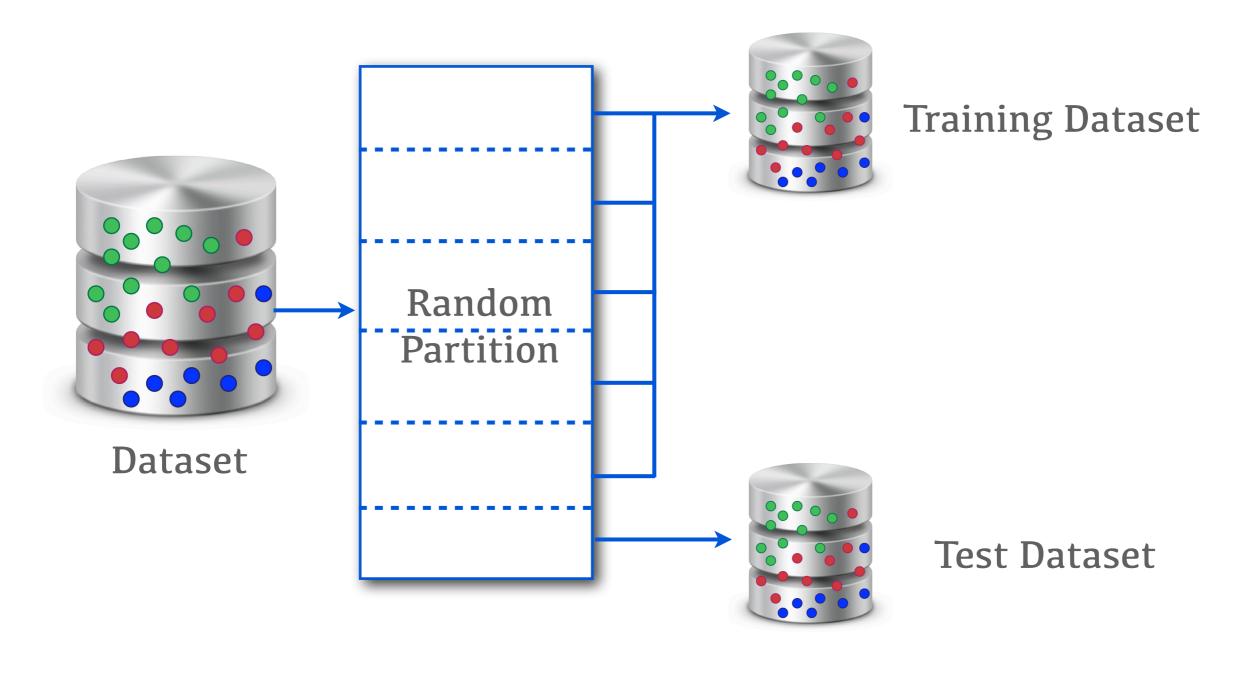
Sometimes there is not enough data to create a test dataset

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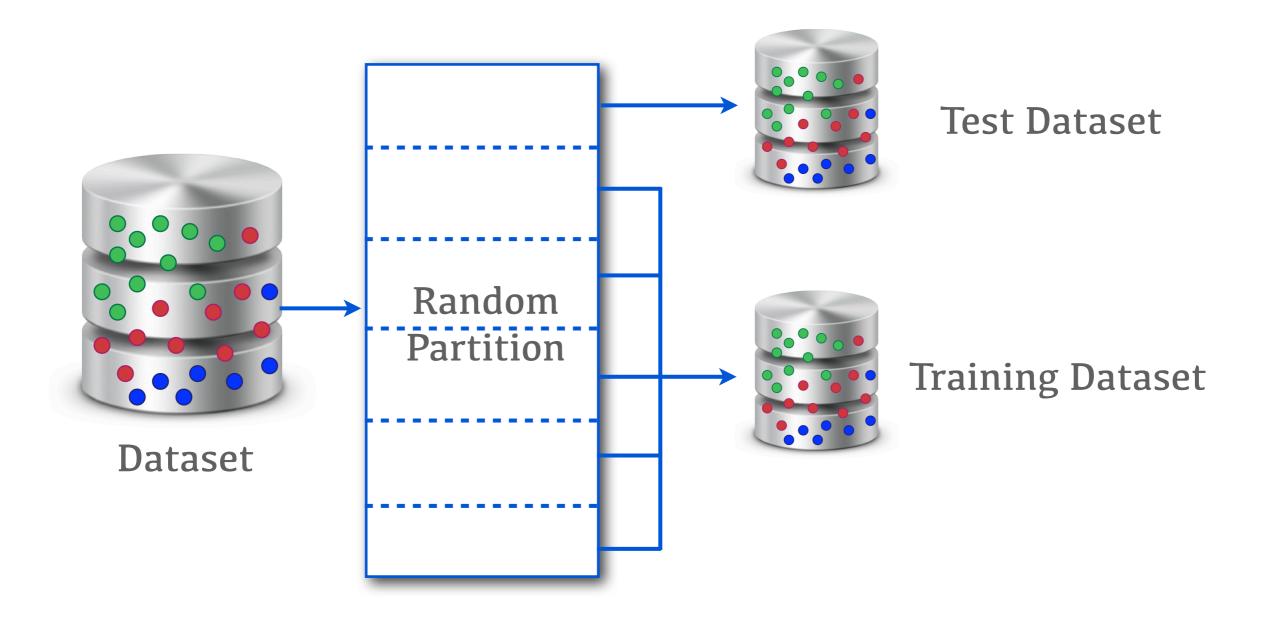
Instead use K-FOLD CROSS VALIDATION



Fold 1

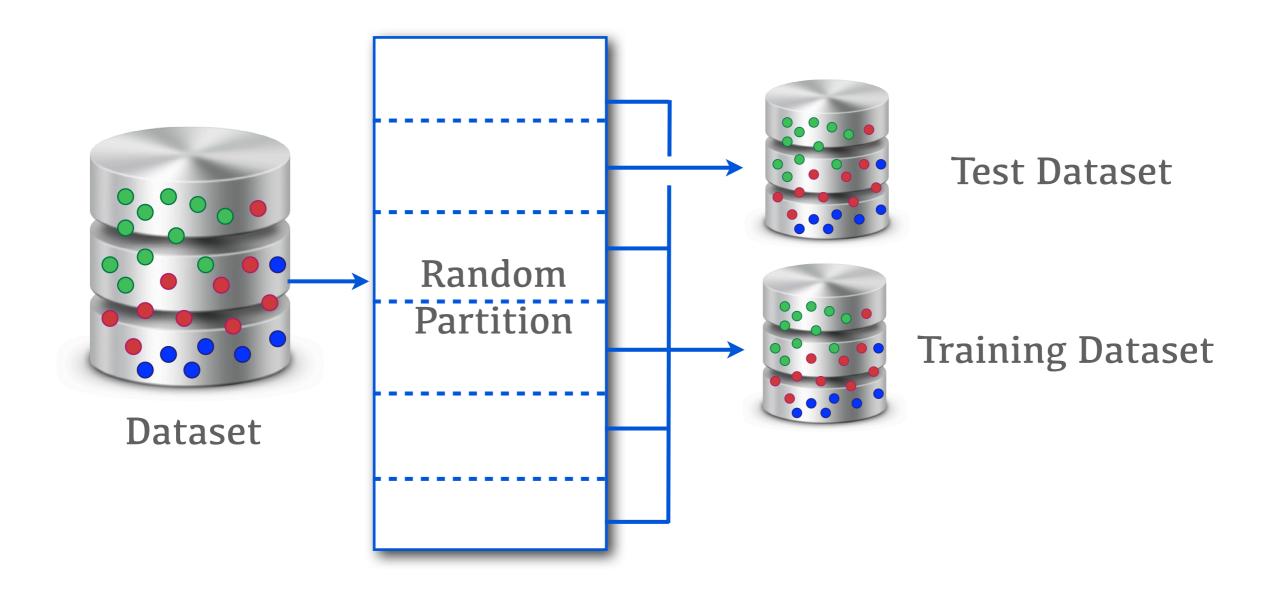
Sometimes there is not enough data to create a test dataset

Instead use K-FOLD CROSS VALIDATION



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Num Correctly Classified Examples

Classification Accuracy =

Num Test Examples

Classification Accuracy =

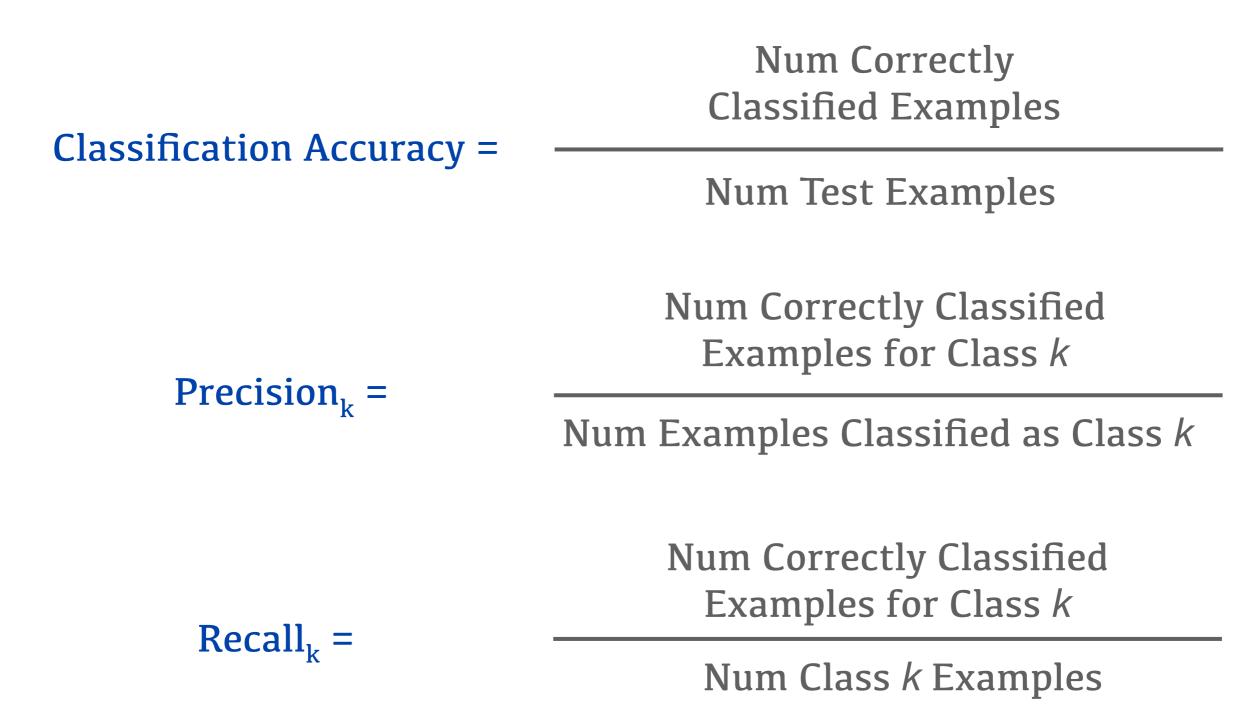
Num Correctly Classified Examples

Num Test Examples

Num Correctly Classified Examples for Class k

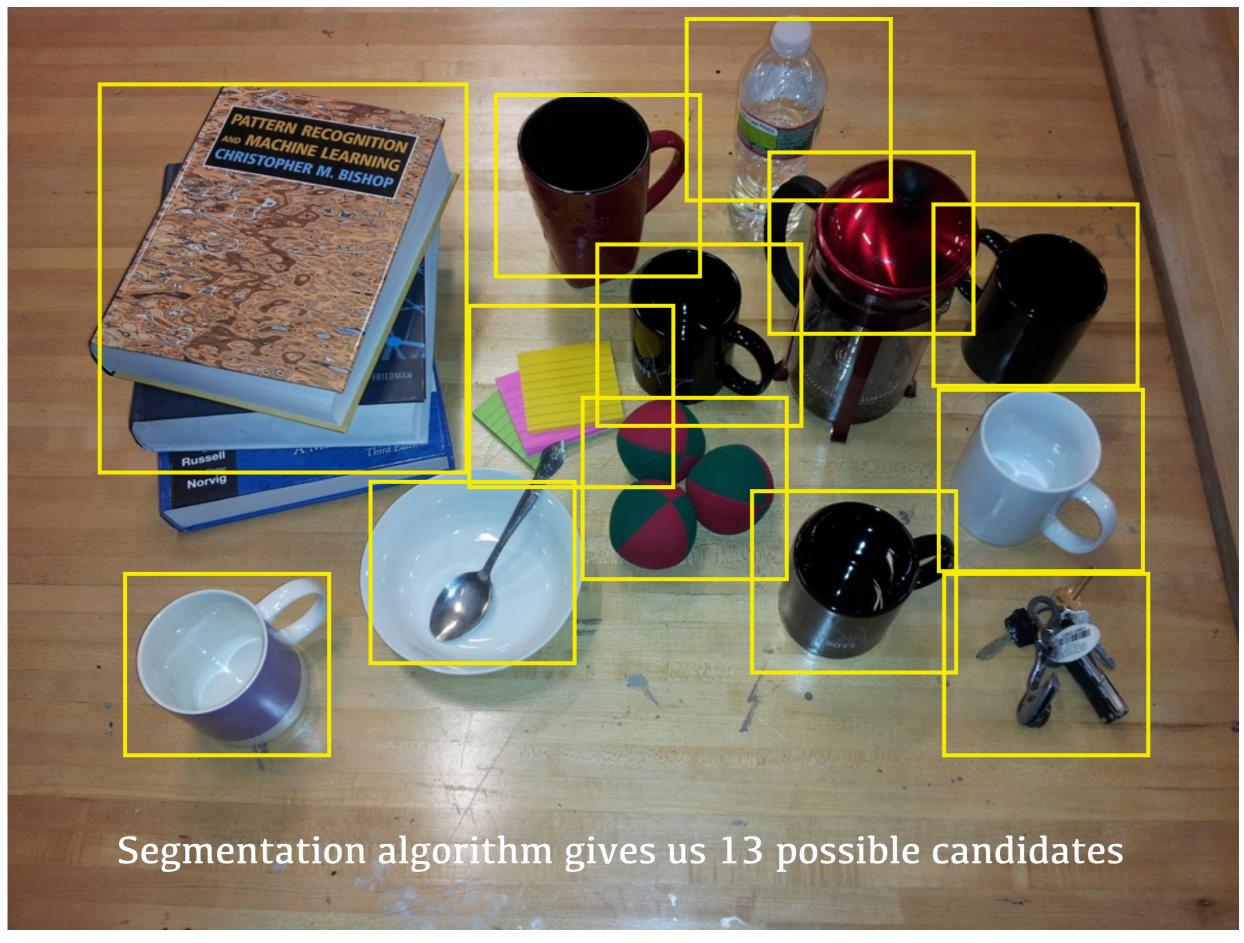
Precision_k =

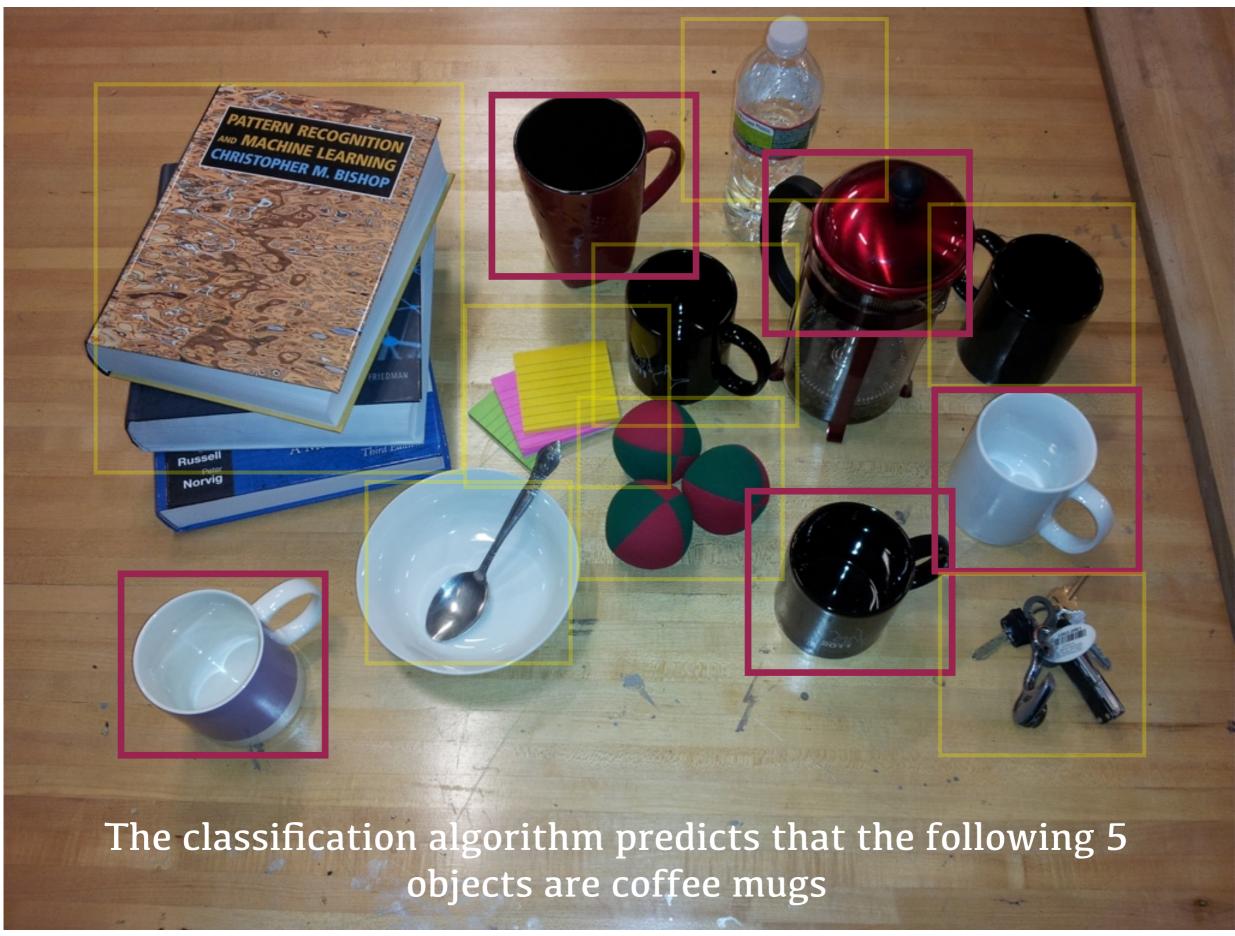
Num Examples Classified as Class k

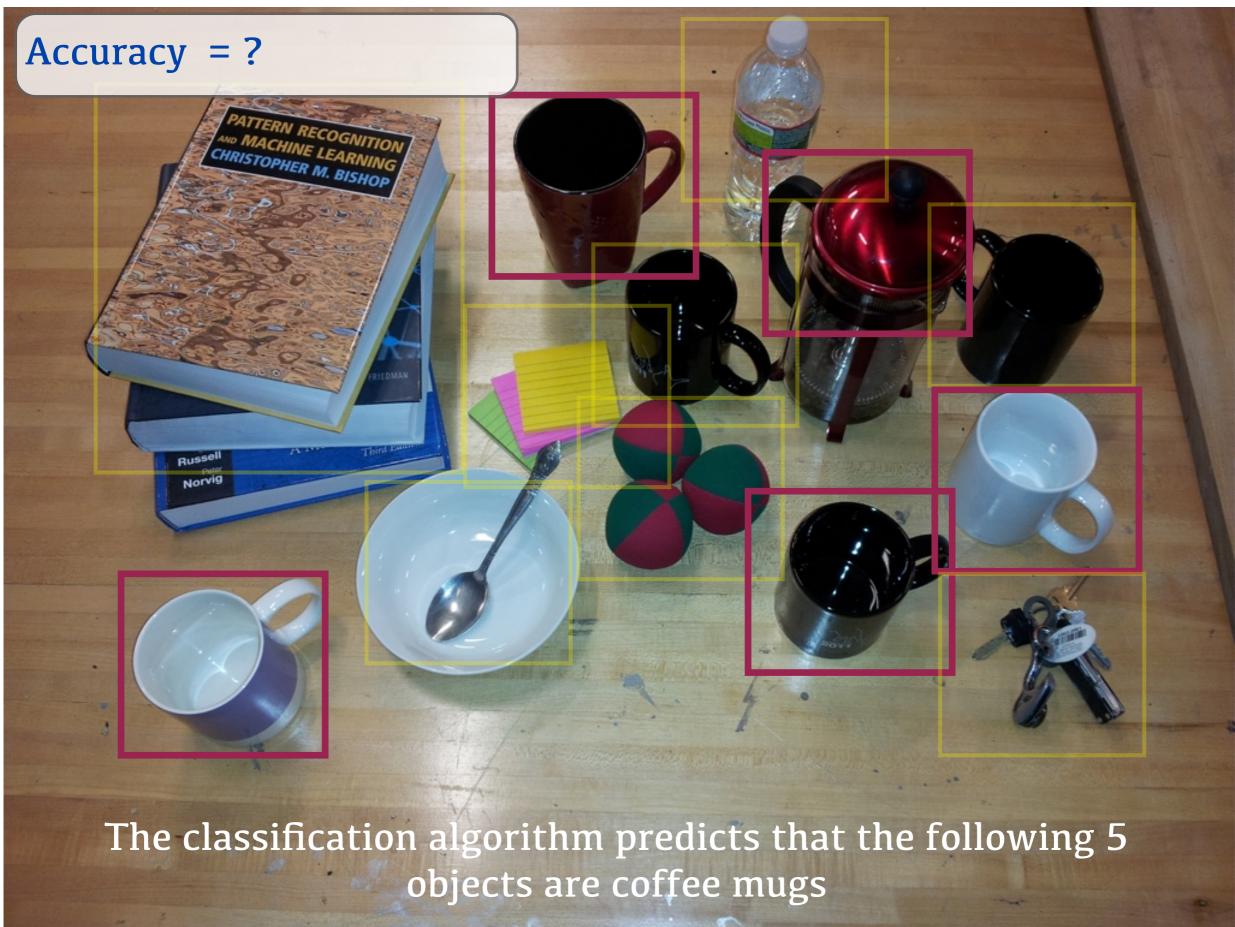


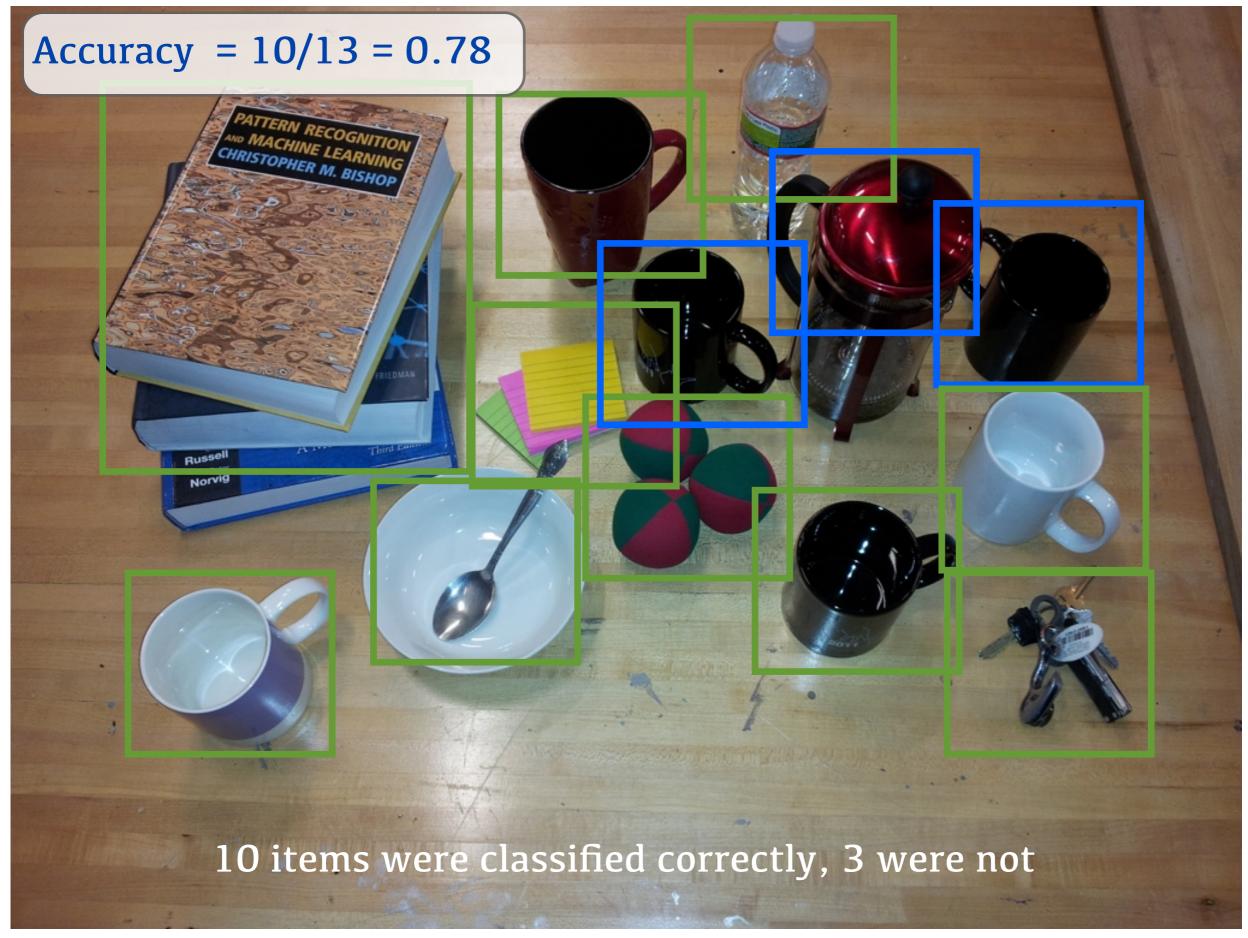
| Classification Accuracy = | Num Correctly Classified Examples |
|------------------------------|---|
| | Num Test Examples |
| Precision _k = | Num Correctly Classified Examples for Class <i>k</i> |
| | Num Examples Classified as Class k |
| Recall _k = | Num Correctly Classified Examples for Class <i>k</i> |
| | Num Class <i>k</i> Examples |
| F-measure _k = 2 * | Precision _k * Recall _k |
| | Precision _k + Recall _k |

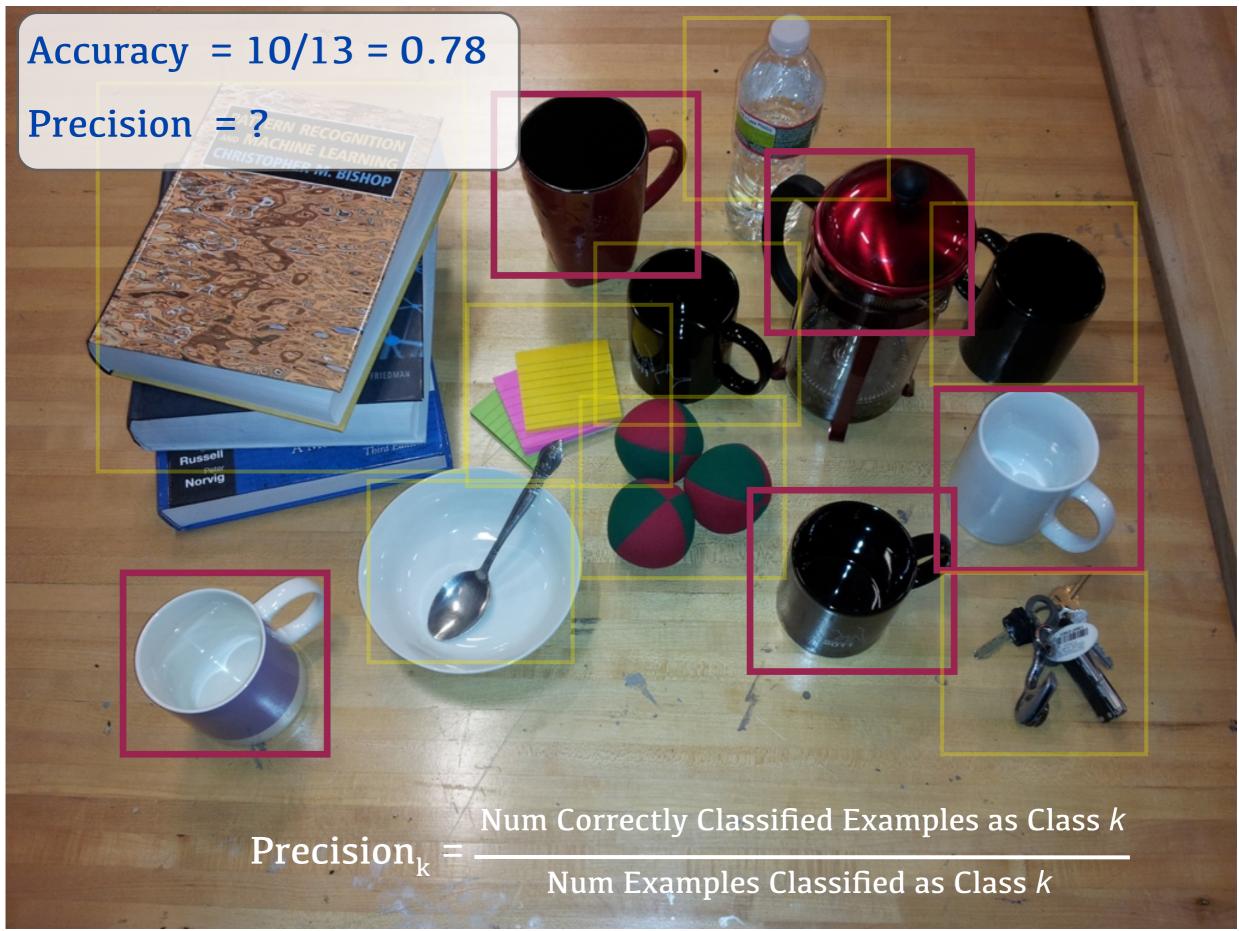


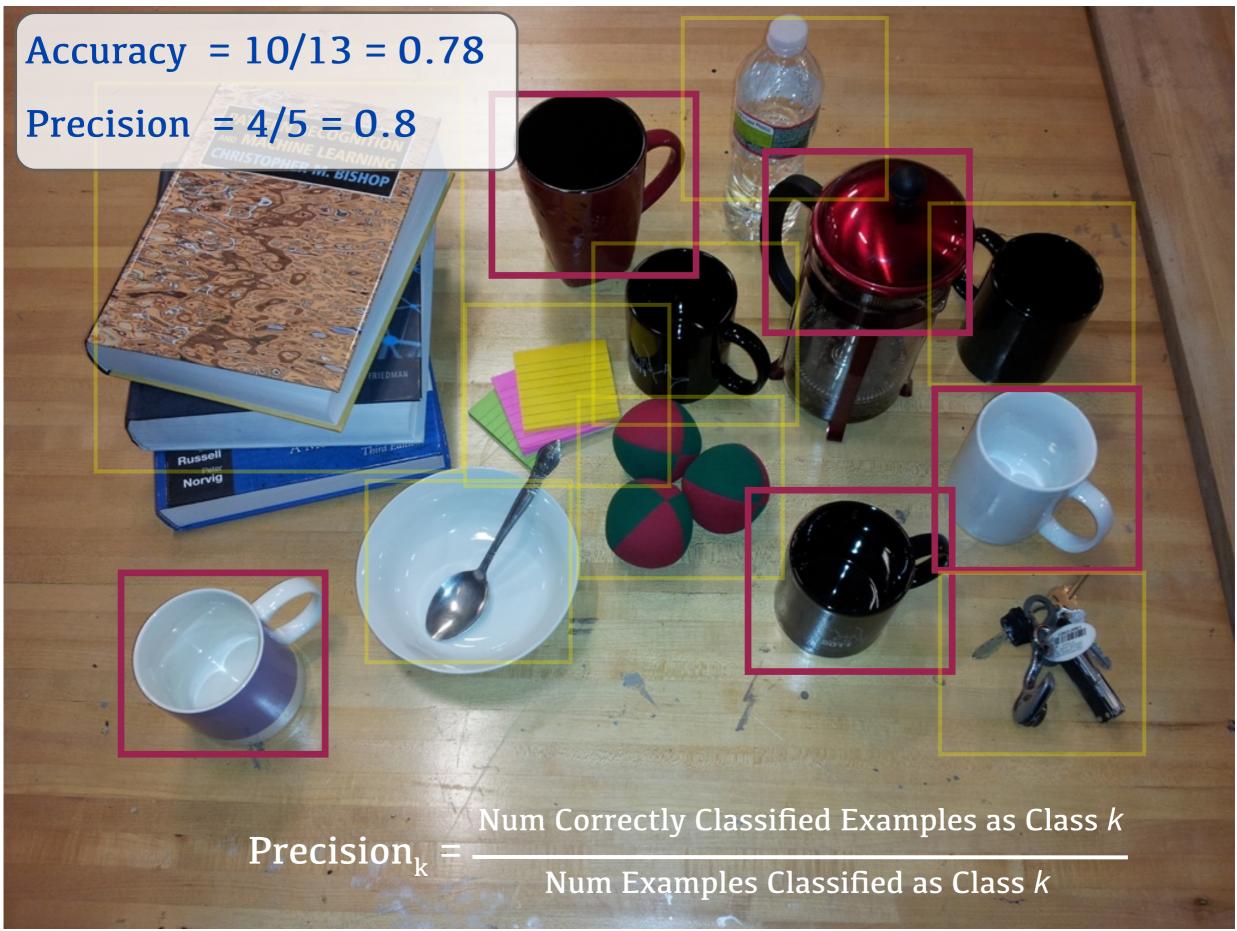


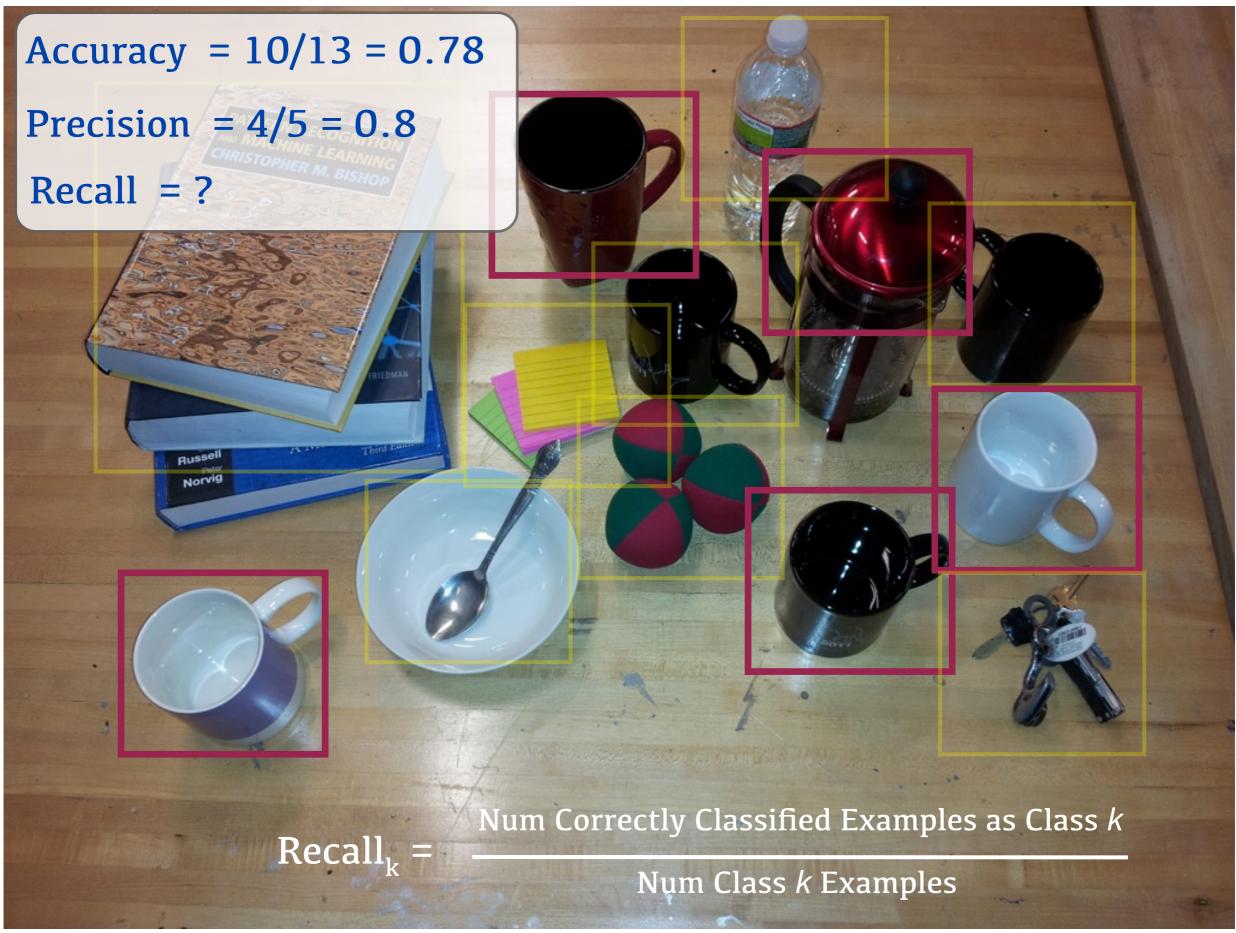


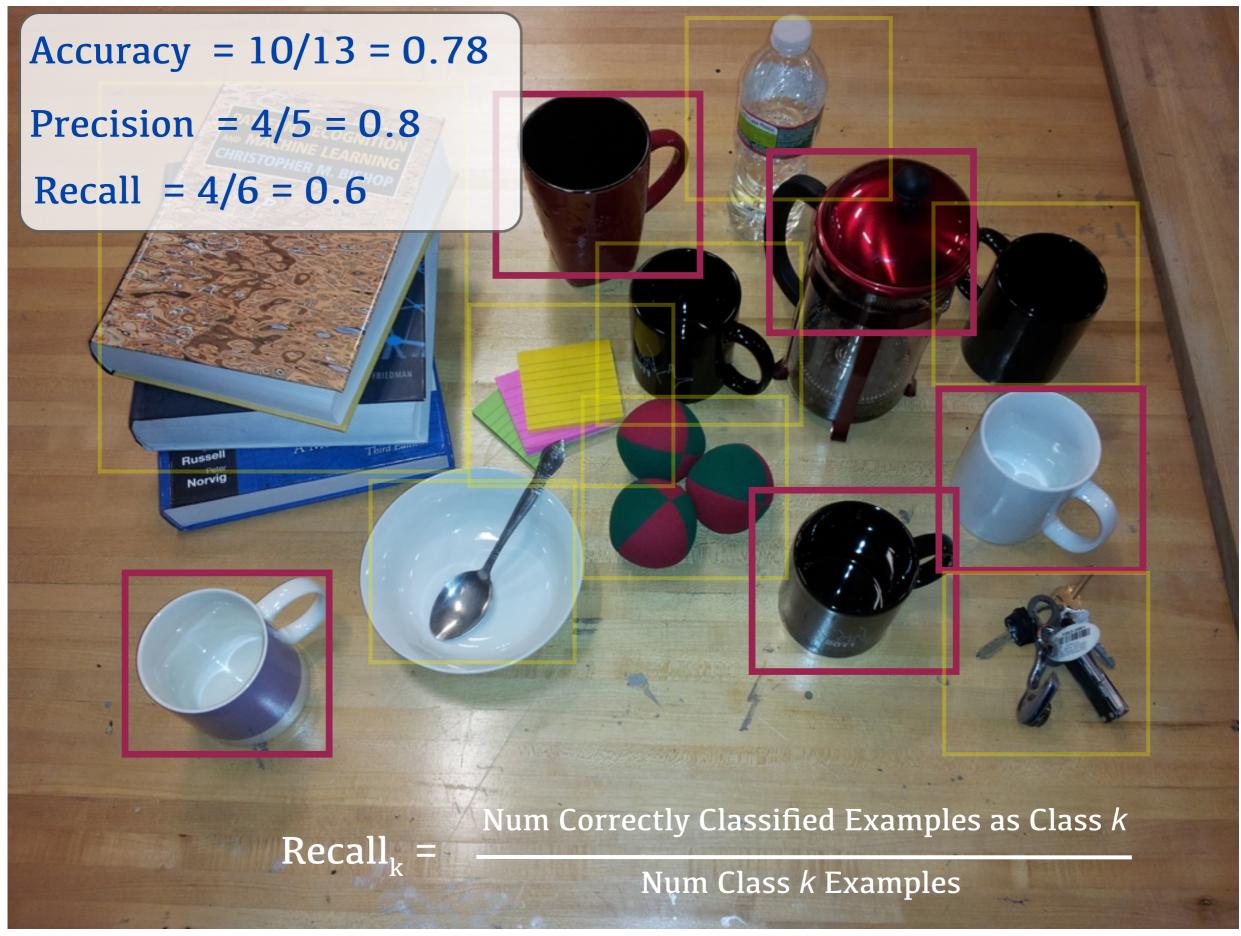


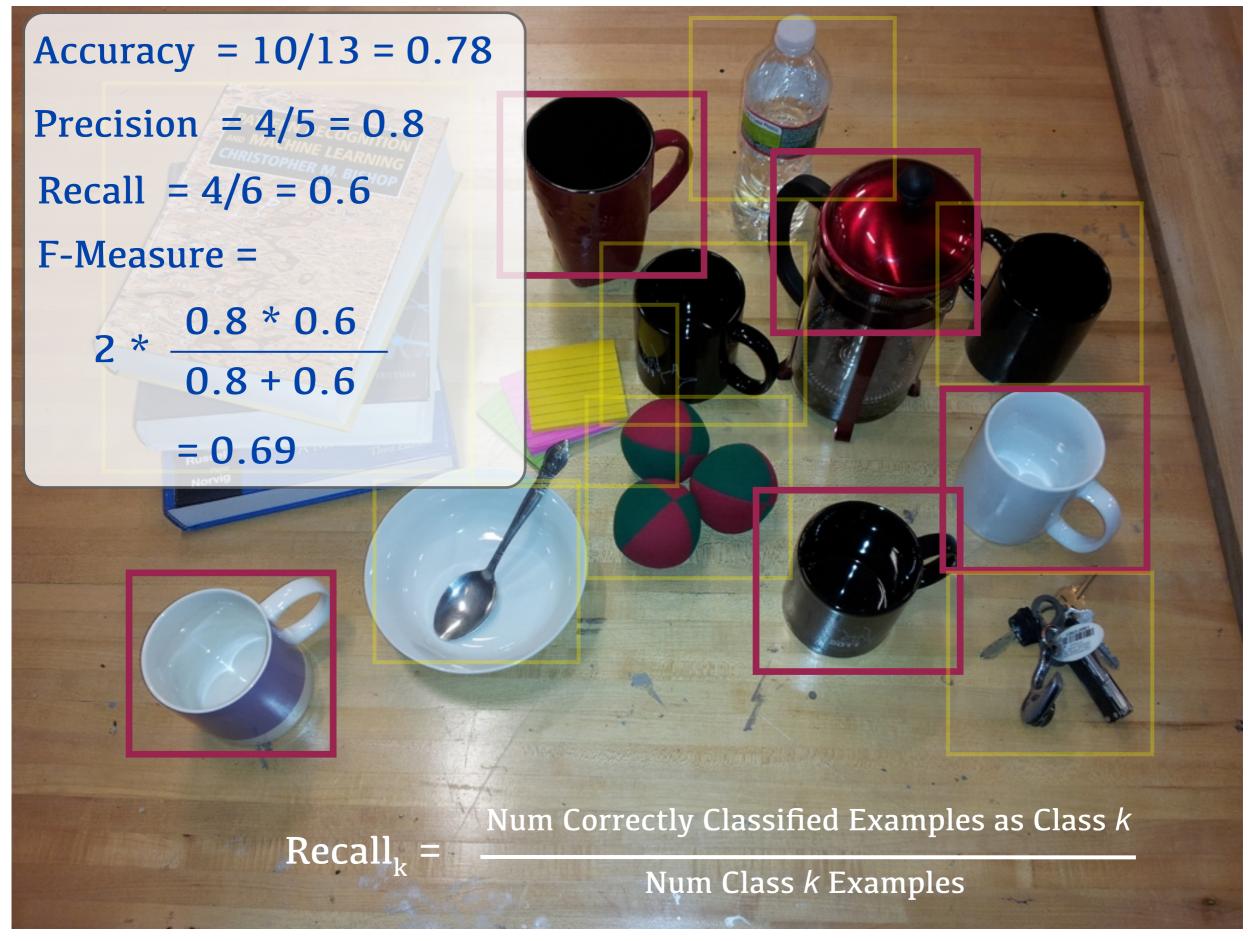








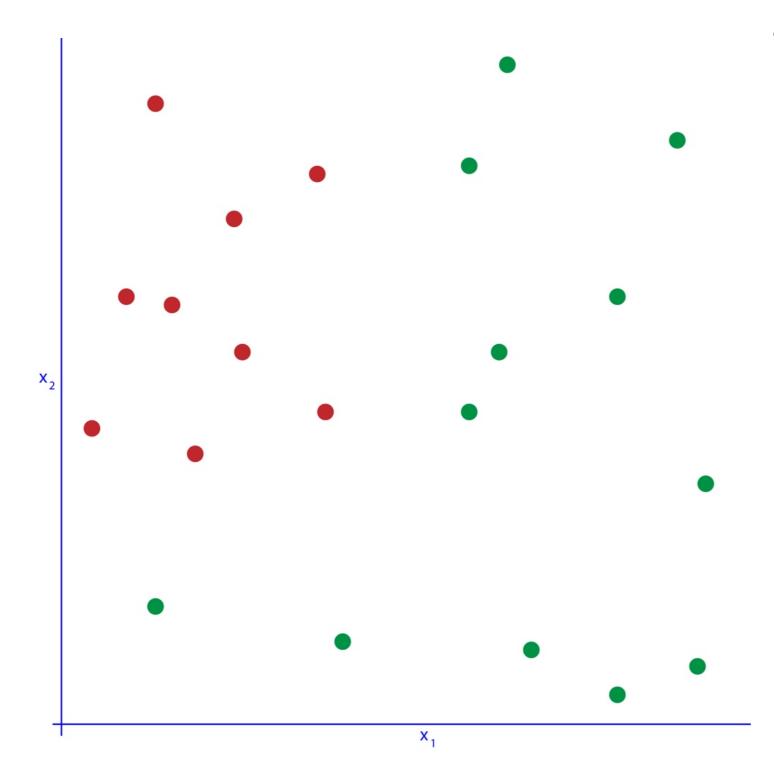




A Simple Classifier Example



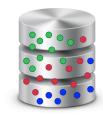
Training Data

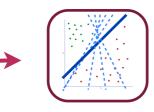


Training Data:

- M Labelled Training Examples

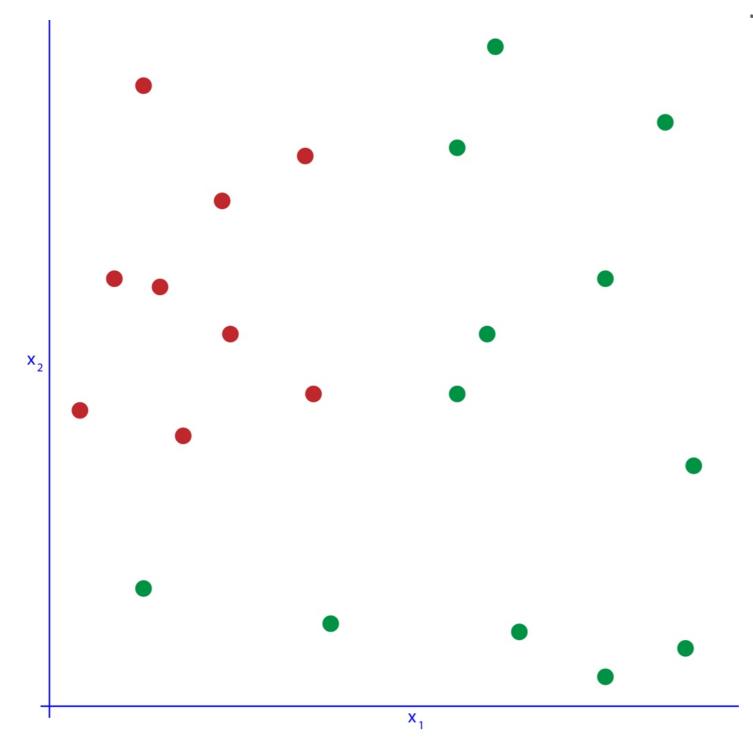
- Each example is an N-Dimensional Vector





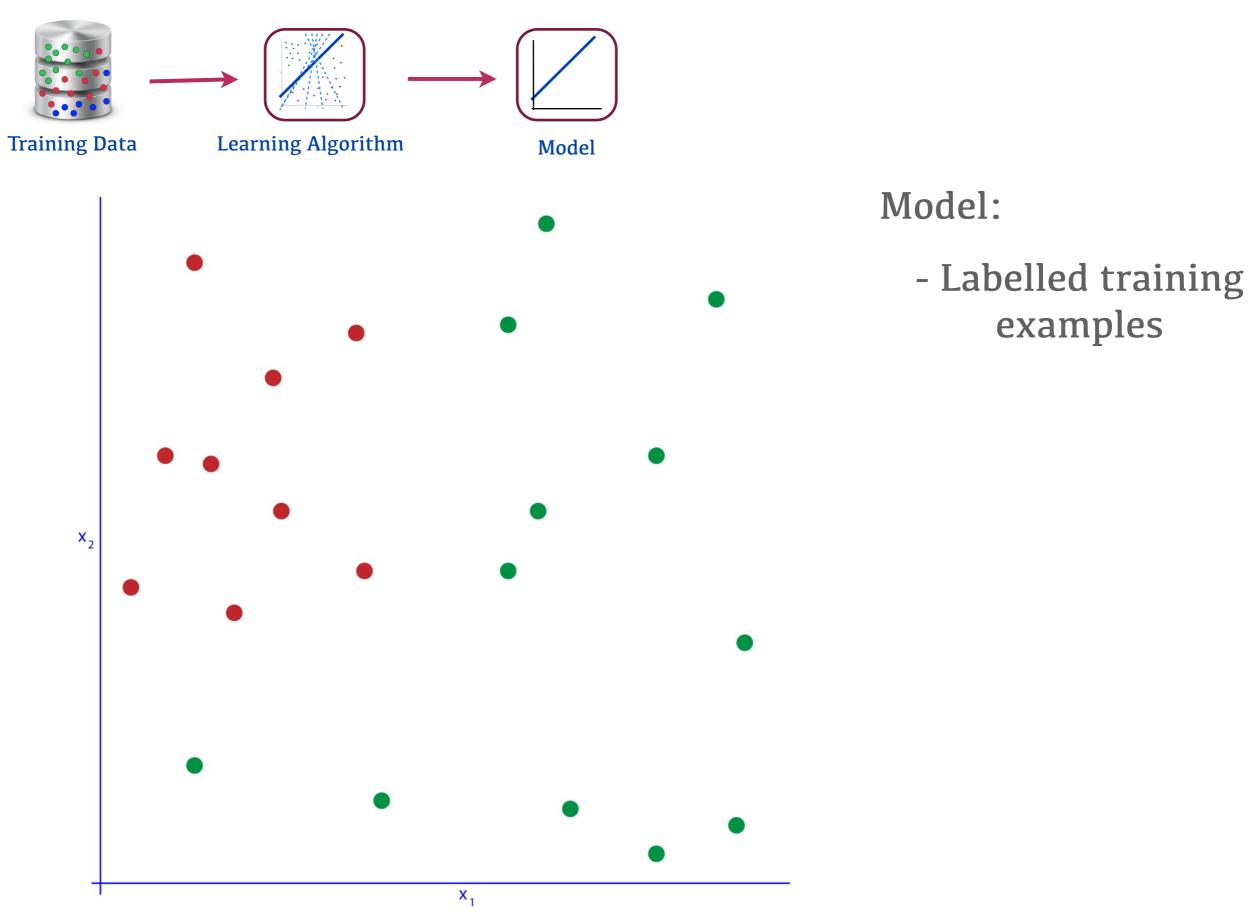
Training Data

Learning Algorithm



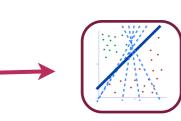
Training Phase:

- Simply save the labelled training examples

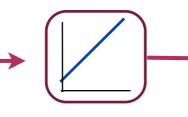




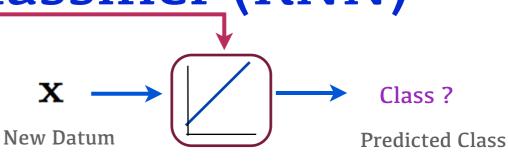
Training Data



Learning Algorithm

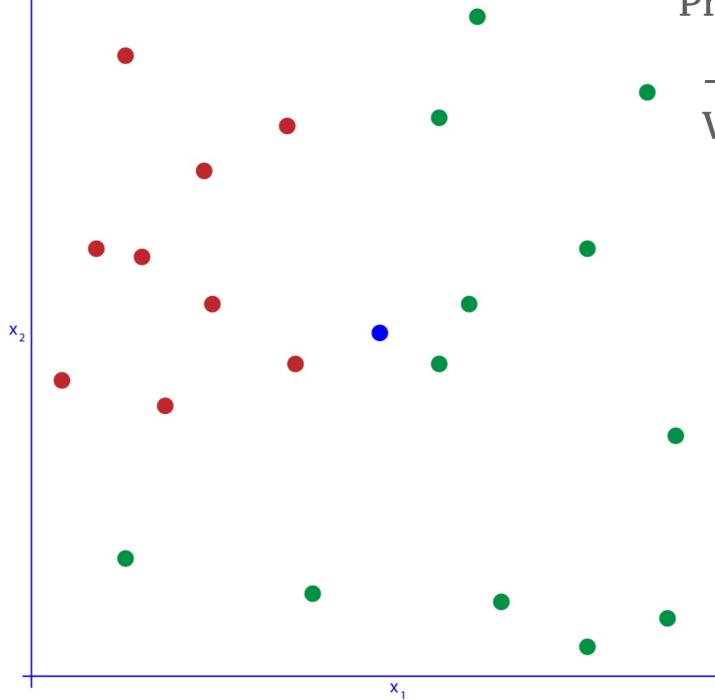


Model



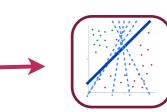
Prediction Phase:

- Given a new N-Dimensional Vector, predict which class it belongs to



Model







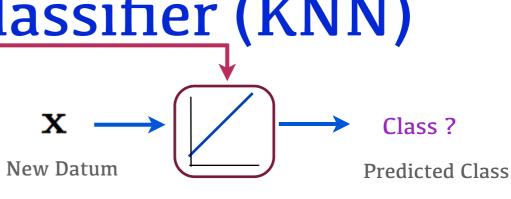
Training Data

x₂

Learning Algorithm

K = 3

X₁



Prediction Phase:

- Given a **new** N-Dimensional Vector, predict which class it belongs to

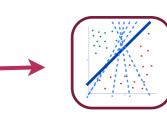
- Find the K Nearest Neighbors in the training examples

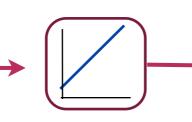
- Classify **x** as the most likely class (i.e. the most common class in the K Nearest Neighbors)

Class A: 2 Class B: 1

Likelihood of belonging to Class A = 0.6



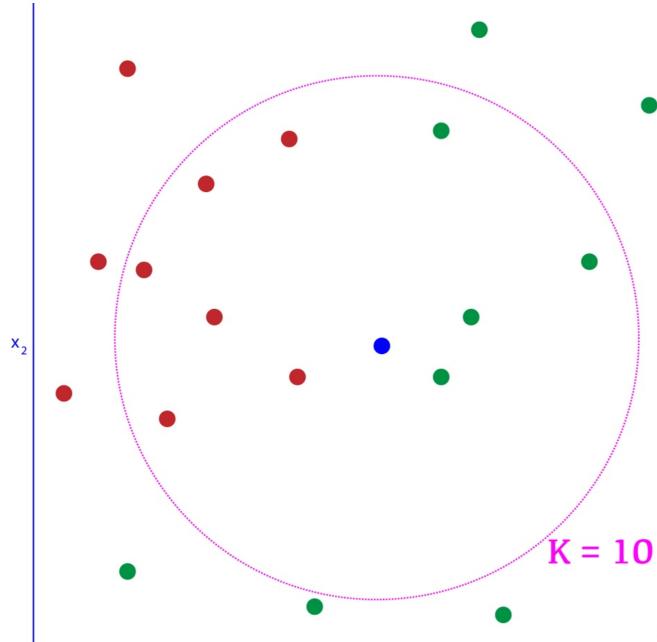




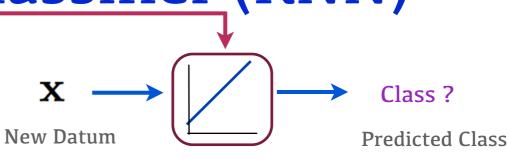
Training Data

Learning Algorithm

Model



X₁



Prediction Phase:

- Given a new N-Dimensional Vector, predict which class it belongs to

- Find the K Nearest Neighbors in the training examples

 Classify x as the most likely class (i.e. the most common class in the K Nearest Neighbors)

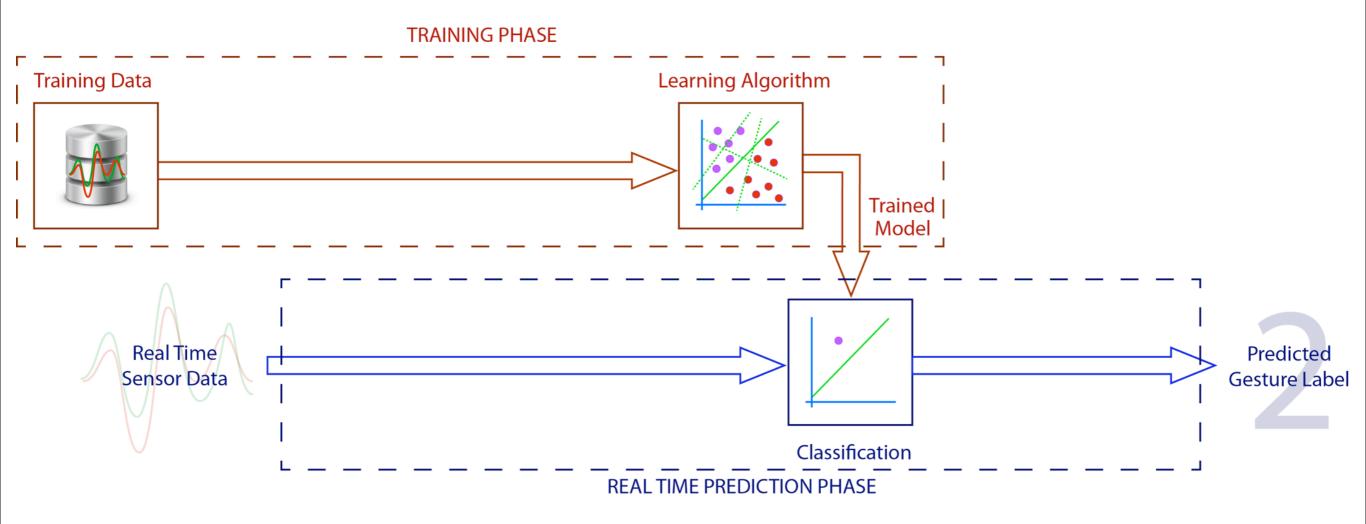
Class A: 4 Class B: 6

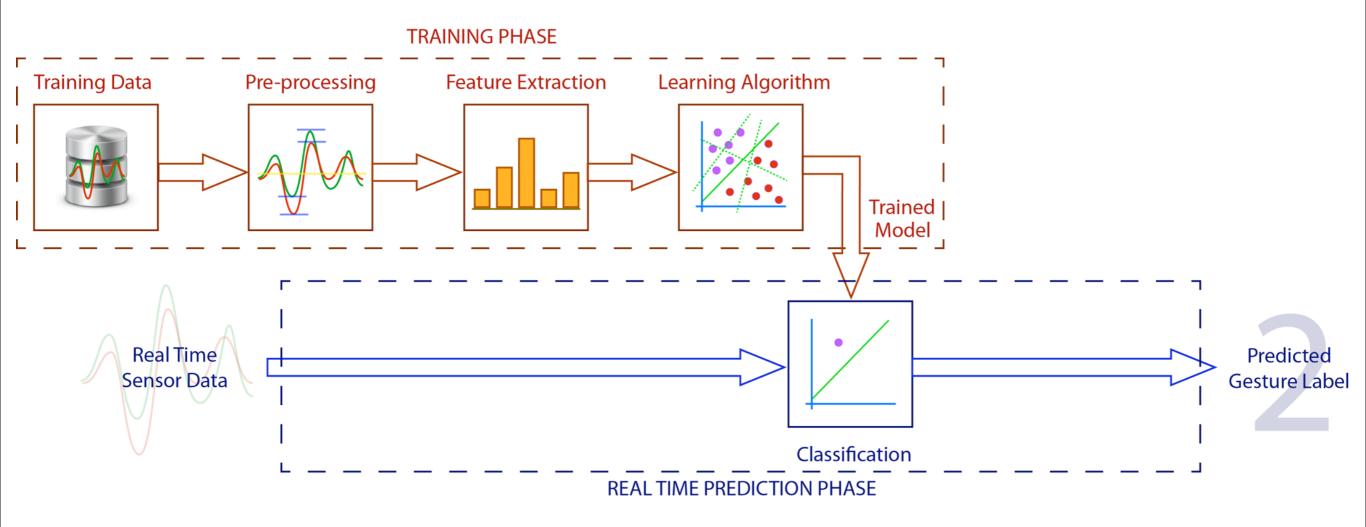
Likelihood of belonging to Class B = 0.6

Hello World - KNN Demo

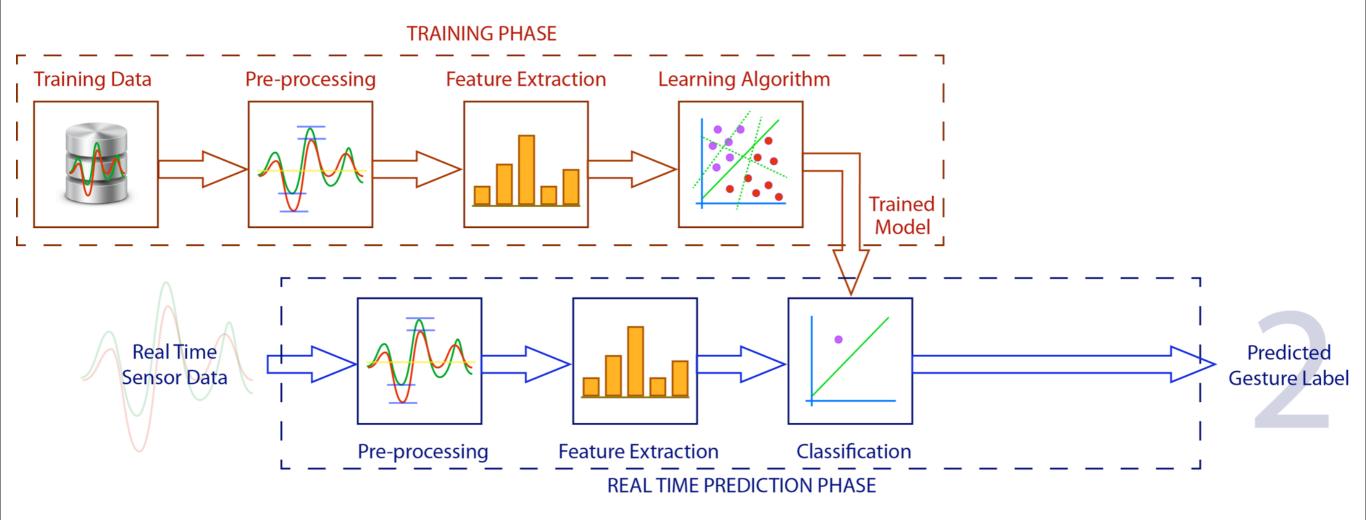
Gesture Recognition

Gesture Recognition

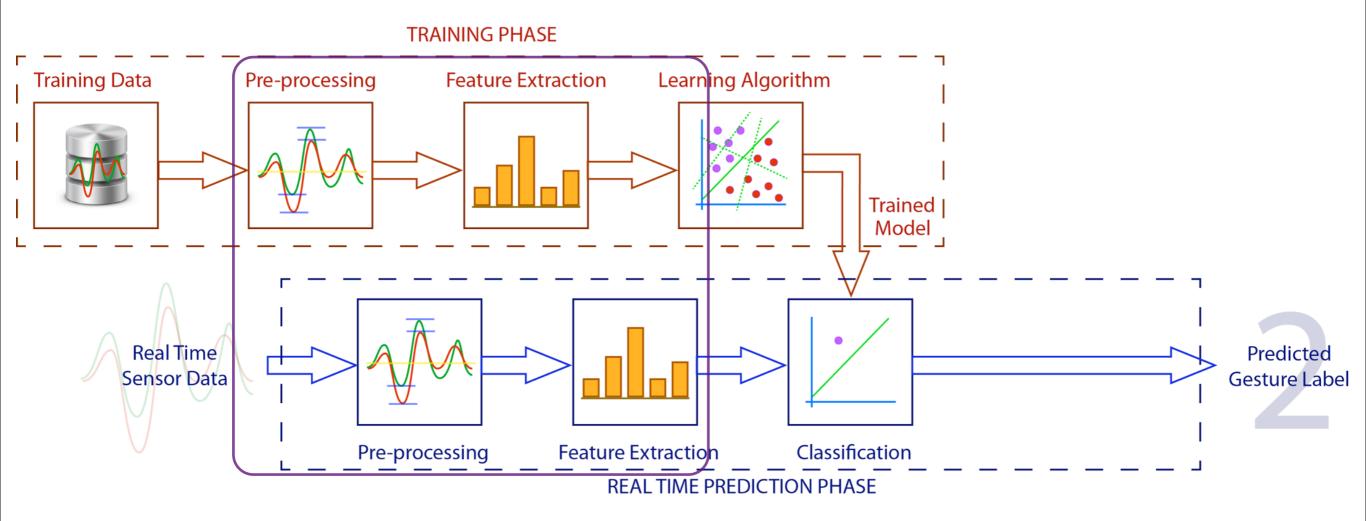




Instead of using the raw data as input to the learning algorithm, we might want to pre-process the data (i.e. scale it, smooth it) and also compute some features from the data which make the classification task easier for the machine-learning algorithm



Important that we also use the same pre-processing and feature extraction methods when predicting the new data!



Important that we also use the same pre-processing and feature extraction methods when predicting the new data!



Classification Task:

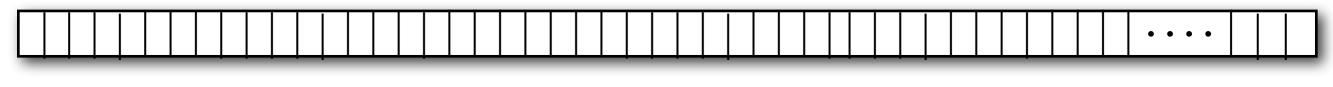
Recognize different postures of a dancer



Classification Task:

Recognize different postures of a dancer

Input Vector:



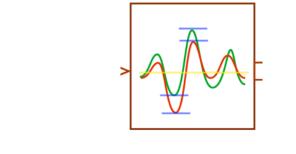
640 * 480 * 3 = 921600

from reference frame (R)

(F) (R)0 < T >= 255 Absolute Subtraction of new frame (F) Thresholding: any value less than threshold is set to black, any value

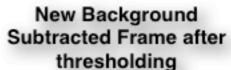
above threshold is set to white

Preprocessing: Background Subtraction

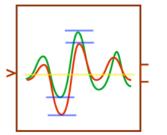


Pre-processing

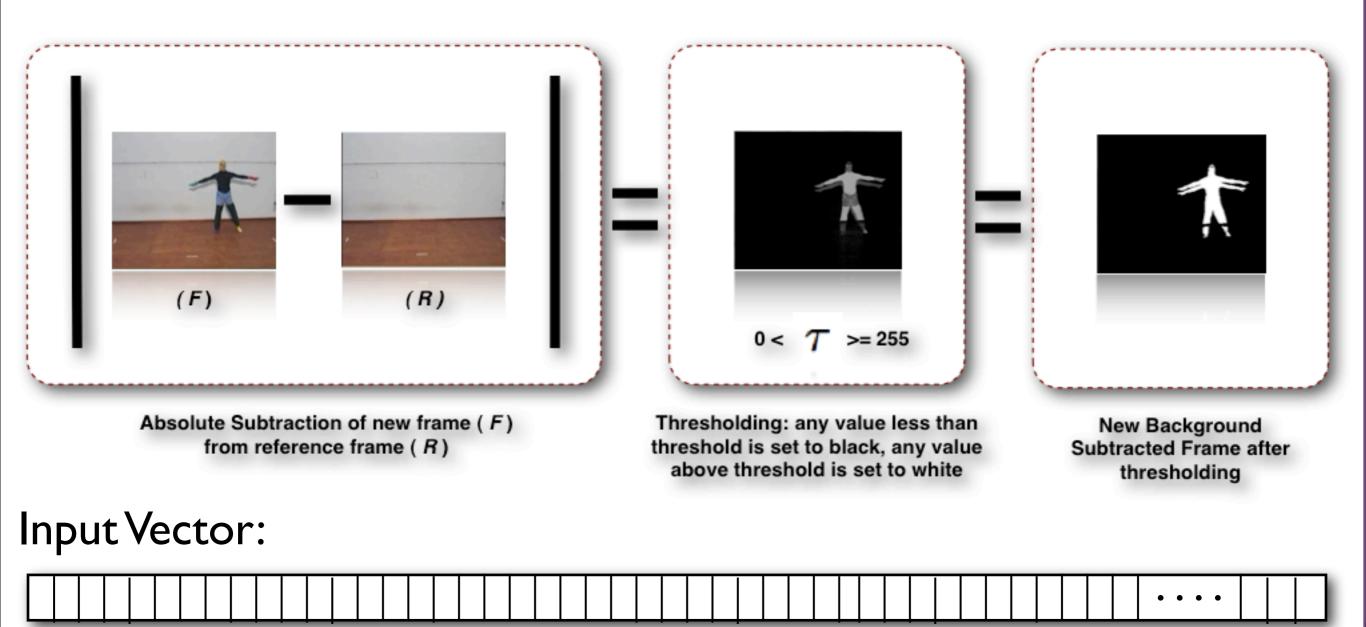




Pre-processing



Preprocessing: Background Subtraction



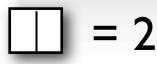
640 * 480 = 307200

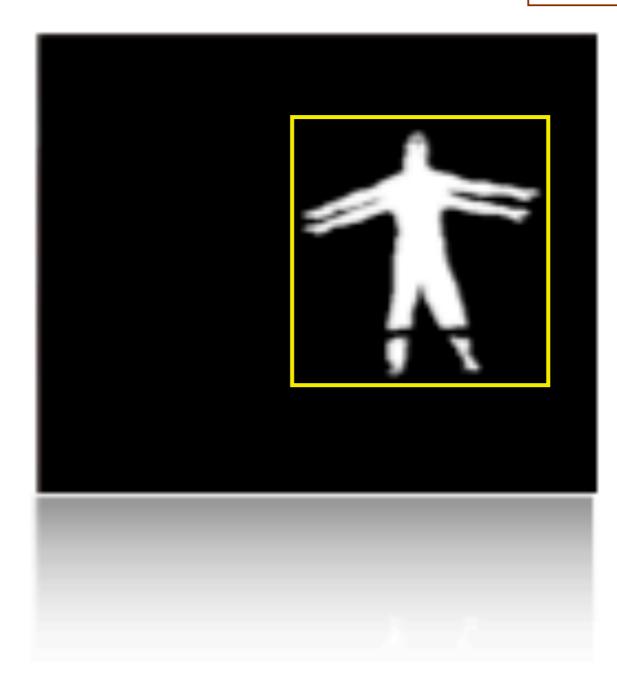
Feature Extraction

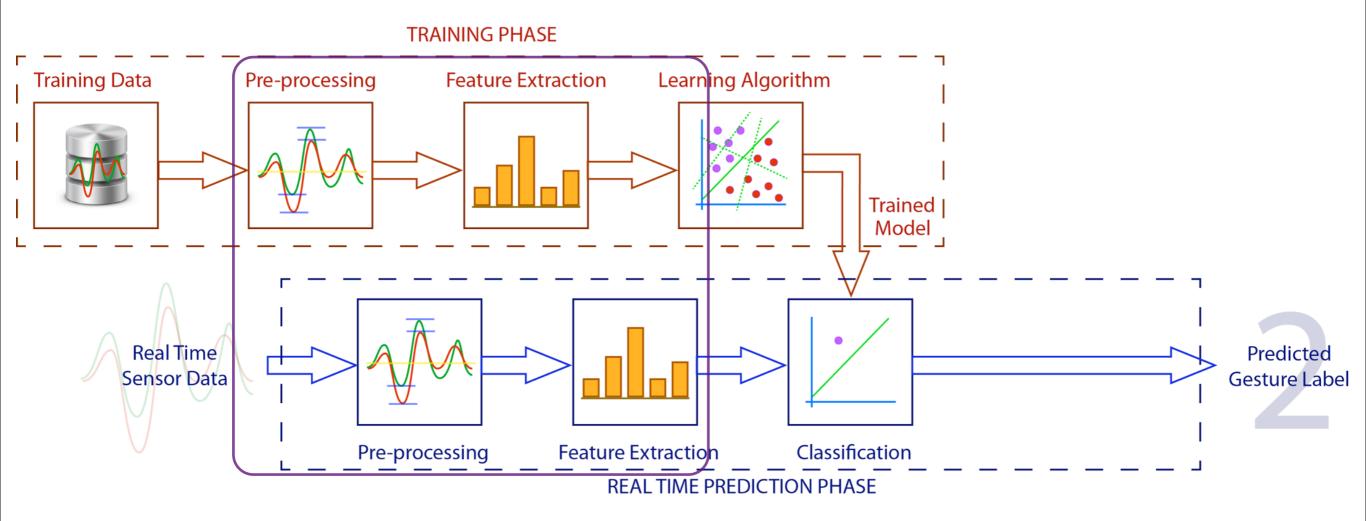


Feature Extraction: Bounding Box

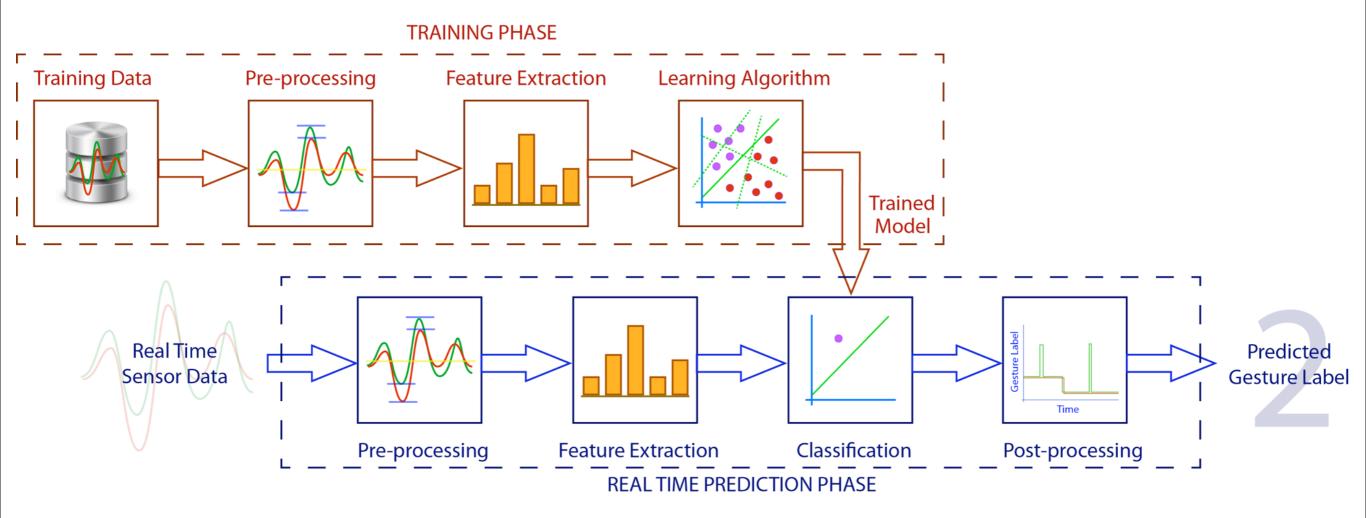
Input Vector:



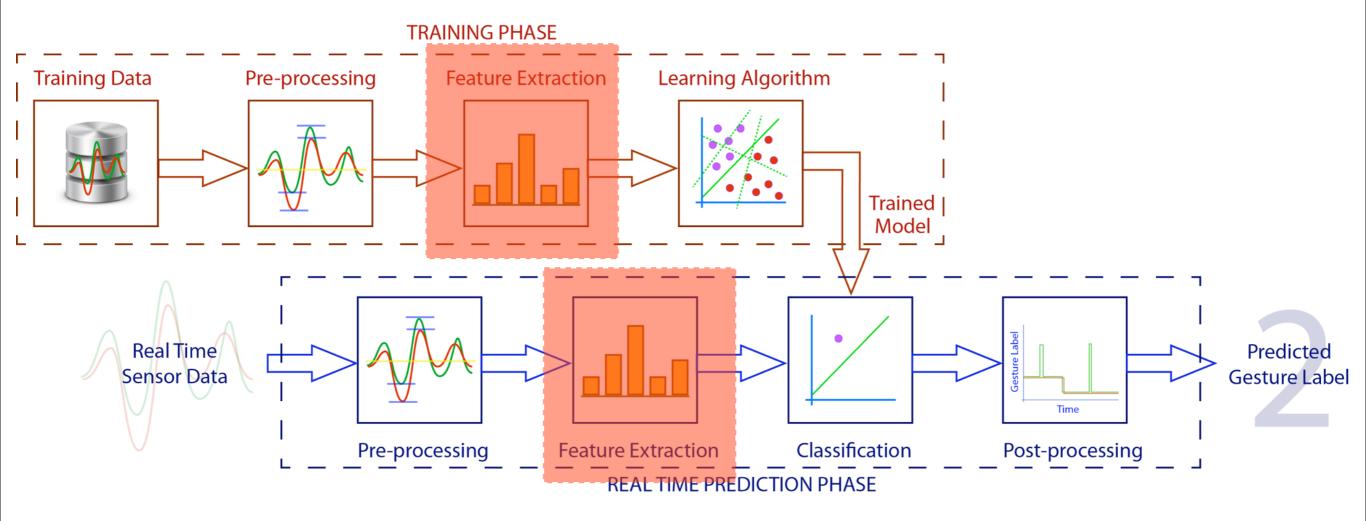




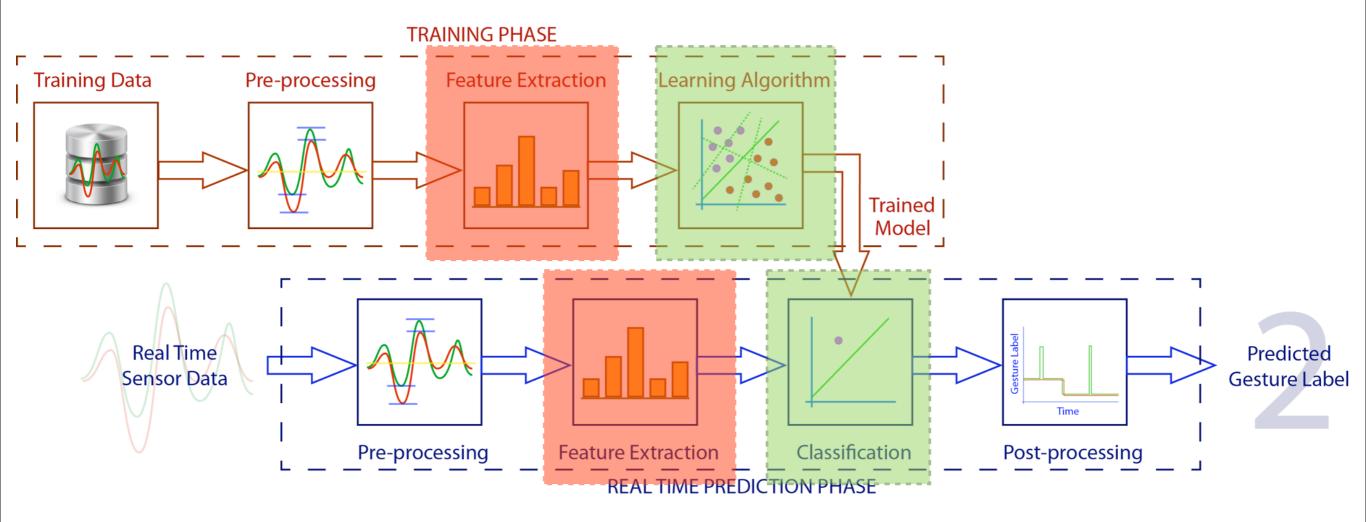
Important that we also use the same pre-processing and feature extraction methods when predicting the new data!



As well as pre-processing the input to the classification algorithm, we might also want to process the output of the classifier



Choosing the right features is REALLY IMPORTANT!

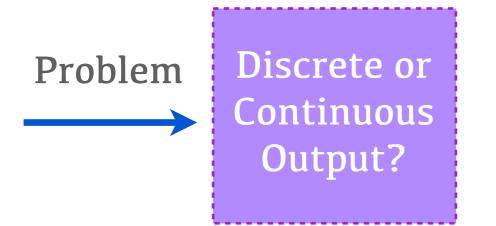


Choosing the right features is REALLY IMPORTANT! Choosing the right ML algorithm is also REALLY IMPORTANT!

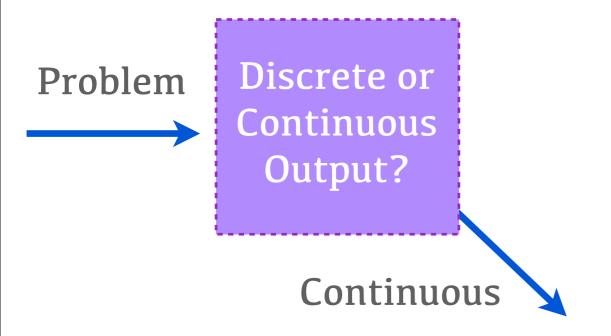
Choosing the right algorithm to solve **your** problem:

Choosing the right algorithm to solve **your** problem:

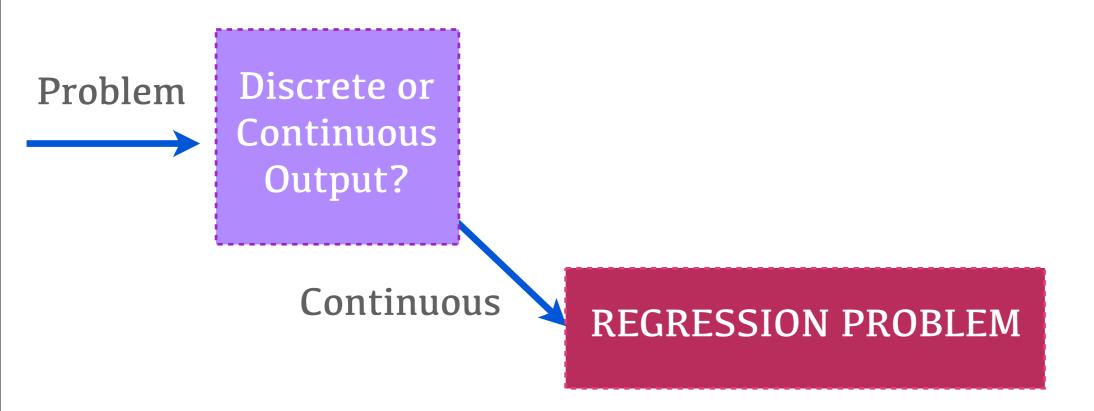
Choosing the right algorithm to solve **your** problem:



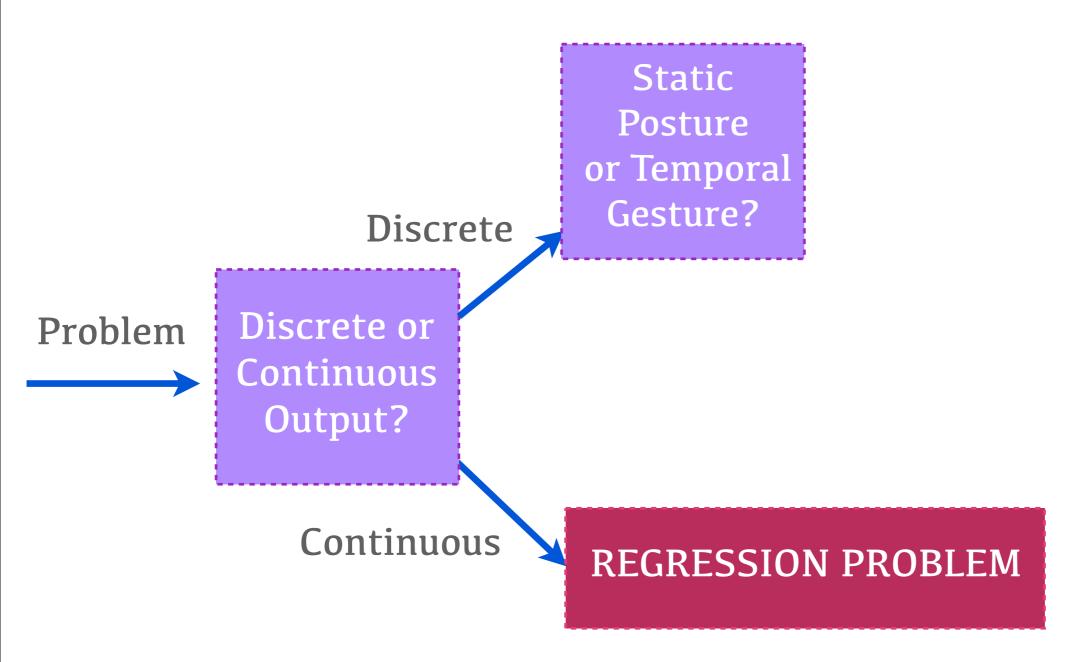
Choosing the right algorithm to solve **your** problem:



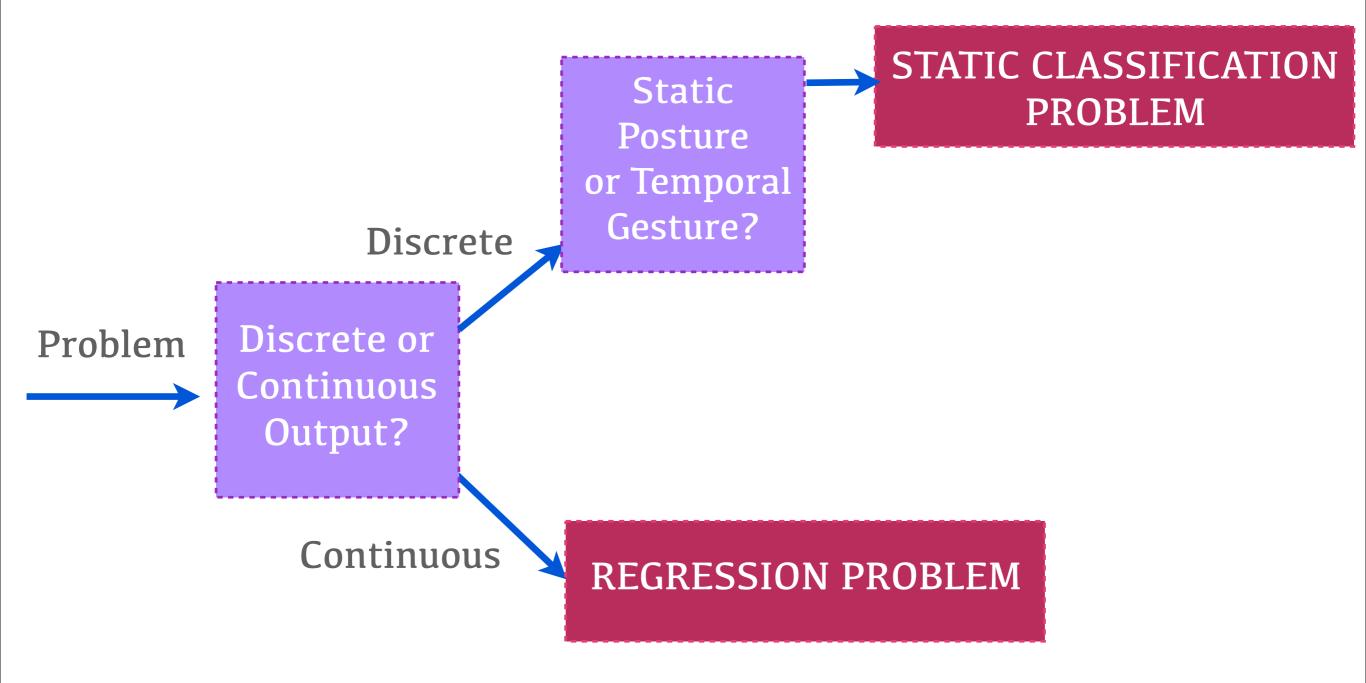
Choosing the right algorithm to solve **your** problem:



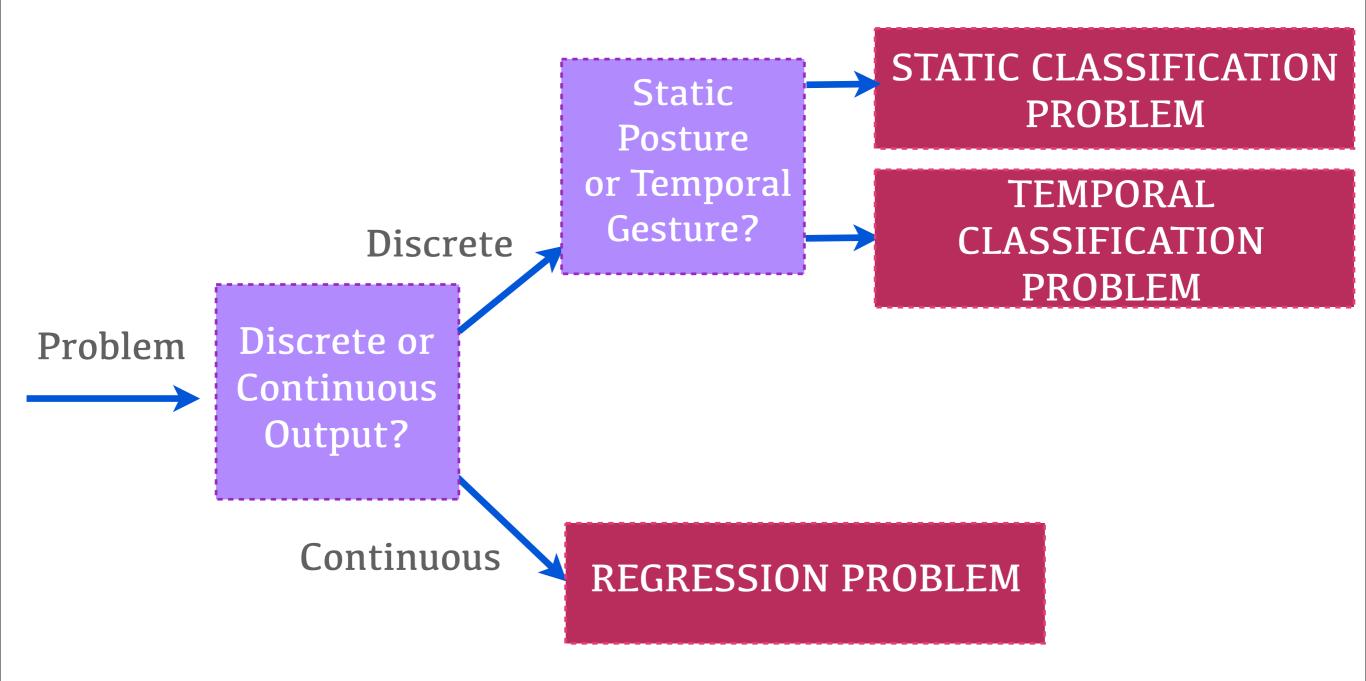
Choosing the right algorithm to solve **your** problem:



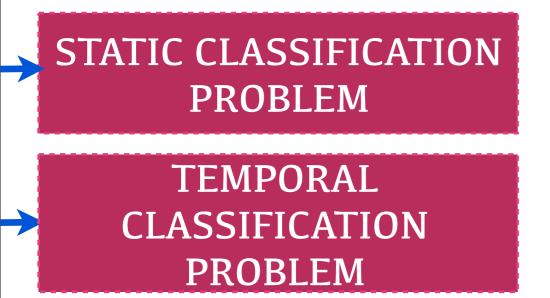
Choosing the right algorithm to solve **your** problem:



Choosing the right algorithm to solve **your** problem:

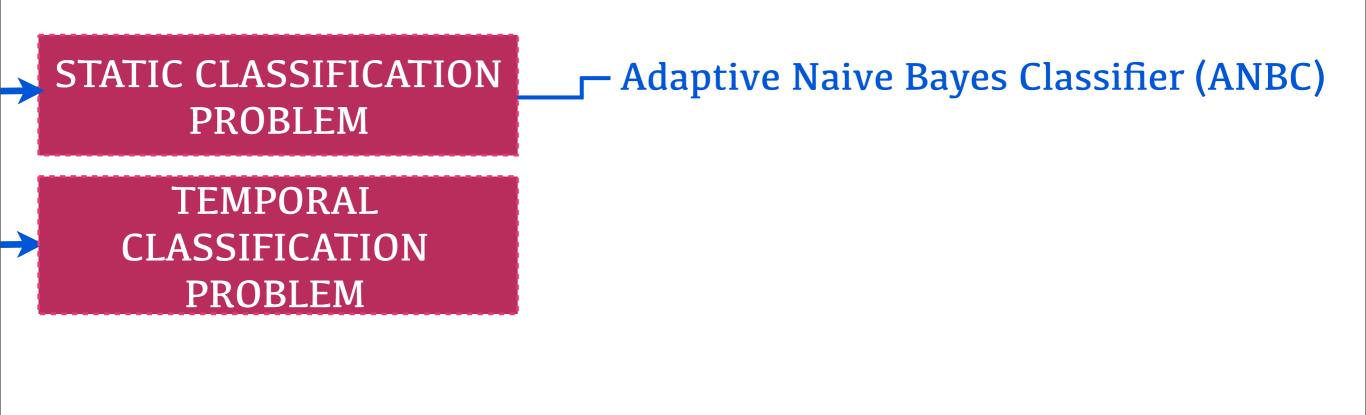


Choosing the right algorithm to solve **your** problem:



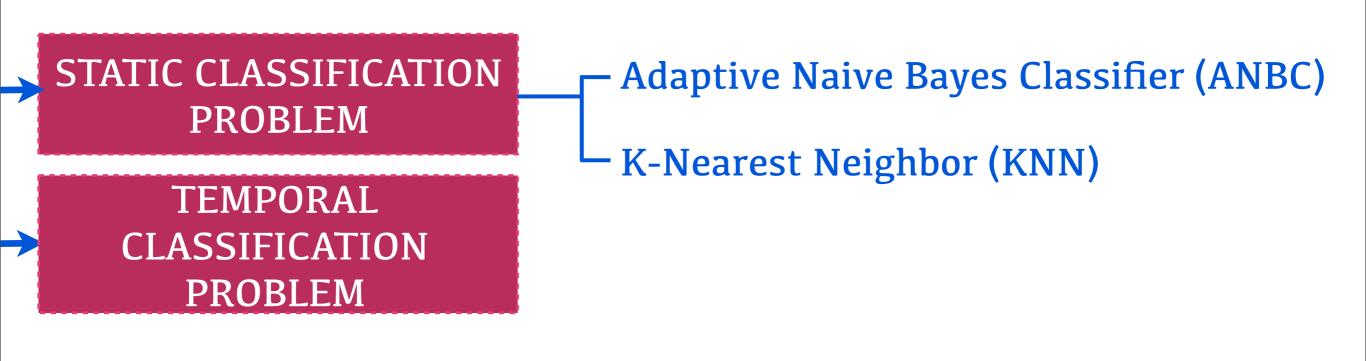
PROBLEM

Choosing the right algorithm to solve **your** problem:



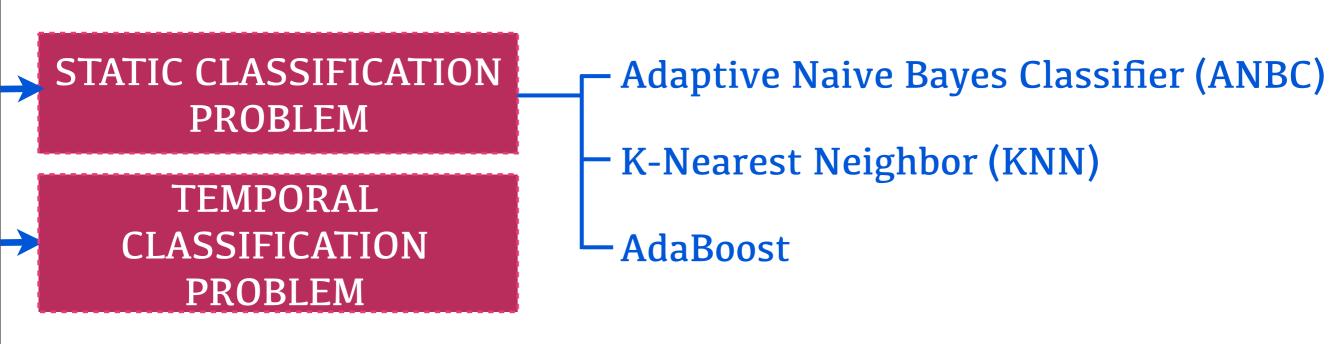
PROBLEM

Choosing the right algorithm to solve **your** problem:



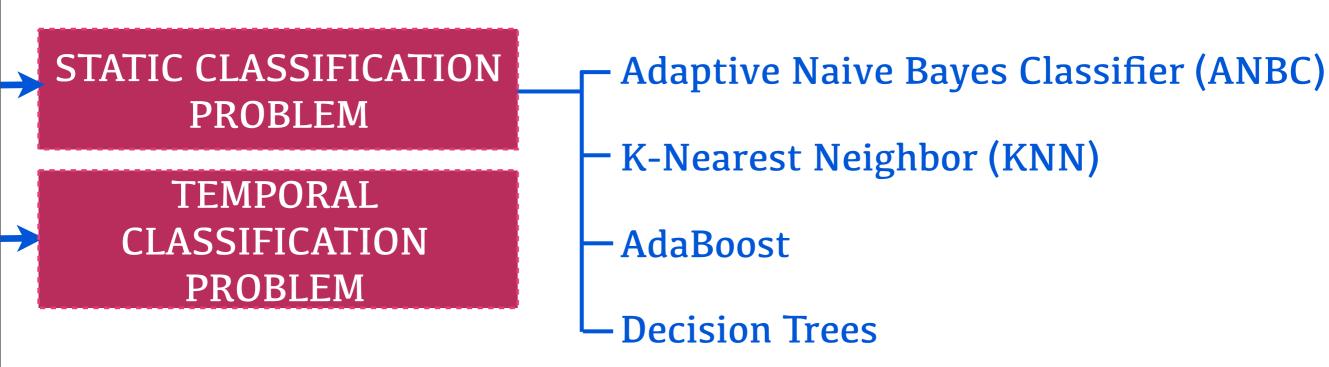
PROBLEM

Choosing the right algorithm to solve **your** problem:



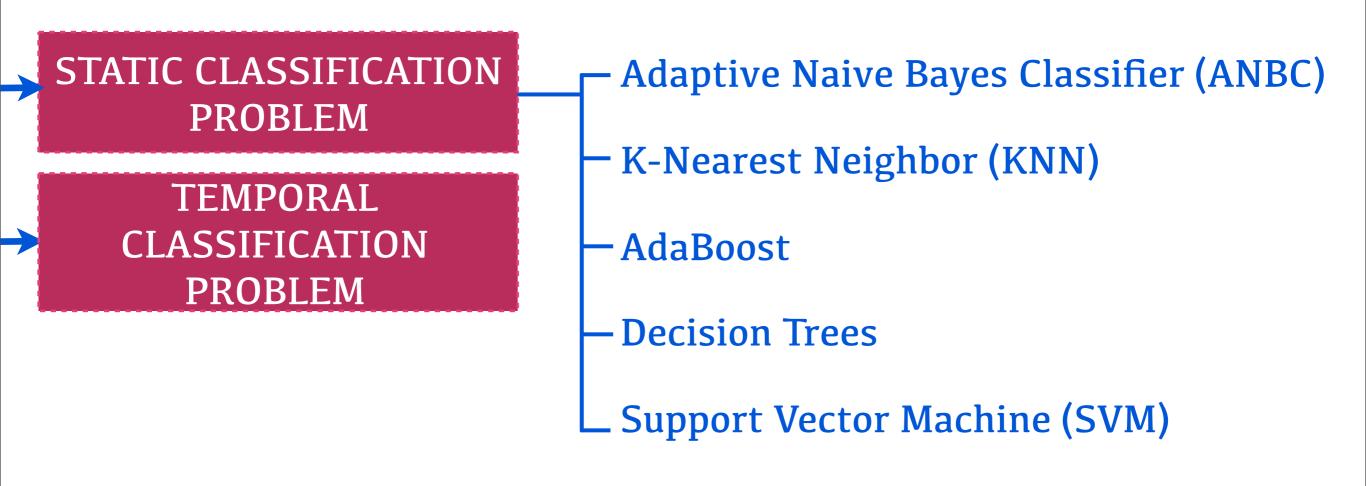
PROBLEM

Choosing the right algorithm to solve **your** problem:



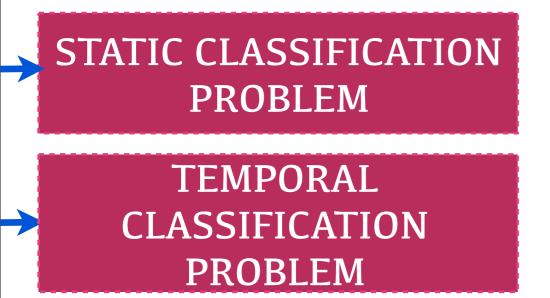
PROBLEM

Choosing the right algorithm to solve **your** problem:



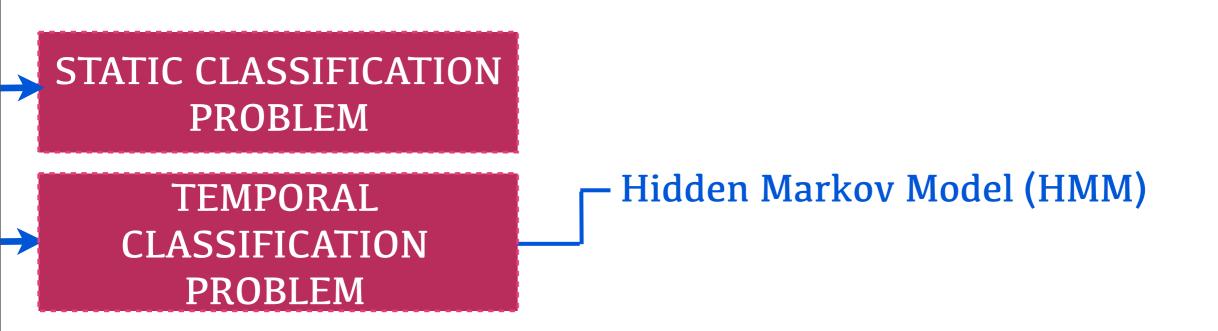
PROBLEM

Choosing the right algorithm to solve **your** problem:



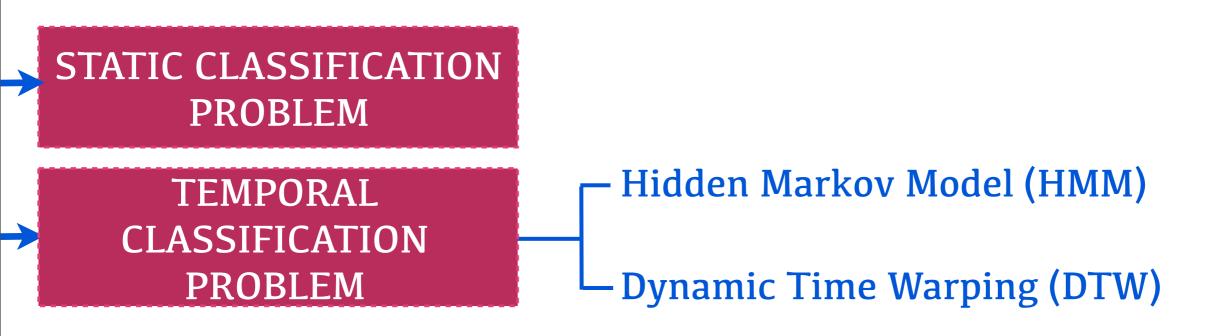
PROBLEM

Choosing the right algorithm to solve **your** problem:



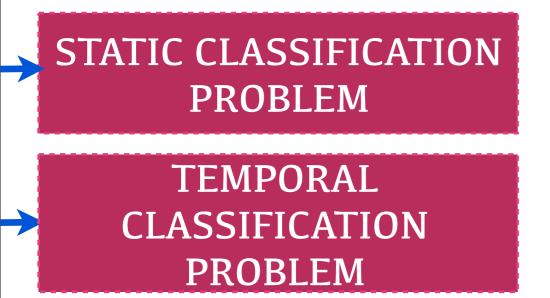
PROBLEM

Choosing the right algorithm to solve **your** problem:



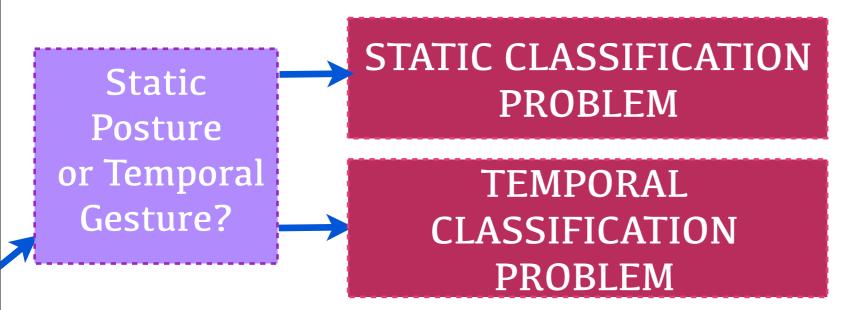
PROBLEM

Choosing the right algorithm to solve **your** problem:



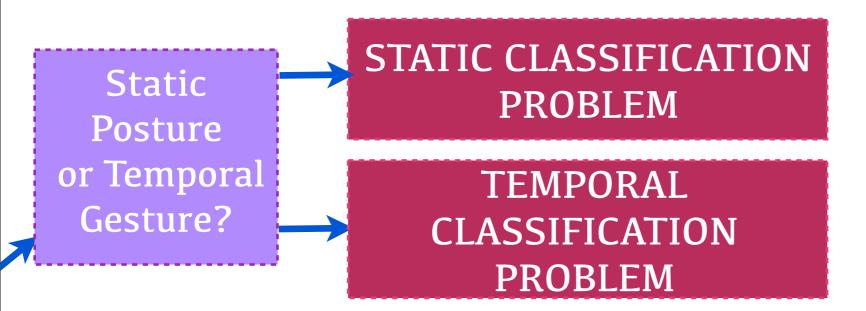
PROBLEM

Choosing the right algorithm to solve **your** problem:



REGRESSION PROBLEM

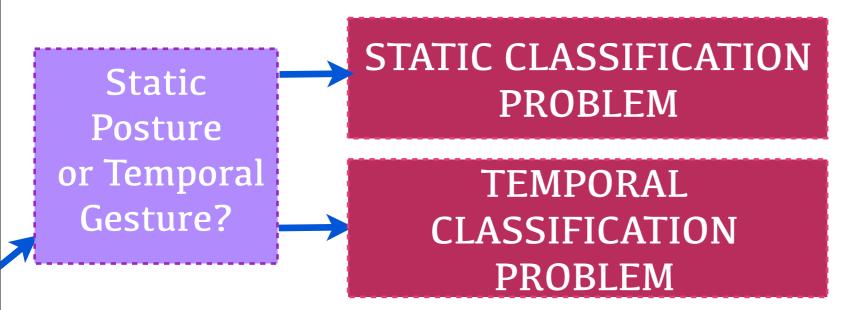
Choosing the right algorithm to solve **your** problem:





Artificial Neural Network (ANN)

Choosing the right algorithm to solve **your** problem:



REGRESSION PROBLEM

Choosing the right algorithm to solve **your** problem:

Machine Learning Resources

- Great books to get started:

Marsland (2009): Machine Learning: An Algorithmic Perspective

Witten (2011): Data Mining: Practical Machine Learning Tools and Techniques

- More detailed books:

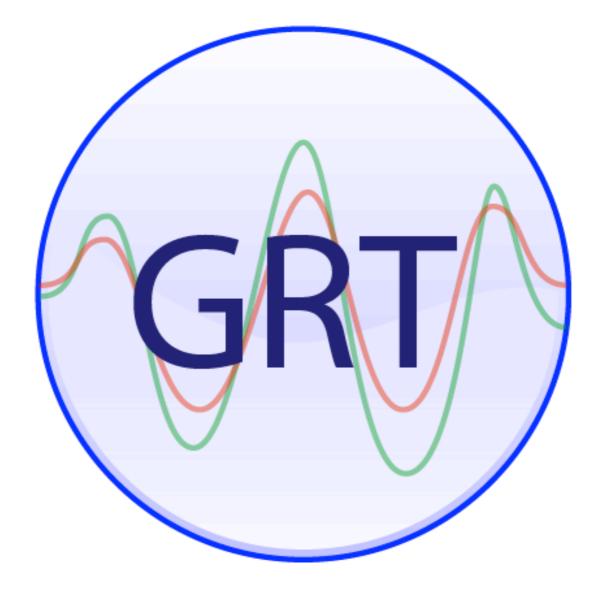
Bishop (2007): Pattern Recognition and Machine Learning

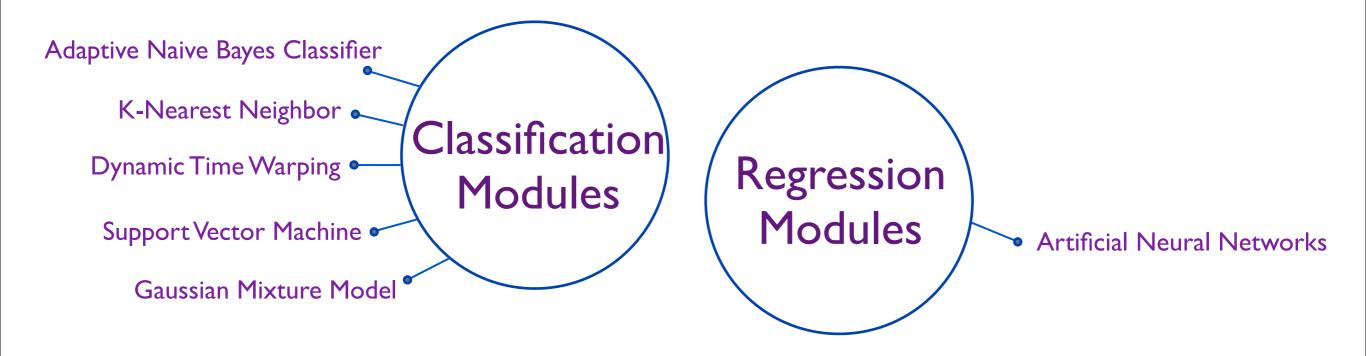
Duda (2001): Pattern Classification

- Online Lectures:

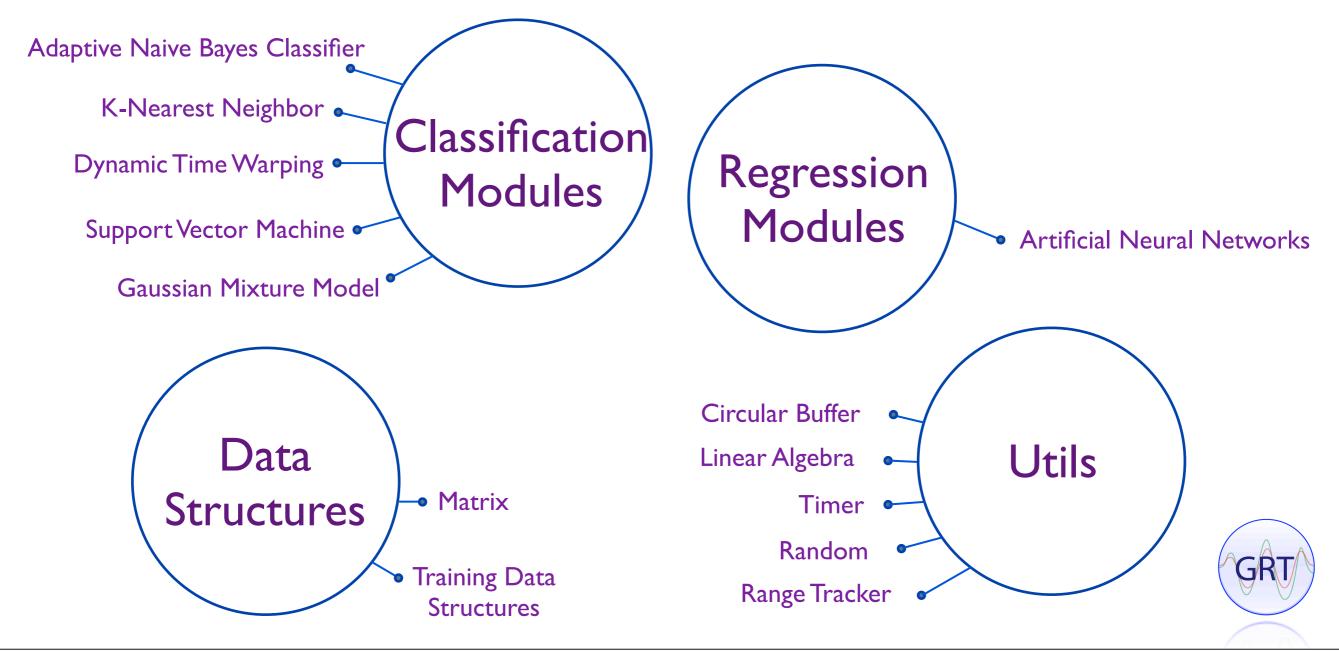
Prof. Andrew Ng (Stanford University), Machine Learning Lectures (search for Machine Learning (Stanford) in youtube)

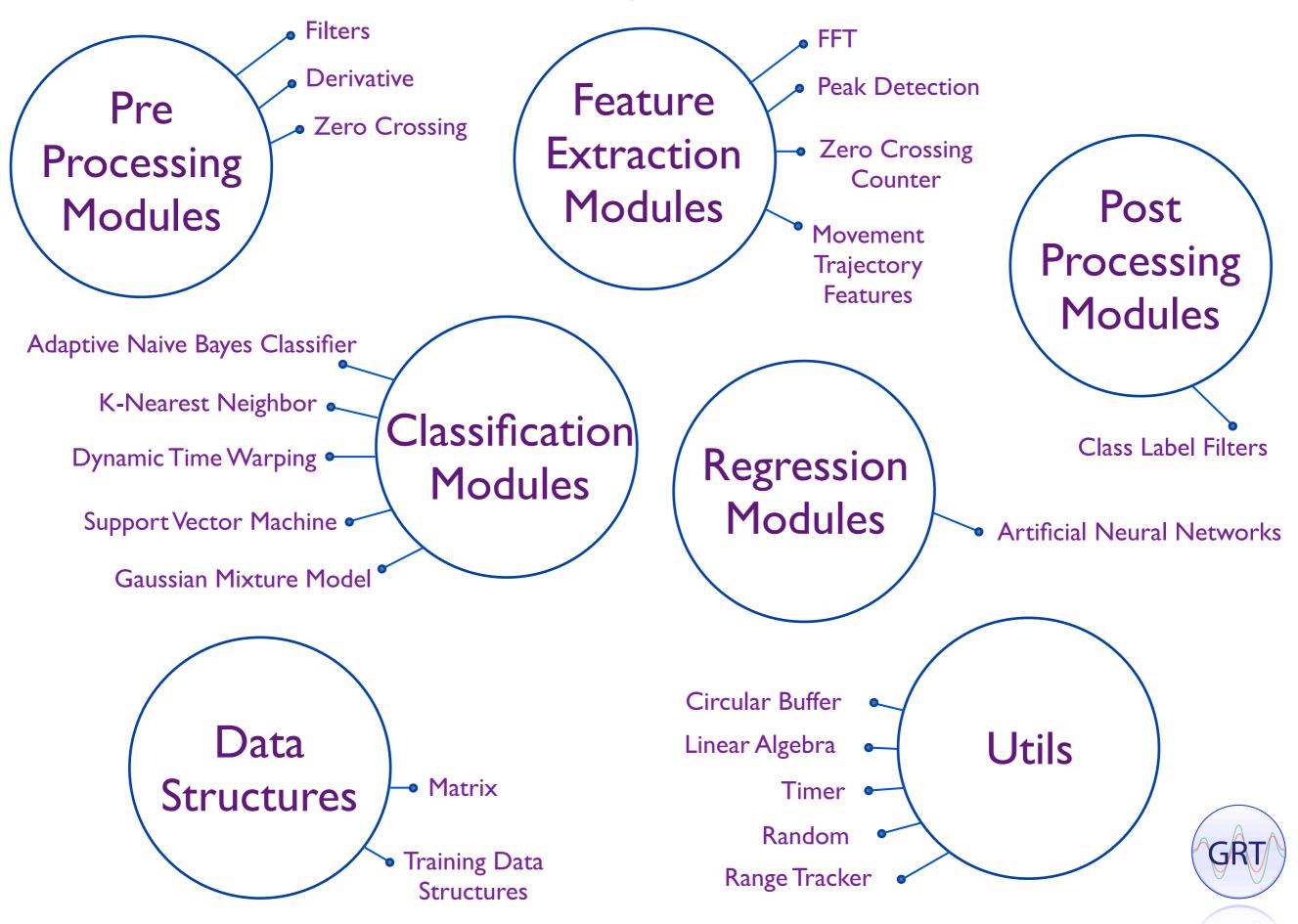
Gesture Recognition Toolkit

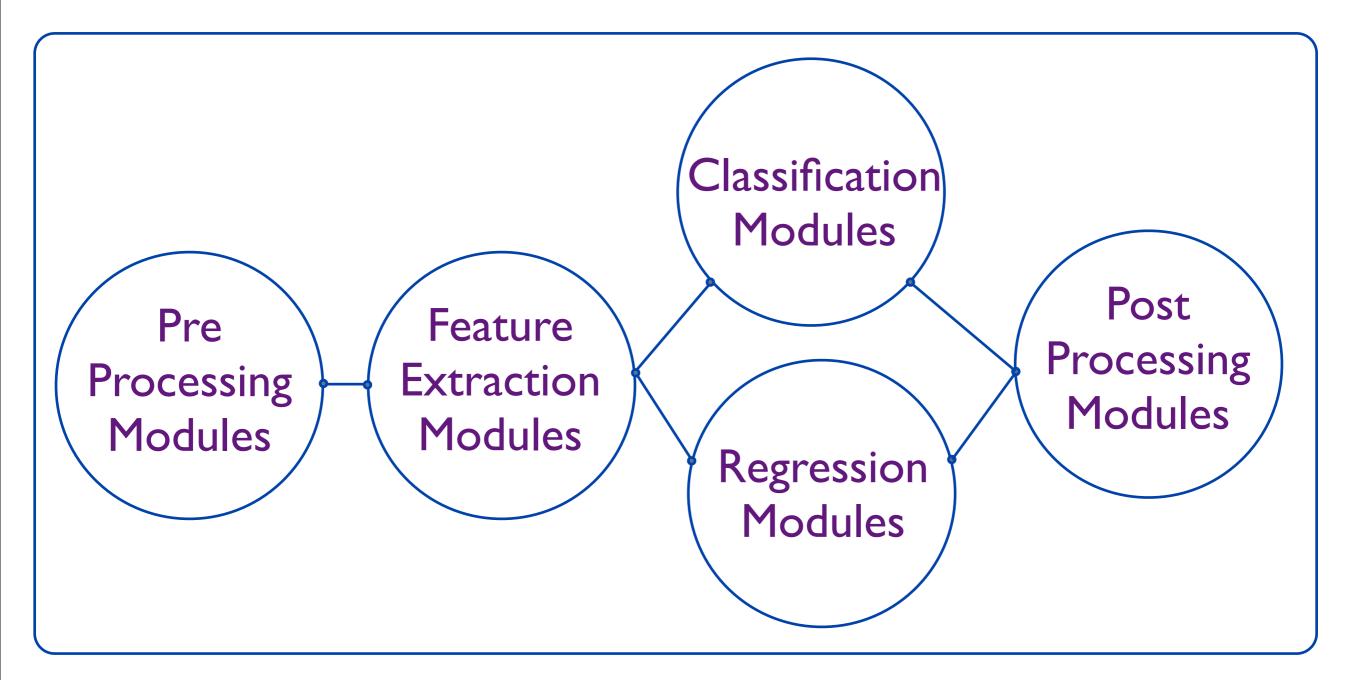


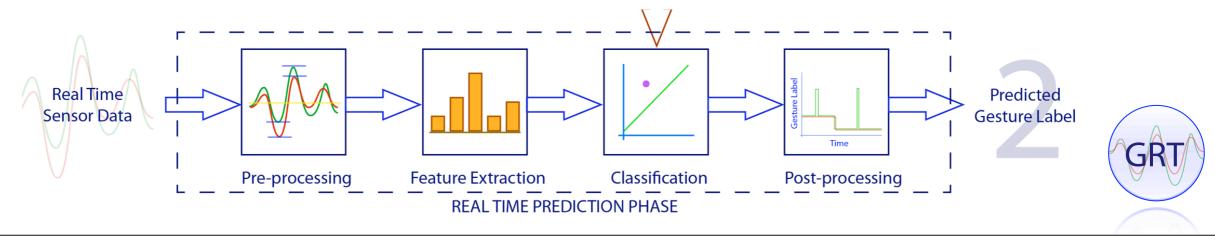


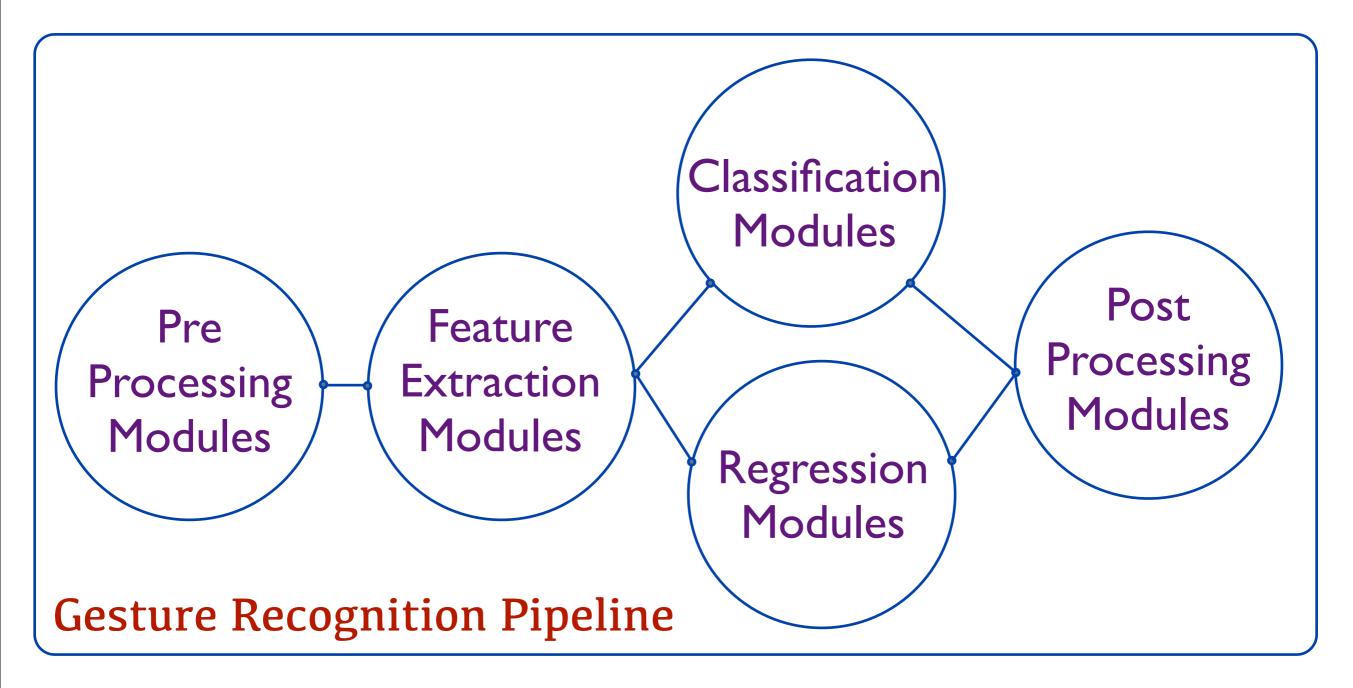


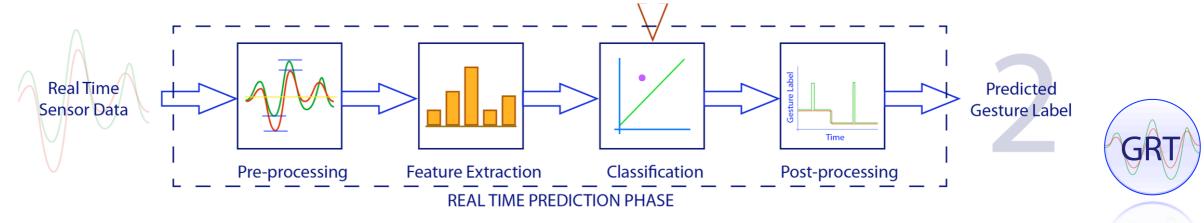












Tuesday, January 8, 13

//Create a new GestureRecognitionPipeline
GestureRecognitionPipeline pipeline;

//Set the classifier at the core of the pipeline
pipeline.setClassifier(ANBC());

This is how you setup a new pipeline and set the classifier



//Create a new GestureRecognitionPipeline
GestureRecognitionPipeline pipeline;

//Set the classifier at the core of the pipeline
pipeline.setClassifier(ANBC());

//Set the classifier at the core of the pipeline pipeline.setClassifier(SVM());

This is how you would change the classifier



//Create a new GestureRecognitionPipeline
GestureRecognitionPipeline pipeline;

//Add a moving average filter as a pre-processing module //With a buffer size of 5 and for a 1 dimensional signal pipeline.addPreProcessingModule(MovingAverageFilter(5,1));

//Add an FFT as a feature-extraction module
pipeline.addFeatureExtractionModule(FFT(1024,1));

//Add a custom feature module to the pipeline
pipeline.addFeatureExtractionModule(MyOwnFeatureMethod());

//Set the classifier at the core of the pipeline
pipeline.setClassifier(ANBC());

//Add a class label timeout filter to the end of the pipeline
pipeline.addPostProcessingModule(ClassLabelTimeoutFilter(1000));

This is how you setup a more complex pipeline



//Train the pipeline
bool trainSuccess = pipeline.train(trainingData);

This is how you train the algorithm at the core of the pipeline



```
//Perform the prediction
bool testSuccess = pipeline.test( testData );
```

This is how you test the accuracy of the pipeline



Tuesday, January 8, 13

```
//Perform the prediction
bool testSuccess = pipeline.test( testData );
//Get the test accuracy
double accuracy = pipeline.getTestAccuracy();
//Get the F-Measure, Precision and Recall for gesture 1
double fMeasure = pipeline.getTestFMeasure( 1 );
double precision = pipeline.getTestPrecision( 1 );
double recall = pipeline.getTestRecall( 1 );
```

You can then easily access the accuracy, precision, recall, etc.



```
//Perform the prediction
bool trainSuccess = pipeline.train( trainingData, 10 );
//Get then get the cross validation accuracy
double accuracy = pipeline.getCrossValidationAccuracy();
```

If you want to run k-fold cross validation, then simply state the k-value when you call the train method and the pipeline will do the rest

//Perform the prediction
bool predictionSuccess = pipeline.predict(inputVector);

This is how you perform real-time classification



Tuesday, January 8, 13

```
//Perform the prediction
bool predictionSuccess = pipeline.predict( inputVector );
//You can then get the predicted class label from the pipeline
UINT predictedClassLabel = pipeline.getPredictedClassLabel();
//Get the likelihood of the most likely class
double bestLoglikelihood = pipeline.getMaximumLikelihood();
//Get the likelihood of all the classes in the model
vector<double> classLikelihoods = pipeline.getClassLikelihoods();
//Use the predicted class label to trigger the action associated with that gesture
if( predictedClassLabel == 1 ){
    //Trigger the action associated with gesture 1
}
if( predictedClassLabel == 2 ){
    //Trigger the action associated with gesture 2
}
```

After the prediction you can then get the predicted class label, predication likelihoods, etc.

